

2019 Alignment Status

PF

11/14/2023



U.S. DEPARTMENT OF
ENERGY

Stanford
University

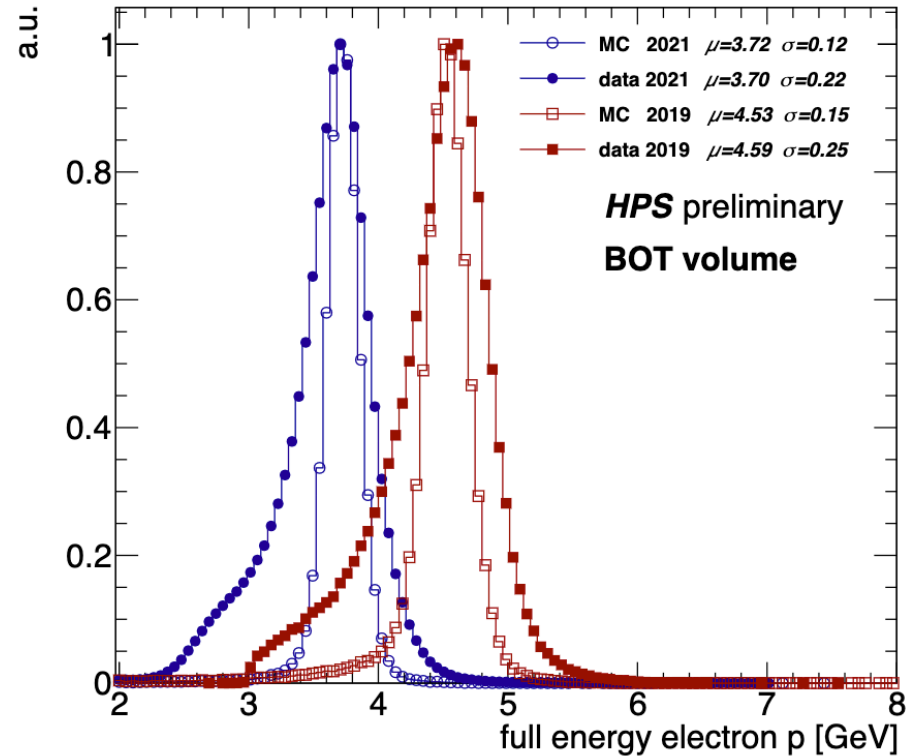
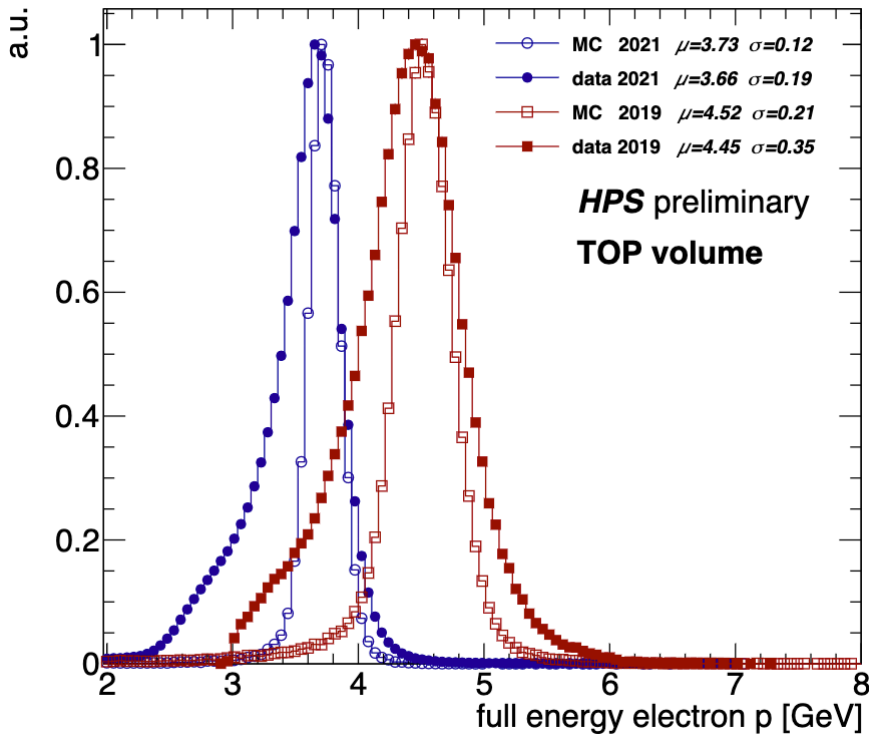
SLAC NATIONAL
ACCELERATOR
LABORATORY

Recap from last collaboration meeting

- Presented new baseline constants for 2019 dataset
 - Documented procedure and motivation for each step
- General performance of 2019 alignment on FEEs
 - Crosschecks with 2016 biases

- Today:
 - Recap of last results
 - Current status of the work done on top of previous solution
 - Ongoing issues
 - Some ideas on how to proceed

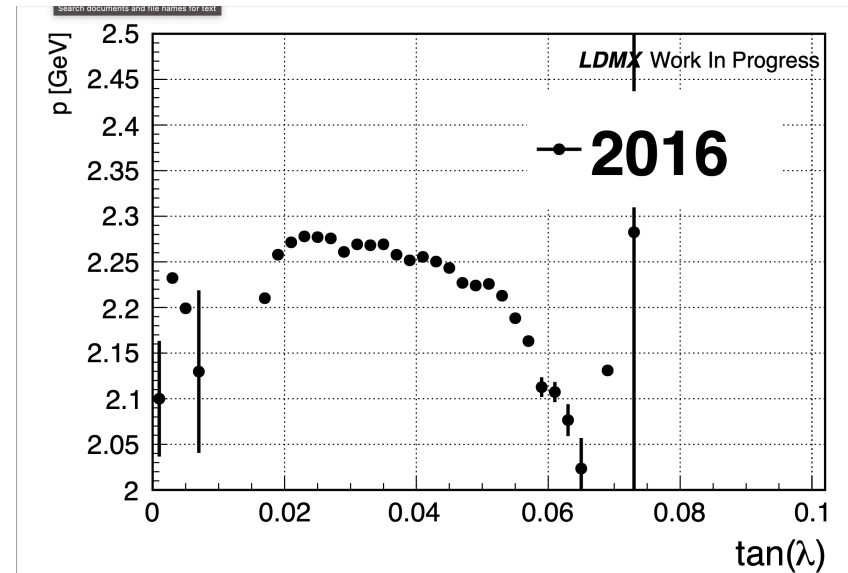
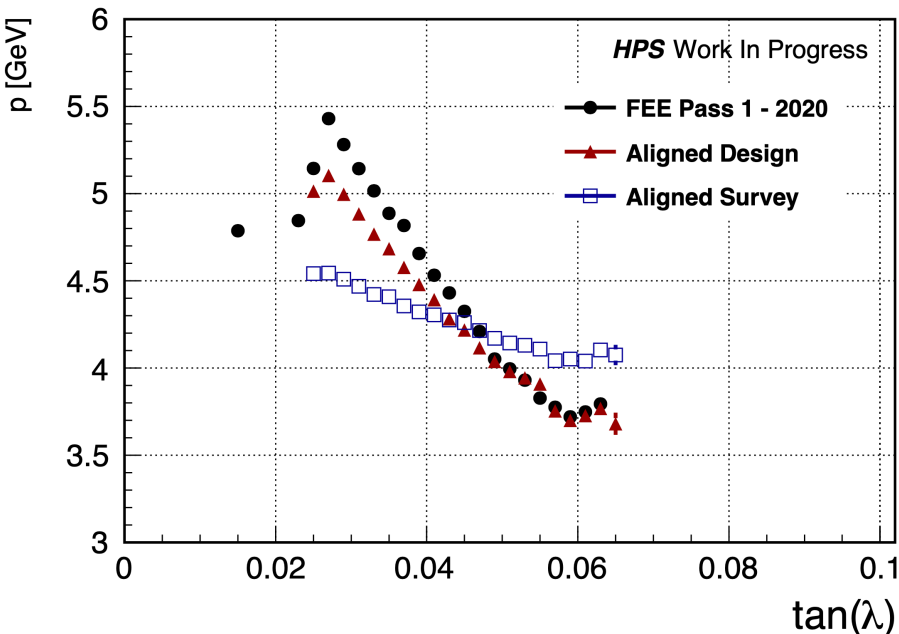
Snapshot from jeopardy



- 2019:
 - Top (Bottom) bias -2% (+0.8%), resolution 7.7% (5.5%)
 - Top, missing ly7
- 2021:
 - Top (Bottom) bias -2% (+0.5%), resolution 5.1% (5.8%)

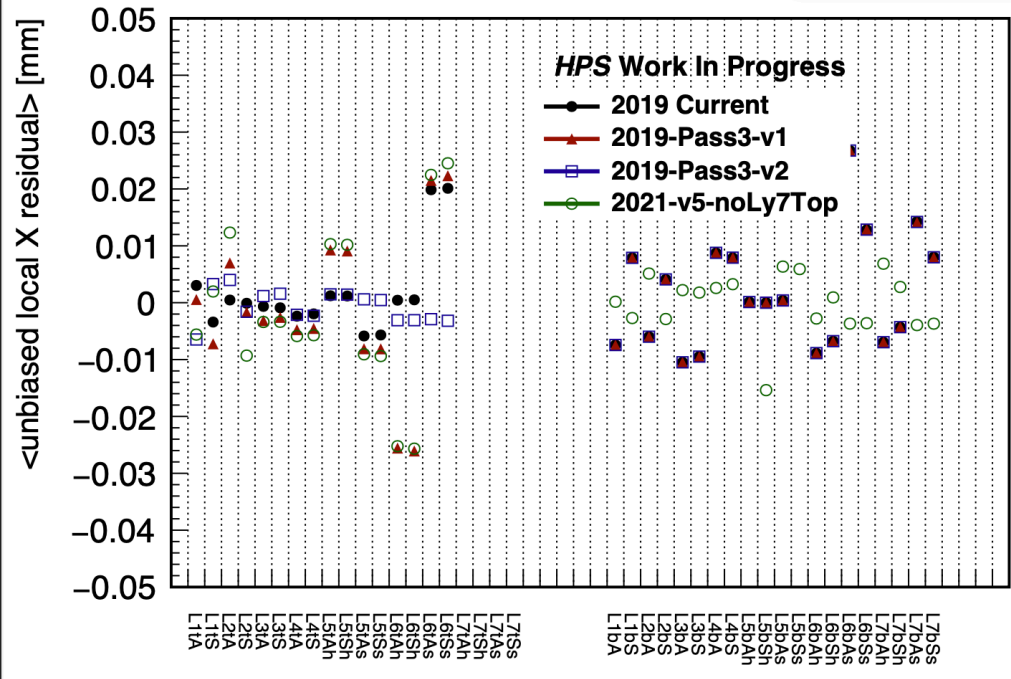
Momentum Biases

- After the re-alignment procedure on Surveyed detector the momentum bias due to $\tan L$ is of the order of **$\sim 10\%$ in $[0.025, 0.06]$ interval** [4.5 to 4]
 - **FEE Pass 1 - 2020 was $\sim 50\%$, $\sim 30\%$ in Aligned Design**
 - A dedicated look to 2016 run7800 shows $\sim 6\%$ [2.28 to 2.15]
- There is a left-over bias that can be removed by simple translation of stereo sensors.

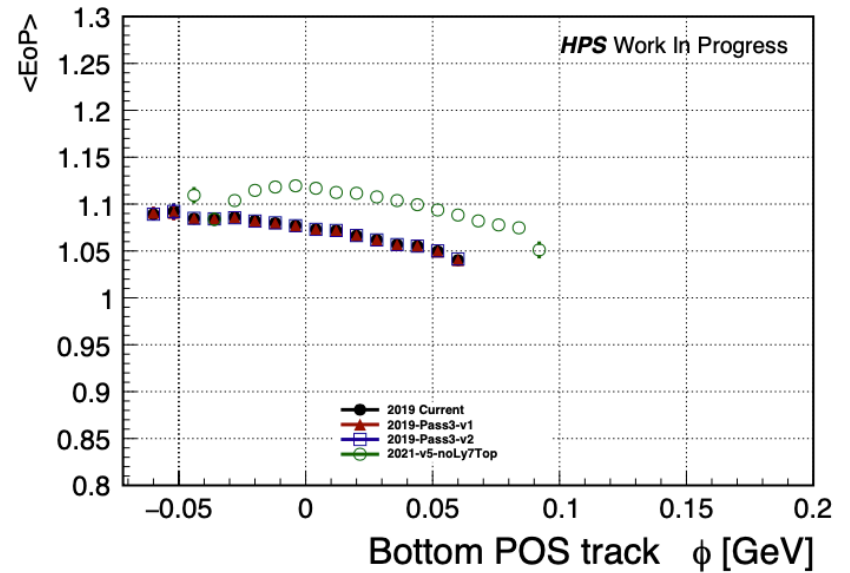
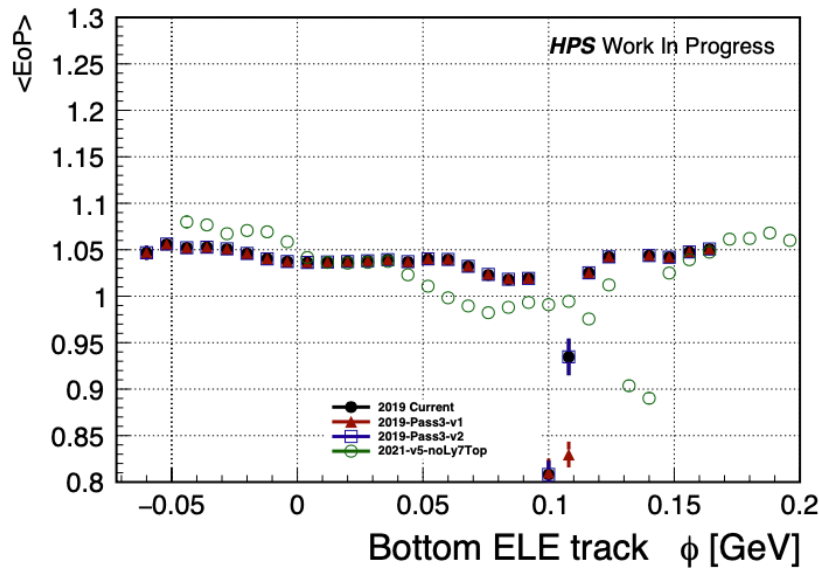


Checks on e+/e- sample

- Used e+/e- to improve current 2019 alignment for top volume
 - Focus on residual mean and E/p metrics
 - Run 10031
- Not straightforward solution:
 - Minimizing residuals doesn't necessarily brings best momentum resolution performance
- Bottom not improved yet
- Compared to 2021 v5 performance (run14770)

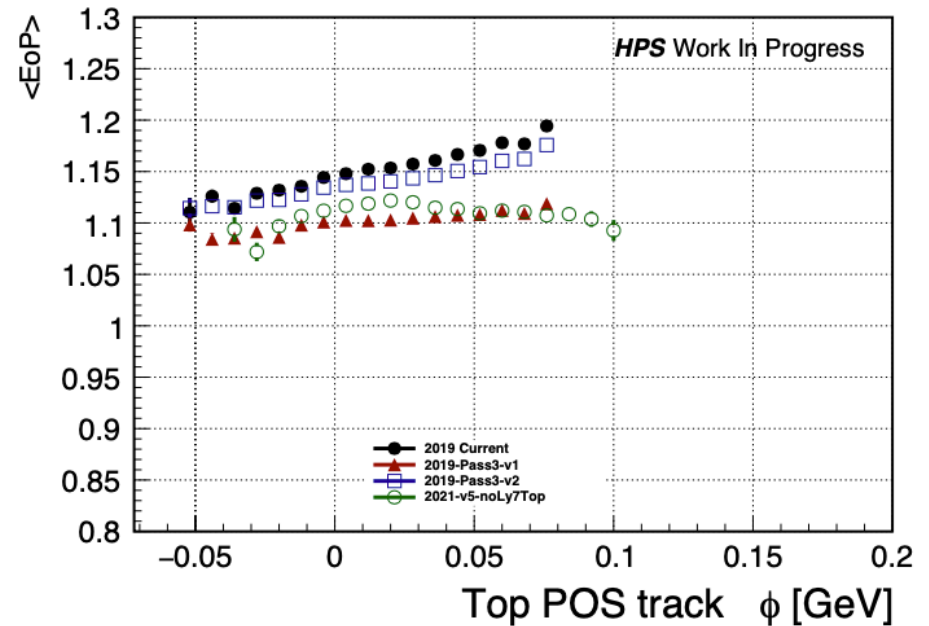
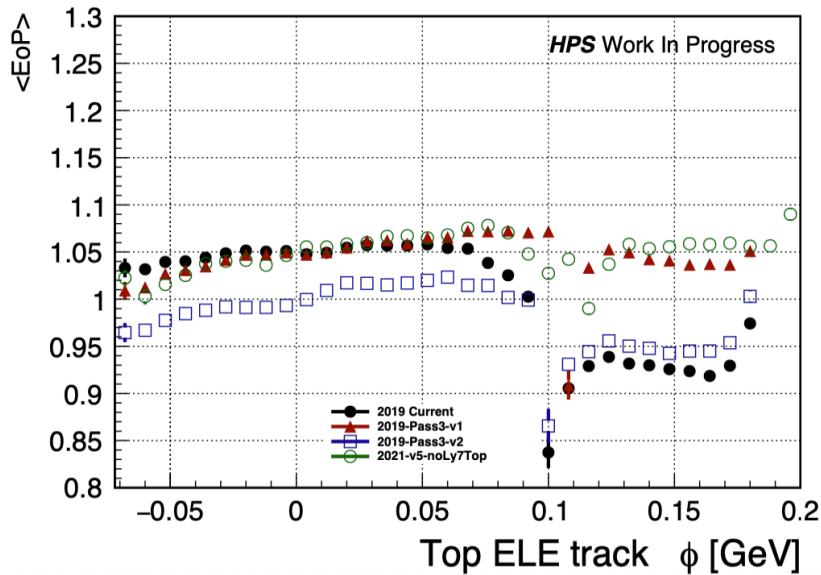


Checks on e⁺/e⁻ sample



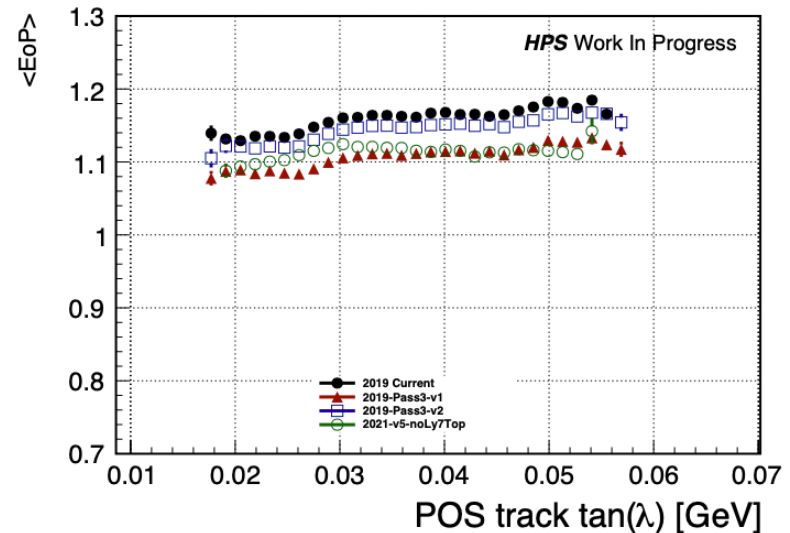
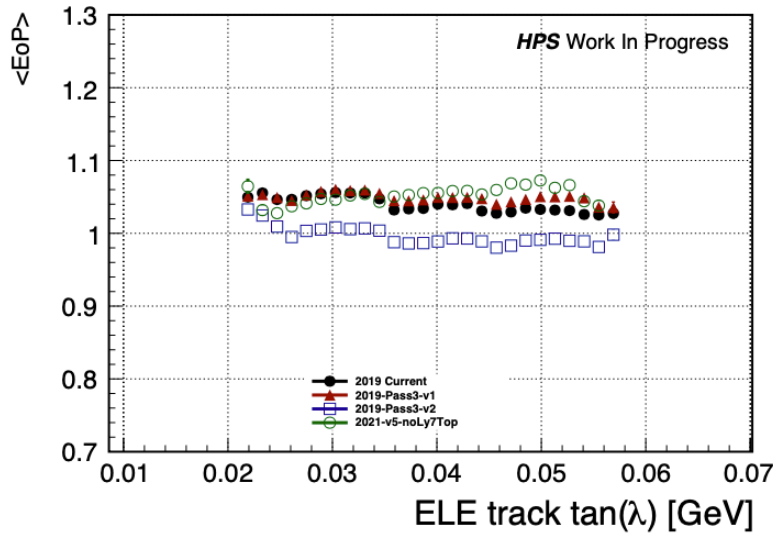
- Bottom volume for 2019 doesn't seem worse than 2021 current performance
 - Did not focus on 2019 bottom.

Checks on e⁺/e⁻ sample



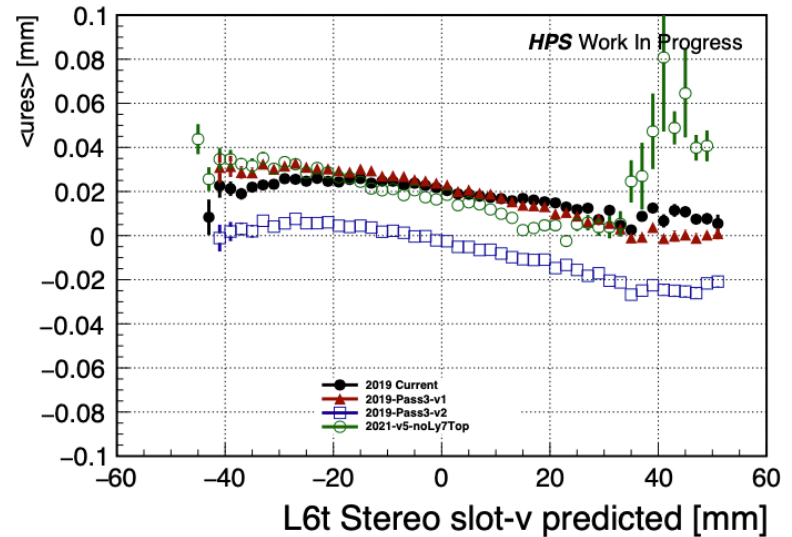
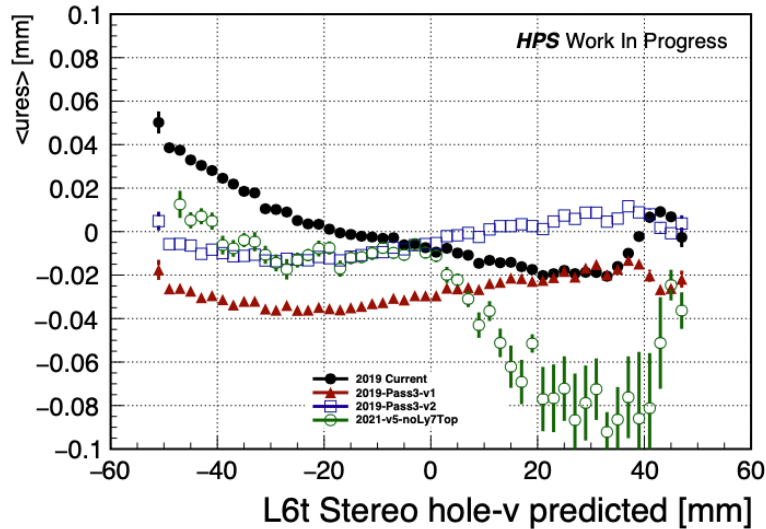
- Improved momentum bias on hole side (Pass3-v2) bit at cost of slot side
- Pass3-v1 has similar performance of 2021 for both e⁺ and e⁻
 - Improvable

Checks on e+/e- sample



- Few % of trends in E/p vs $\tan\lambda$
- Similar in 2019 and 2021
- Scale corrected for electron side (Pass3-v2) and can be improved in positron side.
 - Difficulty seems to rely in getting both at the same time
 - Little bit more on this later

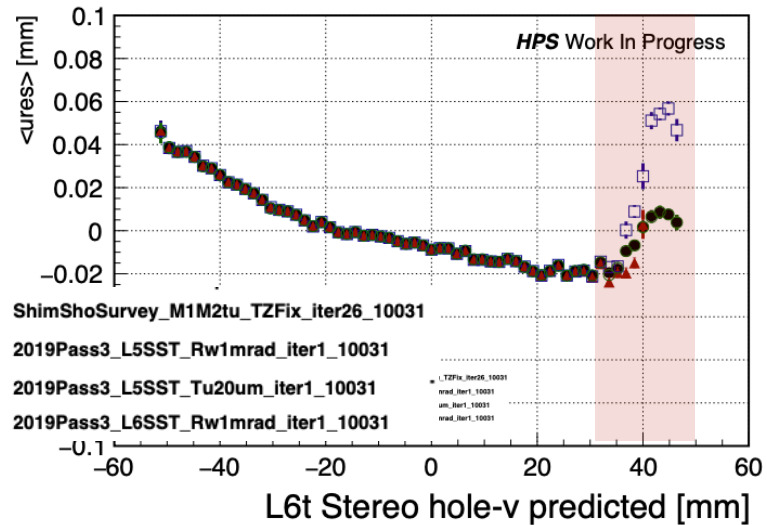
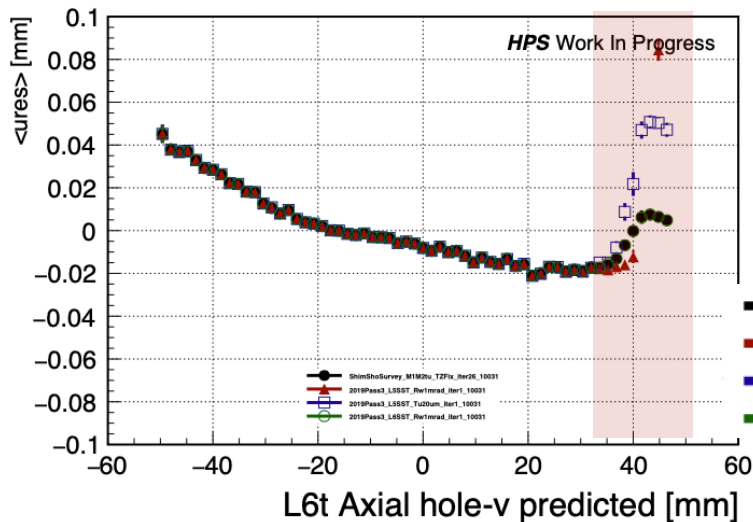
Residuals in the back of the detector



- Residual in the back can be improved by removing structures as function of v
 - More on that later
- Improvement observed in 2019
- 2021 shows sub-optimal alignment in “cross-regions”, i.e. where tracks with hit on Ly6 in the hole (slot) side have hit in slot (hole) side in layer 5
 - Low stat in the profile seems to imply loss of track fits

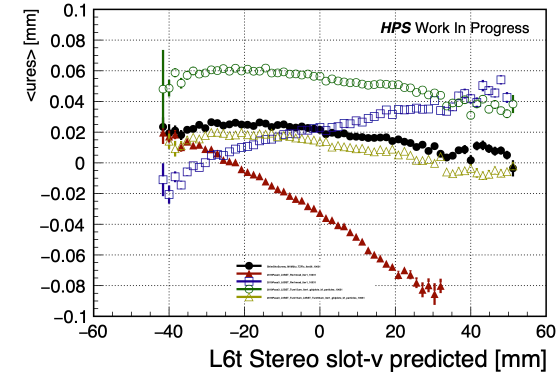
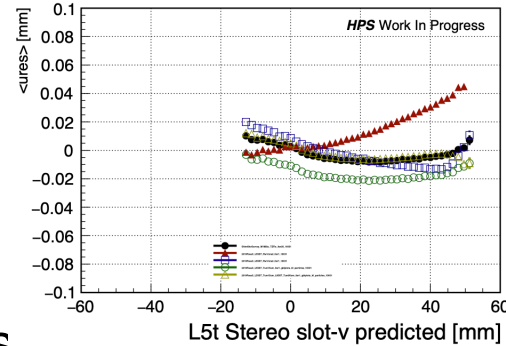
Some studies on residuals

- I've tried to study and characterize effects of movements on residuals
- “cross-side” effects
- Some of my organized studies have been added to the backup of this talk
- **The step in the red region of Ly6 Hole Side can be corrected via Tu of Ly5 Stereo Slot.**

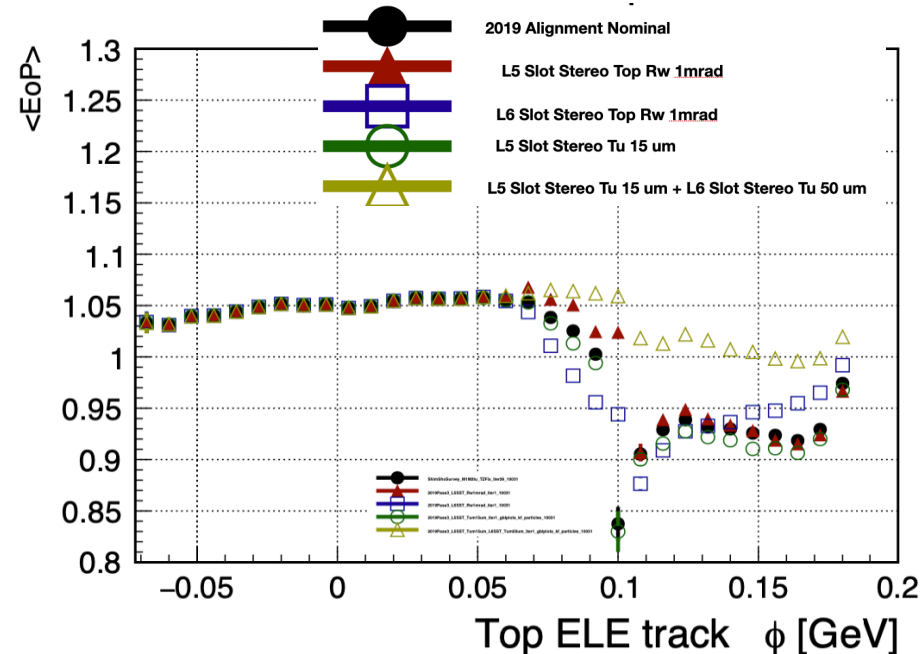


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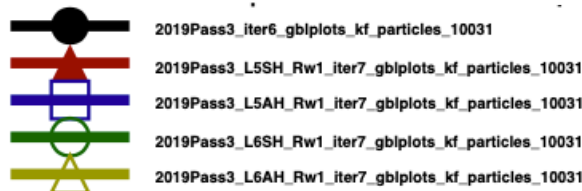
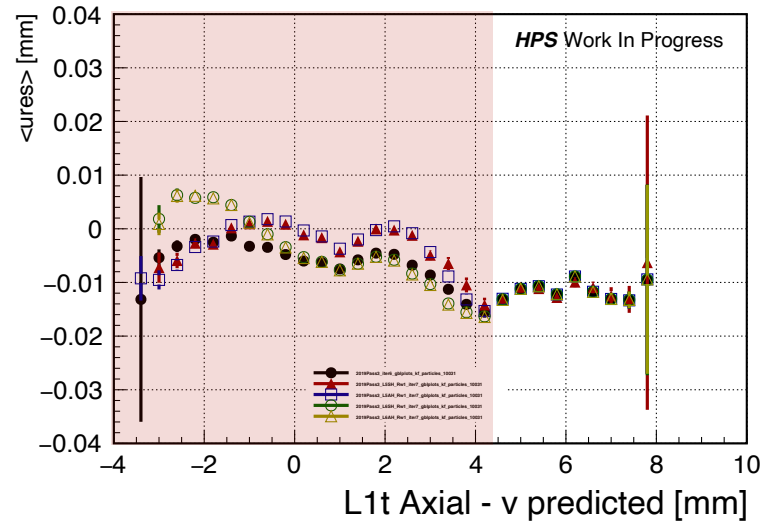
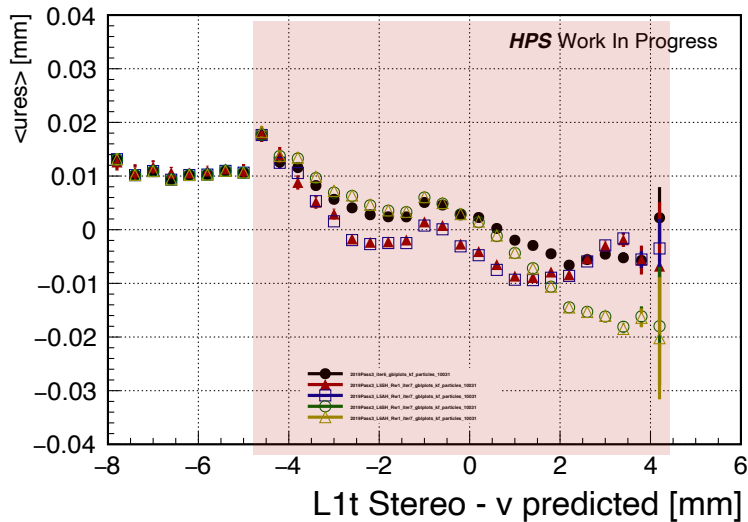


- Movements of the back slot side have an effect on Electron E/p at high phi values
 - Tu = Flat rise, Rw = Linear trend
- In a detector where Ly7 is missing:
 - Tu < 0 in Ly5 leads to lower E/p on the high phi region. Flat correction
 - Rw > 0 in Ly6 creates a trend in large phi with positive slope, i.e. E/p increases with phi => momentum decreases with phi

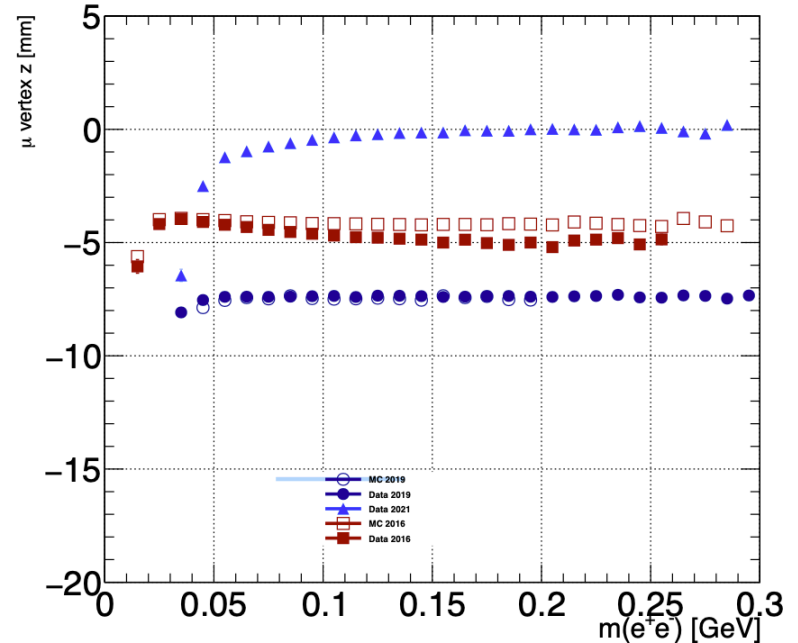
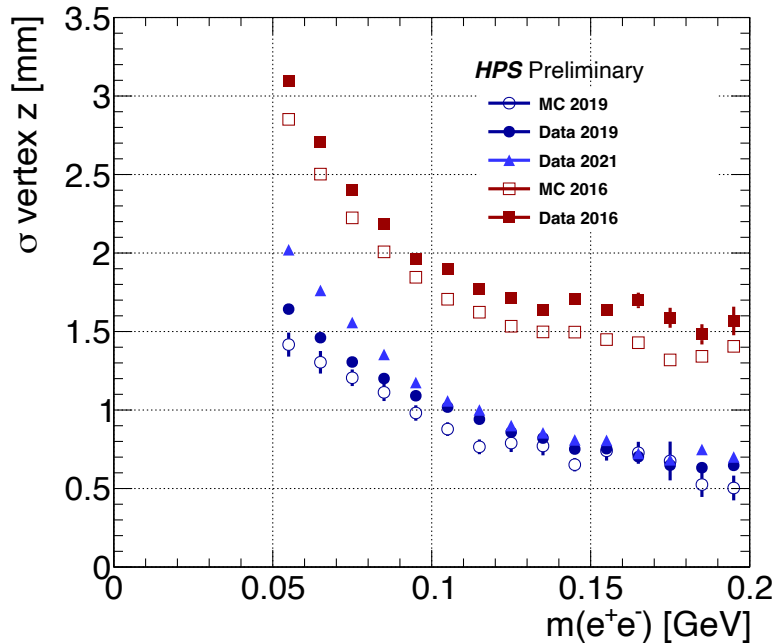


Some studies on residuals

- Front layers show structures in the residuals that are hard to characterize by single sensor movements in the back
- Releasing all sensors that have an effect on MP11 doesn't provide the correct solution
 - Even with constraints
- Improving these residuals might improve VTX resolution and structures in momentum resolution

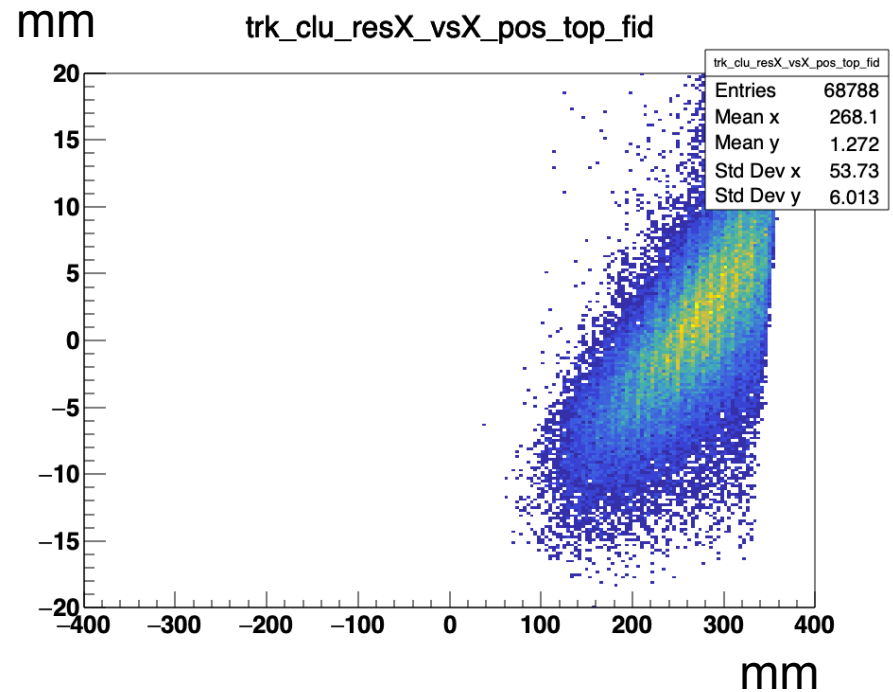
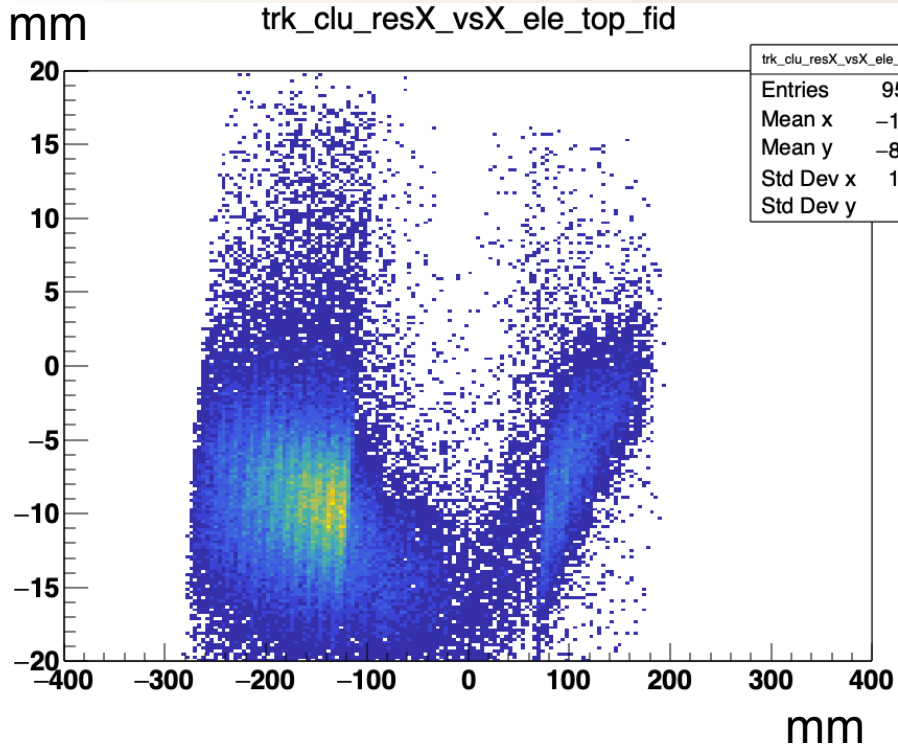


Vertexing side



- 2019 shows good agreement in terms of resolution and mean of the distribution wrt to MC
 - Low mass drift at lower mean in data seems in agreement with MC simulation
 - Expected to be due to L1L1 hit requirement effects and not misalignments
- 2021, shows flat behavior at high masses, steep drift in mean at low masses.
 - To be investigated in principle, not a problem if we don't focus in that region.
- 2021 MC not present in vertexing resolution plot due to un-expected good resolution (couldn't find the plot but procedure to reproduce is fully documented [here](#))
- 2019 MC has low statistics and would be important to check these plots with higher stat for PAC in July.

Calorimeter side



- Track - cluster matching still shows issues in all the 2019 tags
- Here shown Pass3-v1
- Observed in e^+/e^- , with different biases

Current left-over issues and some (personal) ideas

- **Current open issues in 2019 detector**
 - **Dedicated pass on bottom volume**
 - Mostly focused on top volume as that expresses worse momentum resolution performance.
 - However doesn't look worse than 2021 dataset when compared without last sensitive layer
 - **Improve residual shapes for top volume**
 - Potentially improve vtx and E/p resolution
 - **Check time stability**
 - Has been shown that the detector is stable for the full run in 2021
 - Time dependence of the solution wasn't checked in 2019, we should do it
 - **Tracks to cluster residuals**
 - Detector still exhibits biases in track to cluster matching for 2019, this is even after correcting the extrapolation to ECAL
 - Could add ECAL cluster position to track fit and get derivatives, tricky but feasible, or just correct in the matching tool
- **Current procedure issues for both 2019 and 2021**
- **Investigate why MPIL minimization provides wrong results**
 - Running MPIL on sensors that cause innermost layers residual structures doesn't fix the biases. This shouldn't happen in principle and the source of this issue is not clear
 - A possible cause is strongly non-uniform illumination of the sensors:
 - Define procedure to accept tracks that illuminate uniformly our sensors could be a possibility to remove this effect. (Tim)
 - Get first the on-sensor hit distribution
 - Load the distribution in hps-java and throw a random number accordingly
 - Throw away tracks according to 1./ pdf
- **2016 didn't suffer of some of the effects observed in 2019/2021 alignment**
 - New addition are the innermost layers. Maybe try an alignment removing the innermost layers from the track finding and once alignment of mid-back is done, re-introduce them one by one.

Conclusions

- Presented snapshot of recent work on 2019 alignment compared with 2021
- In few of the metrics reached comparable performances
- Some issues remain such as:
 - Time dependence, cluster-track matching still has biases, bottom residuals to be improved, shapes in the residuals still showing internal misalignments...
- Vertex resolution and mean in agreement with MC simulation
- Vtx pSum for 2019 dataset should be re-checked for July PAC with new alignment tag

Conclusions

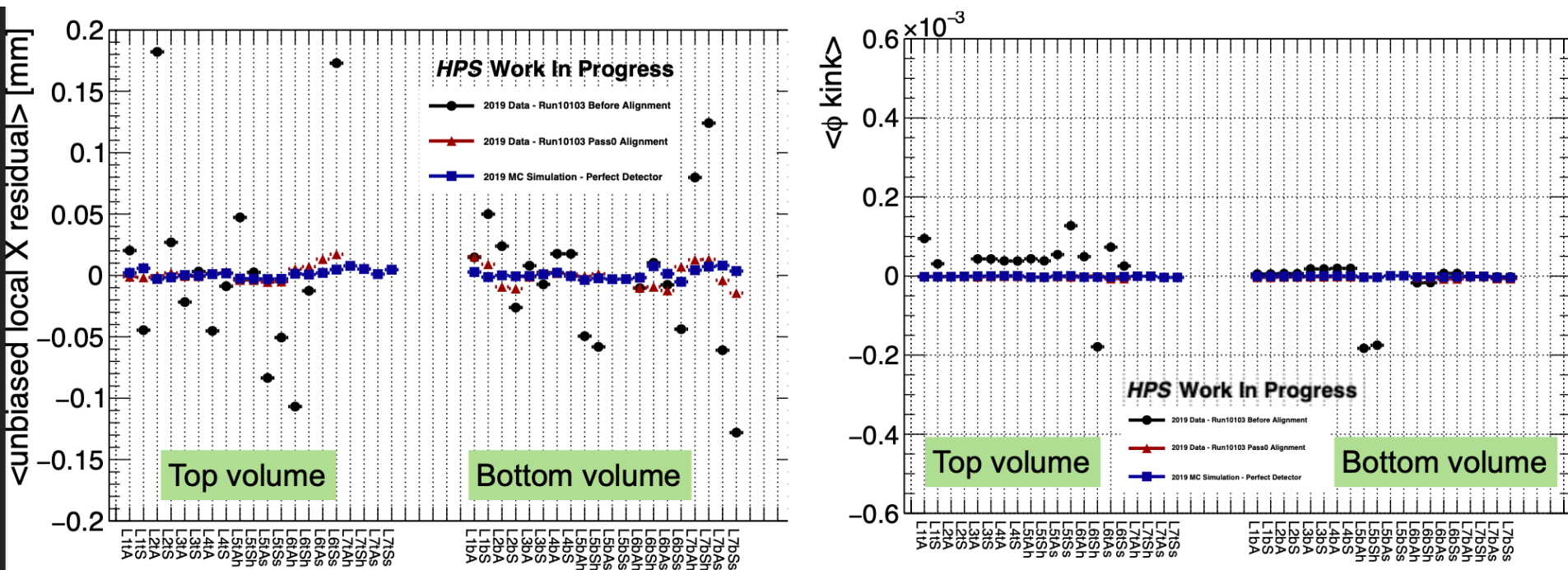
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 - In few of the metrics reached comparable performances
 - Some issues remain such as:
 - Time dependence, cluster-track matching still has biases, bottom residuals to be improved, shapes in the residuals still showing internal misalignments...
 - Vertex resolution and mean in agreement with MC simulation
 - Vtx pSum for 2019 dataset should be re-checked for July PAC with new alignment tag
 - Unfortunately I do not expect to be involved much (at all?) in the coming efforts regarding these endeavors.
-
- I feel privileged to have worked with you all and thankful for having had the opportunity to meet you and get to know this experiment and collaboration

BACKUP

- Proposal of new baseline constants for 2019 dataset
 - Focus on procedure documentation and motivation for each step
 - Comparison with current alignment tag, May 2019 constants
- General performance of 2019 alignment on FEEs
 - Did not have time to produce plots for e^+/e^- for today
 - If people agree with the reasoning behind today's presentation, will do next days
- Move to 2021 dataset

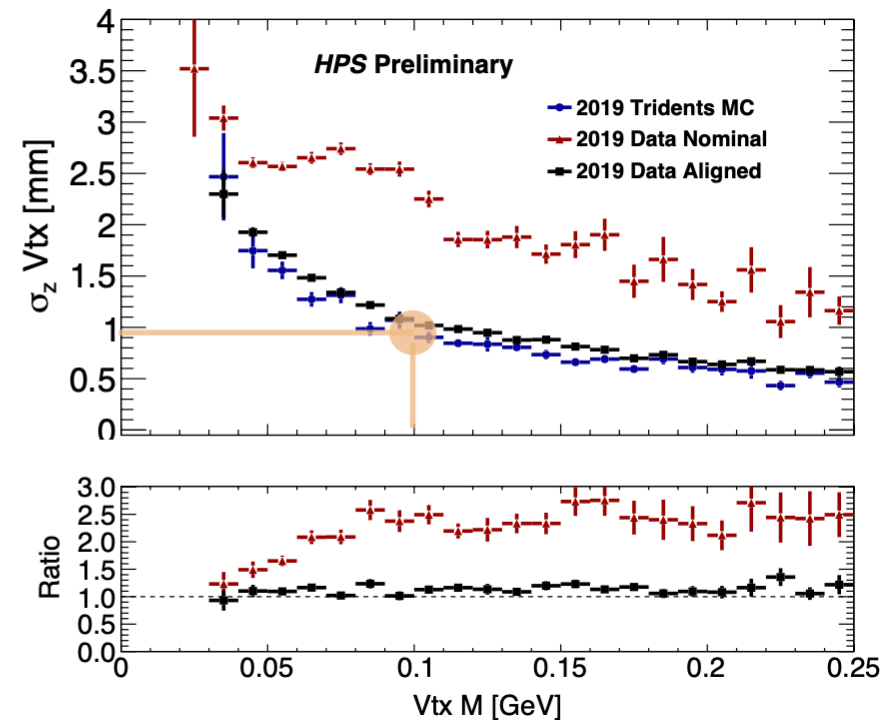
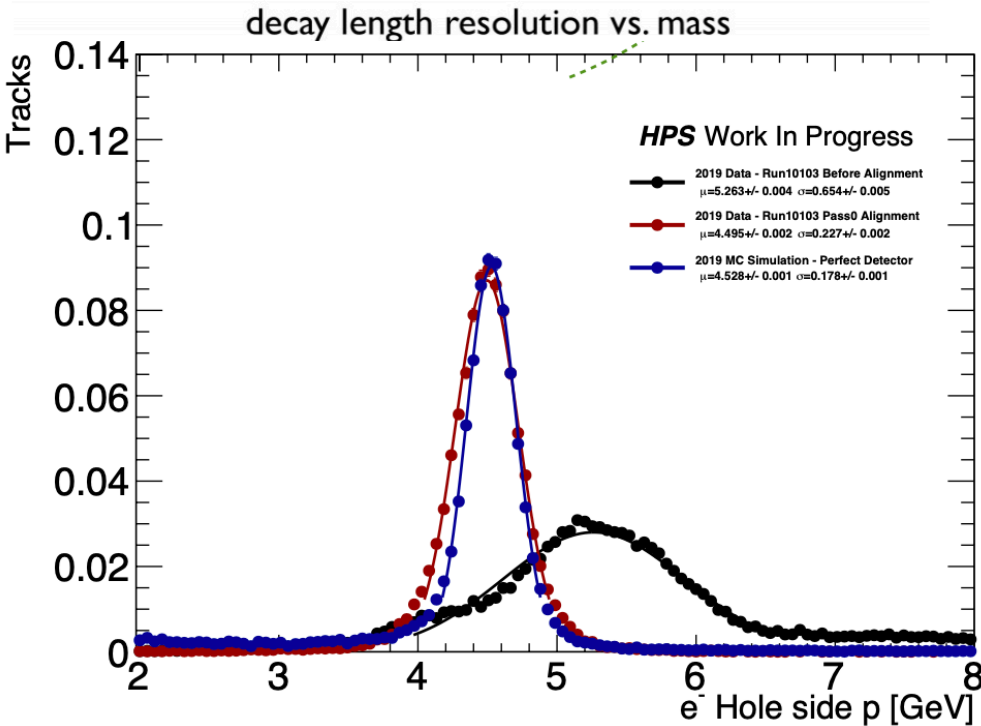
Recap of the general performance of “official” tag

- The “official” tag, i.e. what is in hps-java and can be used out of the box has been derived in 2020 from FEEs (mostly) with some corrections for e+/e- data
- Provides an aligned detector in terms of residuals / kinks.



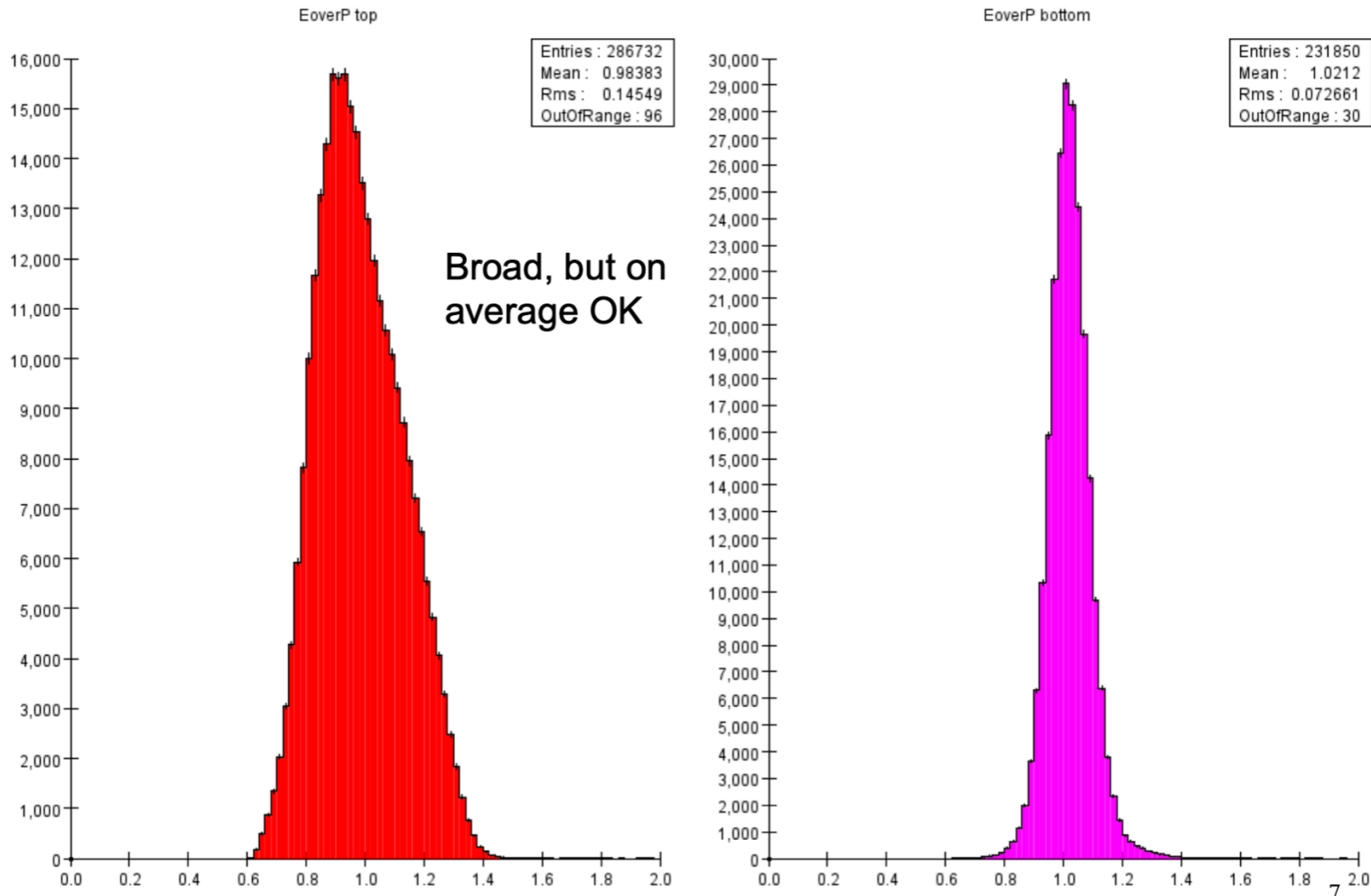
Recap of the general performance of “official” tag

- Provides almost the expected resolution on vtx_z from MC (within 10%)
- As well as close resolution in momentum wrt MC simulation



Recap of the general performance of “official” tag

- However characterized by bad momentum resolution in the top volume
- 2% bias / 7% resolution Bottom volume, 2% bias / 14% resolution top



Recap of the general performance of “official” tag

- Such resolution is considered unsuitable for analysis and need to be corrected
- This lead to the efforts in improving the alignment constants for top volume in the past several months

- We followed few strategies:
 - **Change of alignment starting point:**
 - Dedicated revisit of the HPS design and create a geometry that carefully reproduces that (**HPS_TimDesign_iter0**)
 - Revisit / crosscheck and recomputation of the survey constants for 2019 (Summarized by Sarah) to produce a new geometry starting point (**HPS_ShimShoSurvey_iter0**)
 - Multiple alignment **procedural changes** including reproduction of 2016 steps, different / mixture of FEE + e+/e- datasets, hierarchical alignment from global structures first

Re-Alignment strategy for 2019

- From 2020 alignment tag 2 new starting points have been used to re-align 2019 data
 - Nov '22: As Design detector
 - ~Sep' 23: Surveyed detector
- A summary of the procedures is given

Re-Alignment strategy for 2019

- Additionally I've been requested to perform a check using 2016 alignment strategy
- I performed a new alignment pass without usage of external constraints (BS or momentum) and used only e+/e- tracks from run 10031
- Not easy to really apply the same procedure in 2019 so I kept 2 main ideas:
 - **Keep fixed first and last sensor and align everything in between**
 - **Align the innermost sensors when the rest is fixed**

test #	start from #	floats	Delta p (T-B) MeV/c	chi2 res top	chi2 res bot	mean chi2 tot
0	-	-	40	33.62	71.77	20.14
1	0	tu 3+4+5 T&B	81	11.01	31.97	7.9
2	0	tu 2+3+4+5 T&B	20	9.7	31.9	7.59
3	2	tu 3+4 T&B	3	3.58	8.14	2.44
4	3	tu+tw 3+4 T&B	7	2.76	2.62	1.37
5	4	ru+rv+rw 3+4 T&B	23	4	3.73	1.63
6	5	tu 2+3+4+5 T&B	30	3.75	7.92	2.88
7	5	tu+tw 3+4 T&B	38	3.34	2.77	1.83
8	0	tuw 4+tuw3+tuw 2 T&B 3 steps in row	101	351.7	422.3	150.8
9	0	as 8 curved tracks only	-	-	-	-
10	0	tuw 4TB + tuw 3 + 2 tuw T&B	95	13.8	20.96	8.78
11	0	tu 2+3+4+5 T&B curved only	101	41	7.95	11.4
12	4	tu 1+6 T&B	0	0.56	2.13	0.7
12F	4	" with new fieldmap	3	0.56	2.15	0.7
13	12	global alignment (check compact)	153			14.7
14	12	ru+rv+rw 3+4 T&B	9	0.59	4.17	1.06
15	14	tu 3+4 B + ruvrw 4HB	33	0.56	4.18	1.08
16	15	ruvrw 4H+5H B	33	0.56	2.77	0.86
17	15	ru+rv+rw 3+4H B	26	0.56	2.5	0.82
17F	15	" with new fieldmap	26	0.56	2.48	0.81
18	15	ru+rv+rw 3+4S B	30	0.56	0.57 8 dof	1.48
19	12	tw 4B new fieldmap	5	0.56	0.46	0.49
20	19	ru+rv+rw 4T hole+ 4B	10	0.56	0.99	0.49
21	20	d0, z0 global centering	1	1.86	1.35	0.73
22	21	d0, z0 global centering	5	1.88	1.36	0.74
23	22	tu+tw 1+2+3 T+B	6	0.61	0.86	0.46
24	23	d0, z0 global centering	6	0.57	0.73	0.43
25	24	tu+tw 6T+6B	10	0.45	0.62	0.39

Alessandra's Talk in 2018

- The actual internal alignment corrections performed in 2016 seems to be described in the [2016 compact](#):

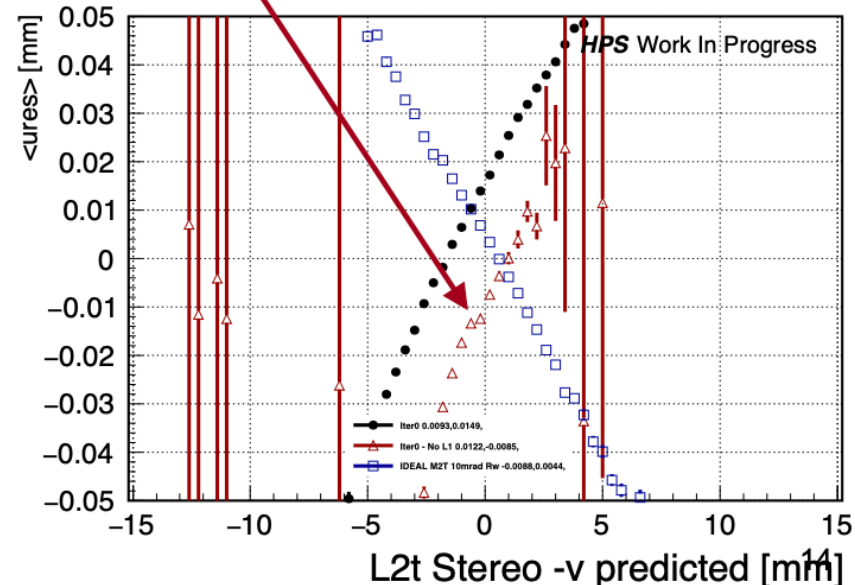
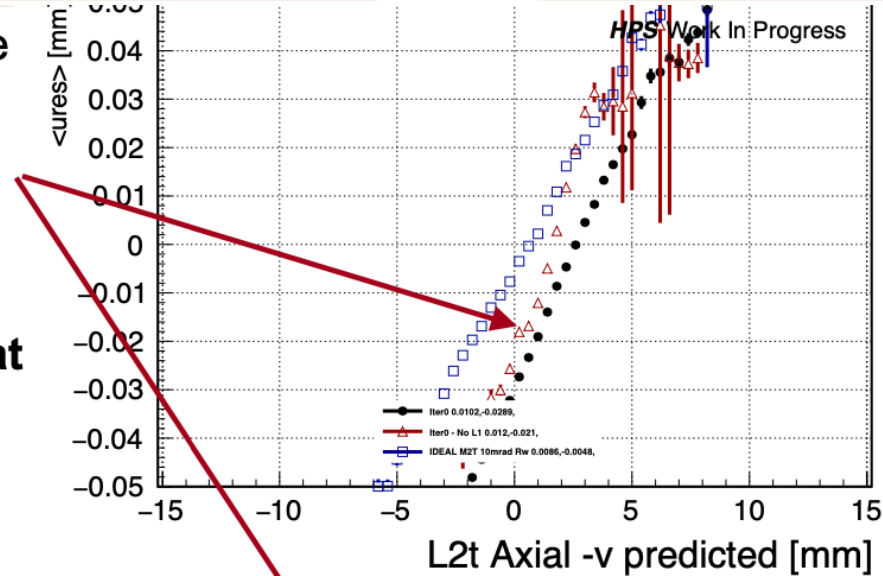
This is an X correction and only for bottom

Global +1 mm shift in y
 Correction on top and bottom Layers 1-3 opening angle
 Millepede internal alignment
 (iterations: 3-4-5TB tu + 2TB tu + 3-4TB tu + 3-4TB rw +1-6TB tu + 3-4TB tu+rw)
 Corresponds to version #31

Rotations of Innermost sensors

- The trends are present in similar form in both the tracks found with and without L1top
 - **Slope also present when L1 is removed**
- It cannot be a full module Rw as previously suggested:
 - **Opposite slopes for Stereo and Axial in that case**
 - Tested on ideal MC + 10mrad Rw of M2T module

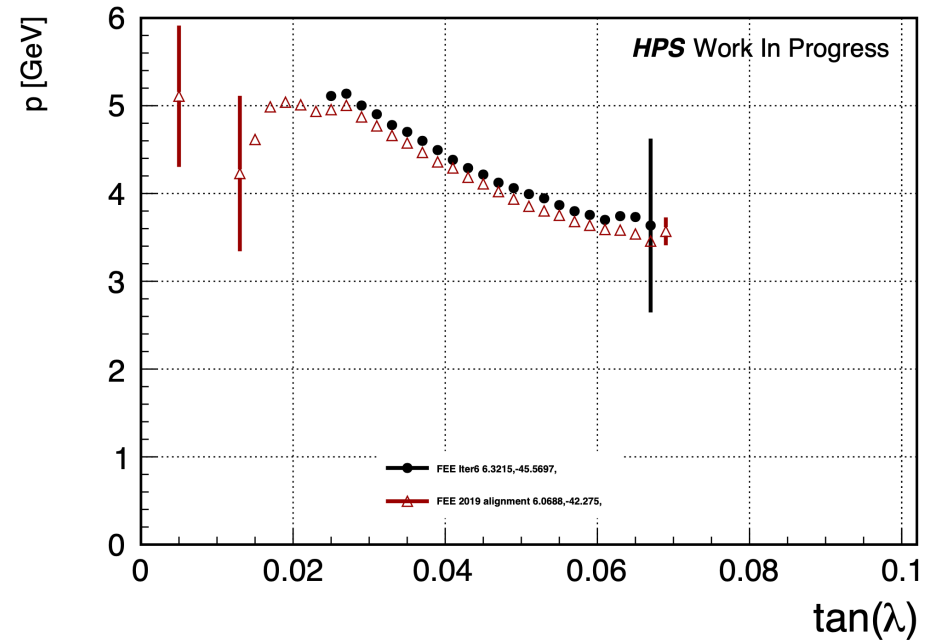
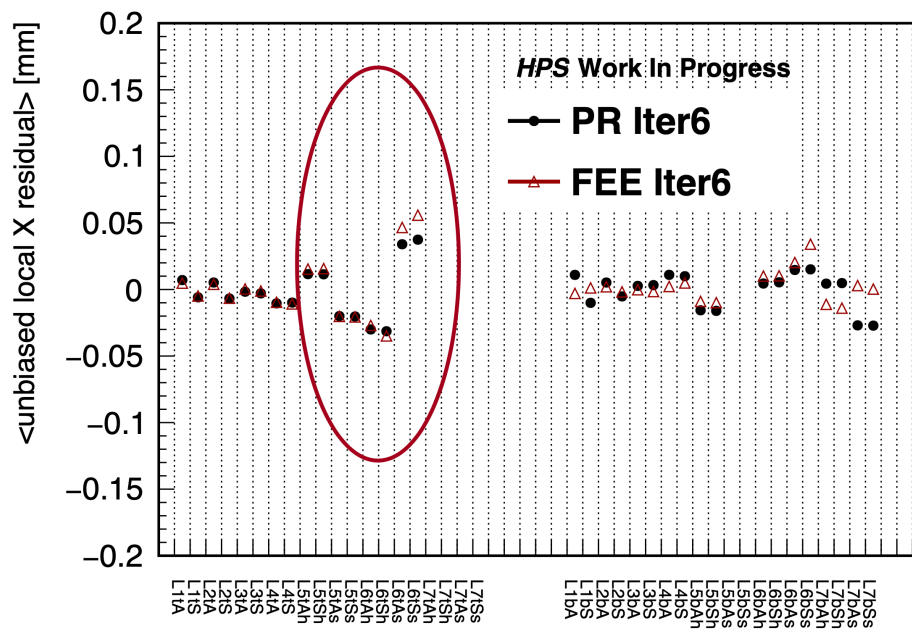
2019 corrections. Stereo sensor
~ 8-10mrad rotation



```
<millepede_constant name="12301" value="0.0 -0.002500 -0.001700" />  
<millepede_constant name="12302" value="0.0 -0.004700 -0.001600" />  
<millepede_constant name="12303" value="0.0 -0.008000 -0.000200" />  
<millepede_constant name="12304" value="0.0 -0.008000 -0.000900" />
```

```
<millepede_constant name="22301" value="0.0 -0.008033 -0.001779" />  
<millepede_constant name="22302" value="0.0 -0.003447 -0.001482" />  
<millepede_constant name="22303" value="0.0 -0.011274 -0.001217" />  
<millepede_constant name="22304" value="0.0 -0.005886 -0.001047" />
```

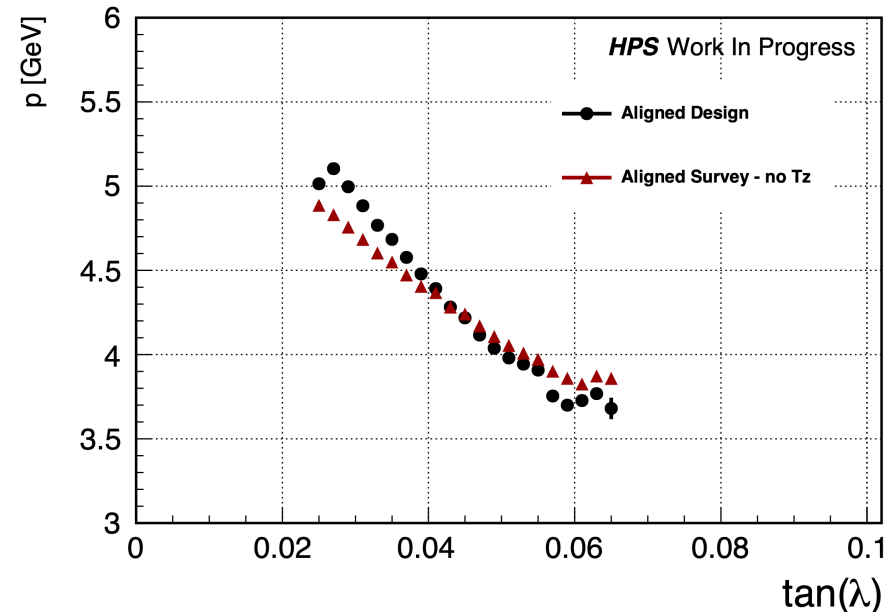
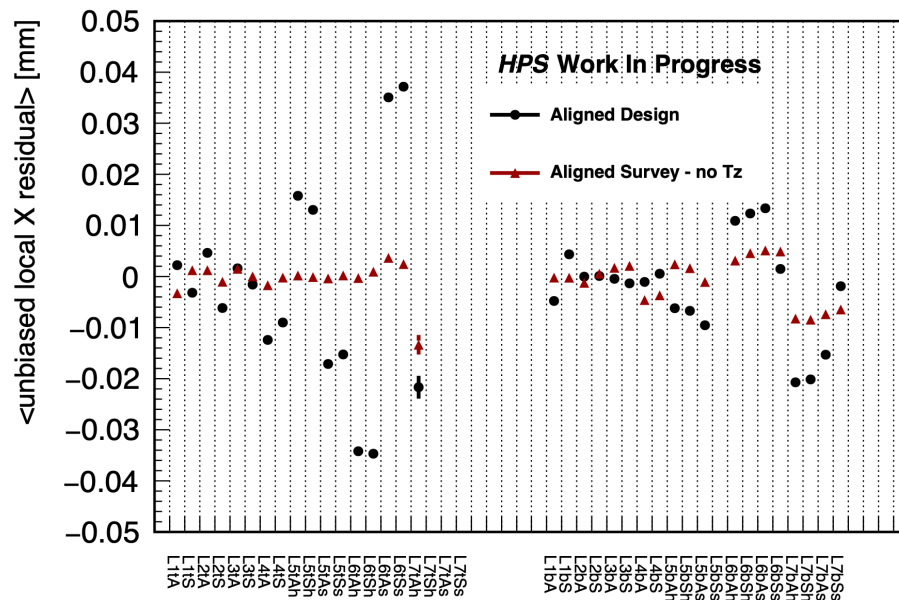
Results from Design



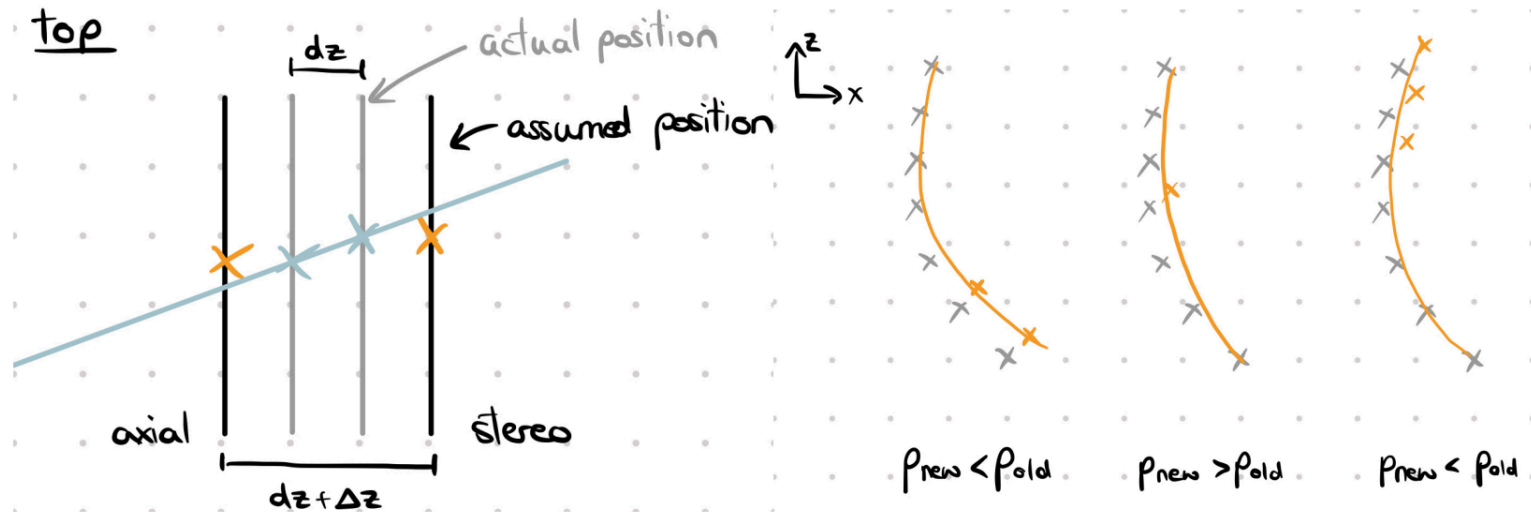
- A Full report on the procedure given in May Collab Meeting
- Residuals are due to resu vs tanL dependence
- **No sizeable improvement on previous iteration re-using 2020 constants.**

Re-alignment from Survey

- The re-alignment on survey focuses on the fact that survey sensors positions are known and Innermost Sensors positions are largely unknown.
- Perform alignment of innermost sensors first, then move to back sensors
 - Improve detector residuals and track parameters with BS + MomC
- **Perfect residuals in top volume, marginal improvement on momentum slope**



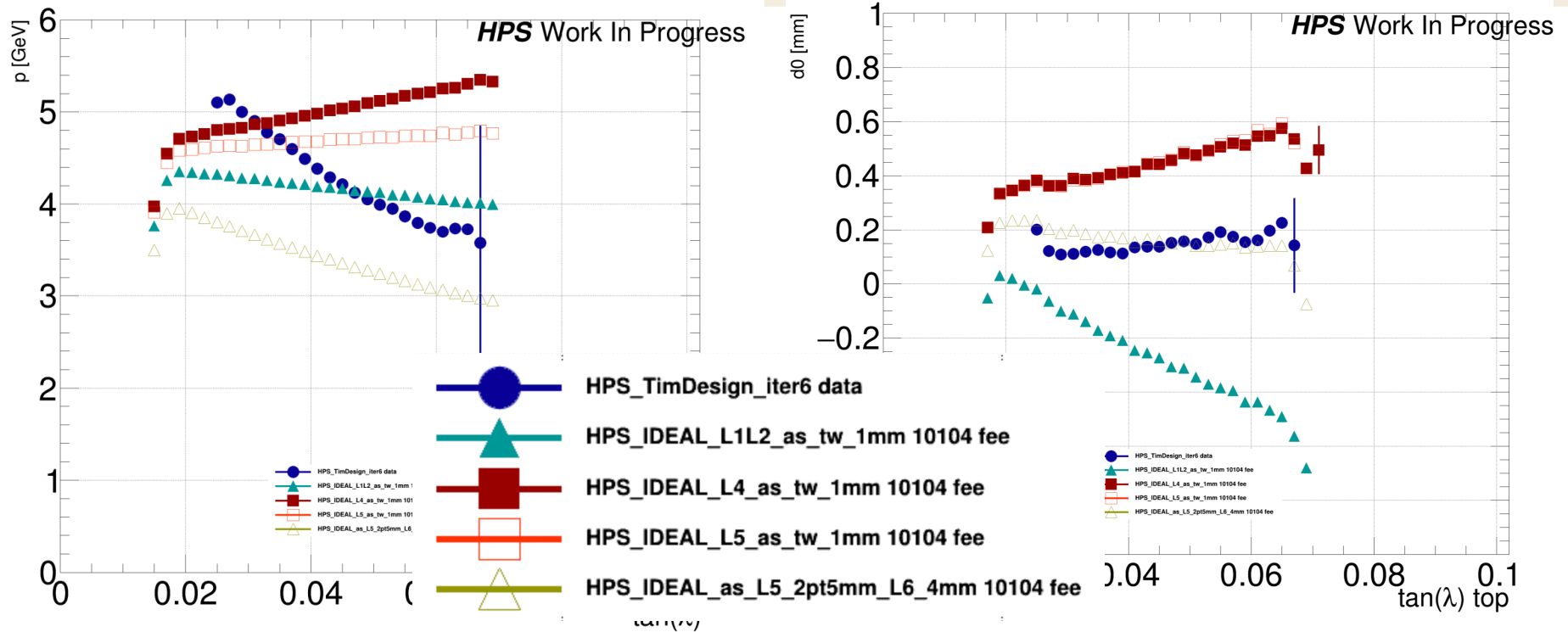
Effects of increased sensor separation on curvature



Sarah

- Actual position of sensors and hits (grey and blue) and reconstructed position with misaligned detector (black and orange)
- Decrease of reconstructed $\|\tan \lambda\|$ and ϕ
- Movements in front and back \rightarrow increase of curvature, movements in middle \rightarrow decrease of curvature

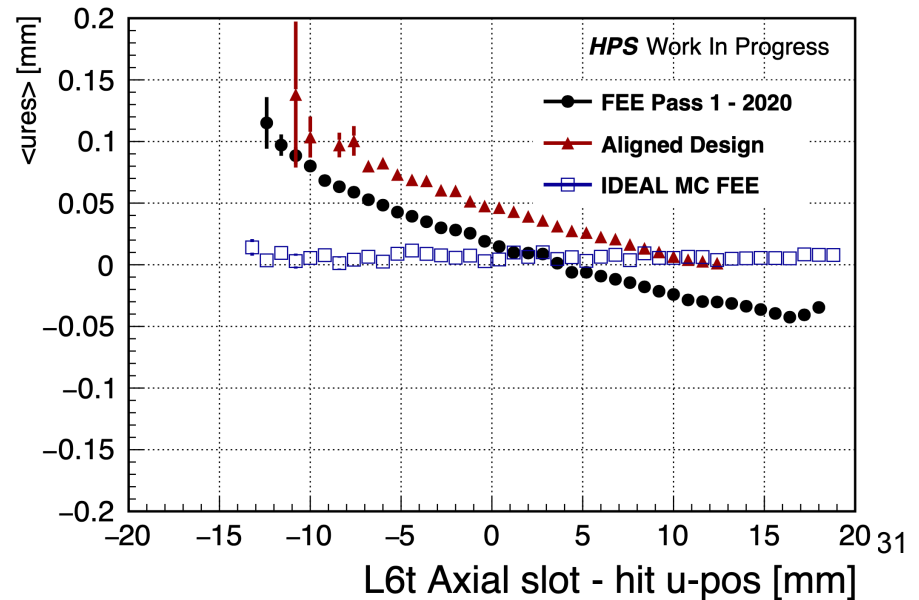
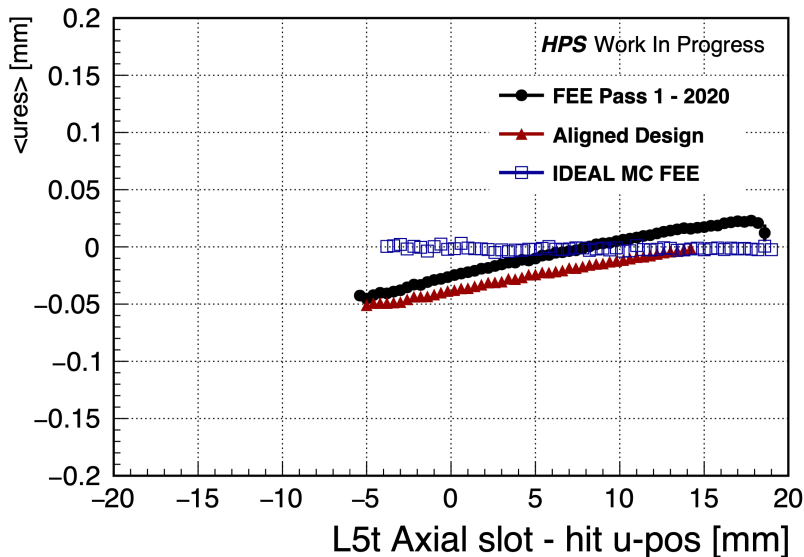
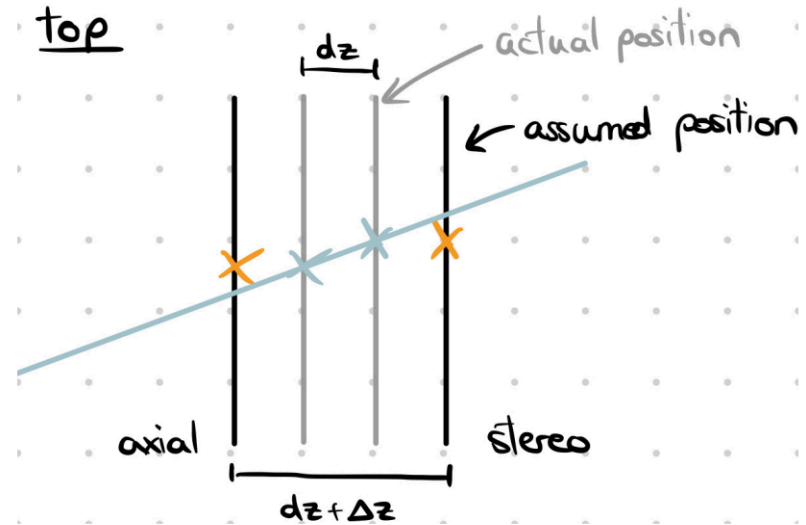
Effects of increased sensor separation on curvature



- Movements out of plane will have effects on curvature as well as d_0 as function of $\tan L$
- Rotations in rW of stereo sensors do not produce the same results
 - $O(4\text{mrad})$ Rotations of L1L2 stereo do not produce similar d_0 vs $\tan L$ (backup)
 - $O(\text{mrad})$ Rotations of L5L6 in rw do not produce similar p vs $\tan L$ (backup)

Additional evidence of out of plane misalignments

- Additional evidence for out of plane misalignment is given by the presence of residual trends as function of $\tan L$ (or hit measured position on layers)



Difficulty to align out of plane

- Our tracks are basically perpendicular to the sensors
 - $\tan L \sim 0.02$
- This means that $dR/dTw \sim \tan L \ll 1$, leading to large possible corrections
- A large Tw will have minimal impact on Chi2: definition of weak mode
- Additionally releasing multiple sensors at once free the telescope scale resulting in \sim singular matrix in the linear system

- Chi2 approach
- Symmetric real matrix, always diag
 - Eigenvectors correspond to coherent movements of sensors
- In this example I moved all the back layers from L3-L6 in u/w

```
Store          3 : low-value end of eigenvalues
stored n-tuples:          16
  1  1.000000    0.7091320E+10
  2  2.000000    0.6890340E+10
  3  3.000000    0.2592552E+10
  4  4.000000    0.2048553E+10
  5  5.000000    0.7688589E+09
  6  6.000000    0.1521045E+09
  7  7.000000    0.4009384E+08
  8  8.000000    3264373.
  9  9.000000    539056.9
 10 10.000000    524527.5
 11 11.000000    204057.8
 12 12.000000    153961.9
 13 13.000000    60010.82
 14 14.000000    12762.64
 15 15.000000    3774.473
 16 16.000000    401.6375
```

- Eigenvalues span across 8 orders of mag
- **Eigenvector 12 poorly constrained**
 - **Weak mode, corrections unreliable**
 - $\sigma_{corr} \sim 1/\lambda_{corr}$

Difficulty to align out of plane

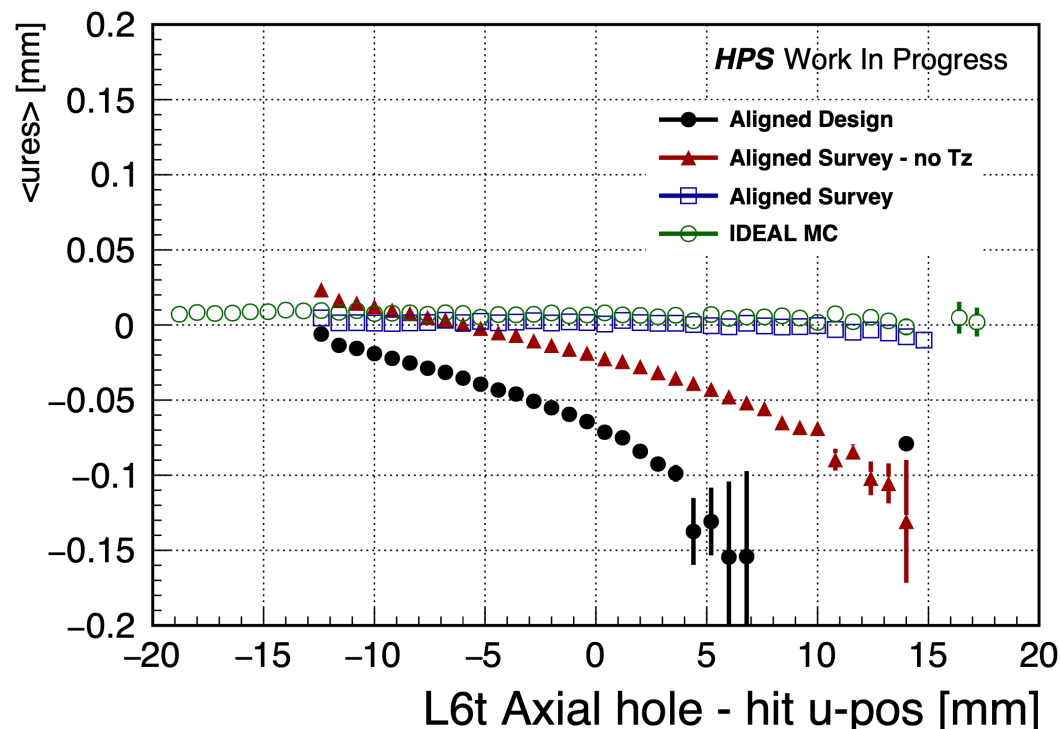
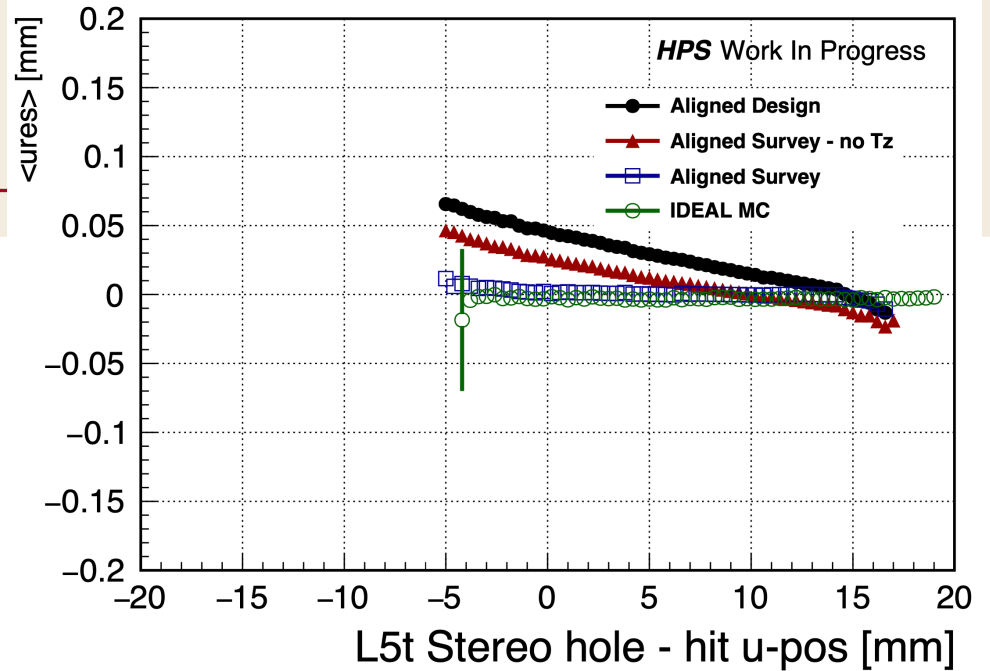
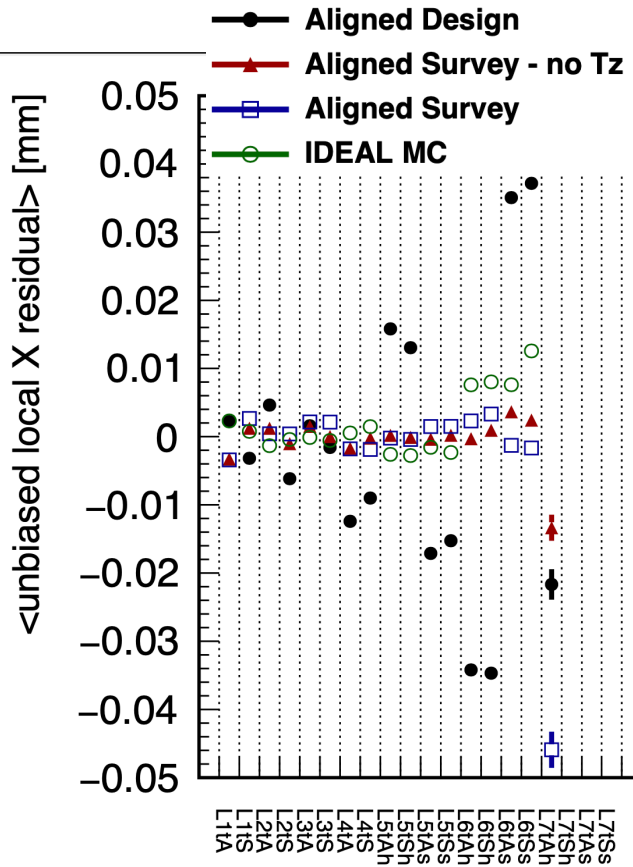
- **Challenge in 2019 alignment:**
 - No strong mode T_u/R_w or linear combination of those across many modules provides complete correction of observed track parameter biases
 - **But again, I might have overlooked.**
 - Residuals strongly depend on $\tan L$:
 - Physics and FEEs will have different residuals as they illuminate the detector differently in $\tan L$
 - Indication of sizeable of plane distortions.
 - Not possible to align in one go out of plane due to weak modes
 - Even with V_{tx} / momentum constrain. Better with e^+/e^- but too low $\tan L$ anyway.

Procedure I followed

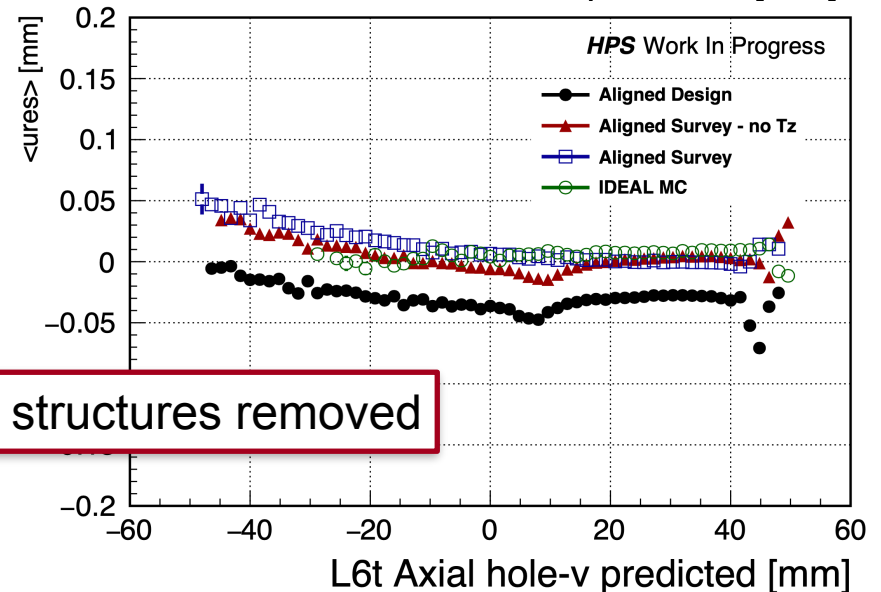
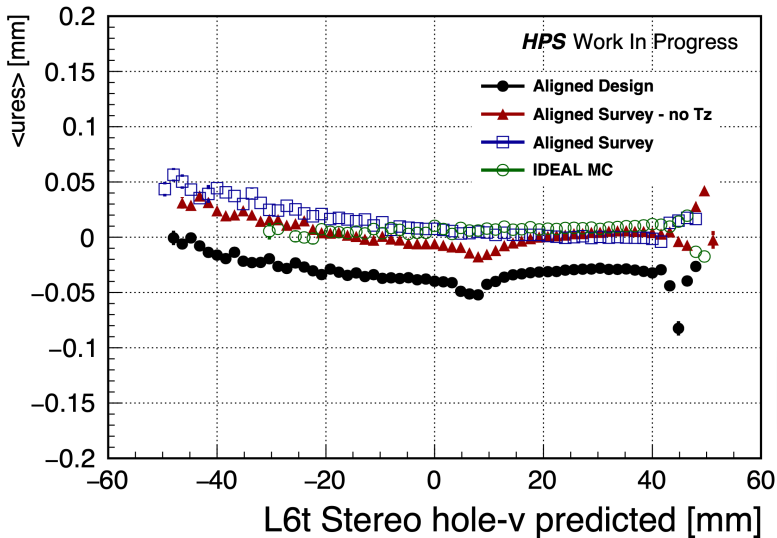
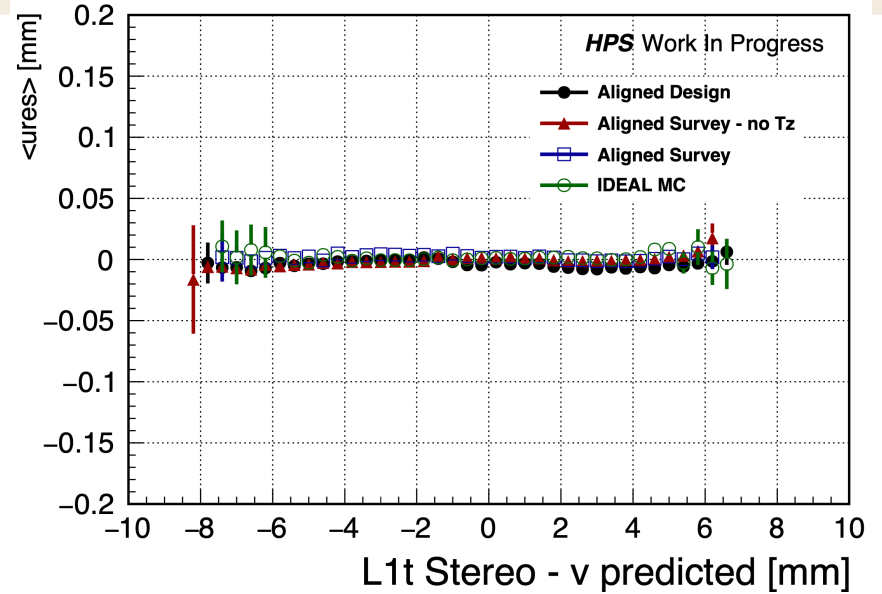
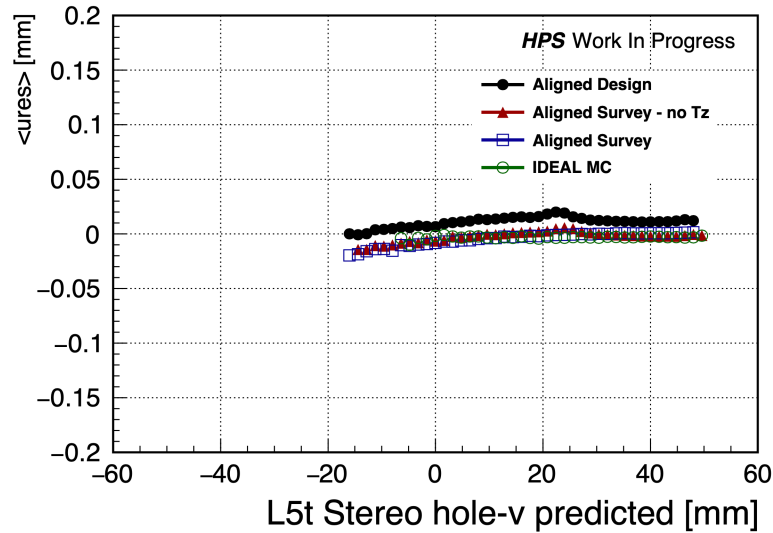
- **Used BS and P constraint assuming 4.55 GeV and -7.5 target**
- 1 - tu/rw/tw of L1-L2
 - This causes d0 vs tanL bias in Top
- 2 - tu/rw/tw of L4-L5
 - Use L123 and L6 to constraint Z scale
- 3 - tu/rw/tw of L5S + L6
 - Improve momentum
- 4 - tu/rw/tw of L1-L2
 - Reduce d0 bias (it takes out corrections from 1)

- **Final Tz corrections in backup**
 - **Up to 1mm in Stereo correction at ly6 (~1 / 700 correction to z scale)**
 - **Kept it as small as possible, doesn't fully correct the biases**

Results

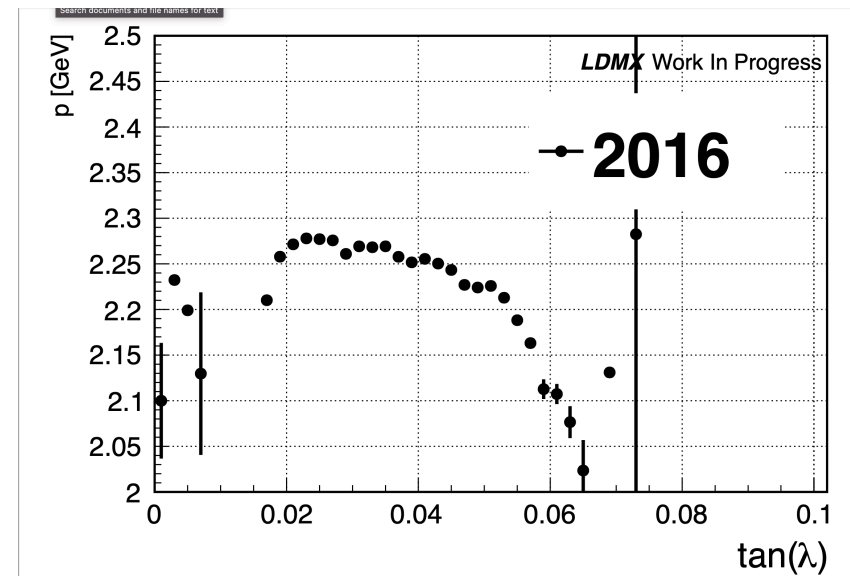
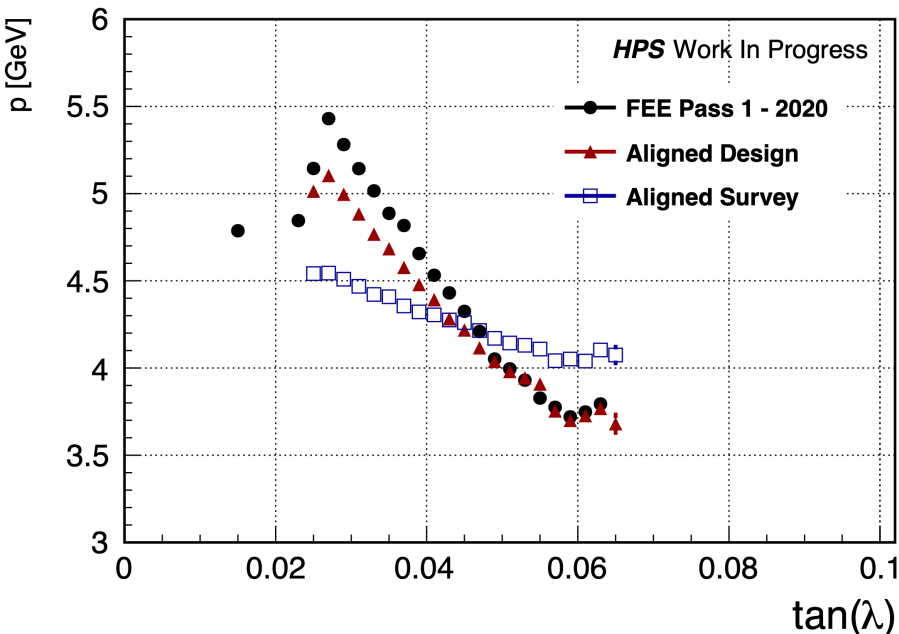


Results



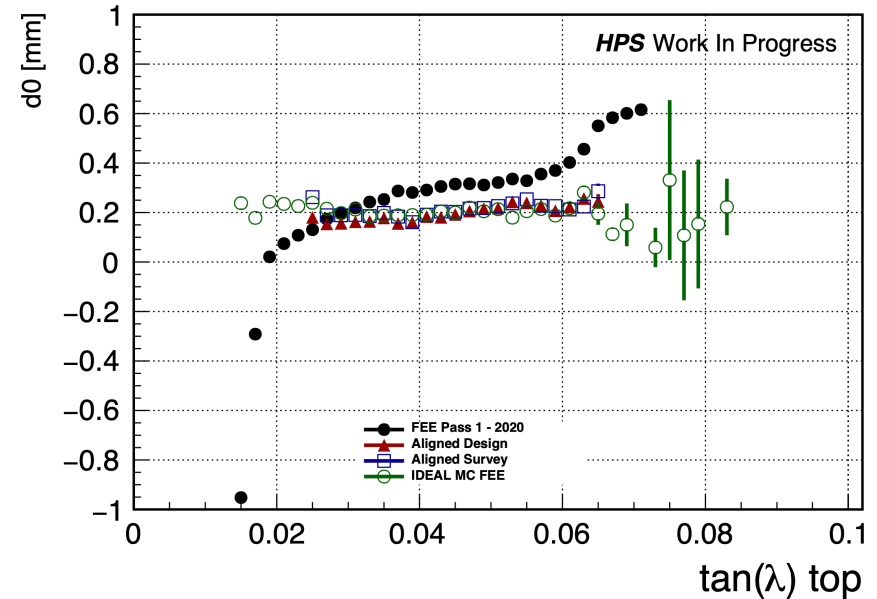
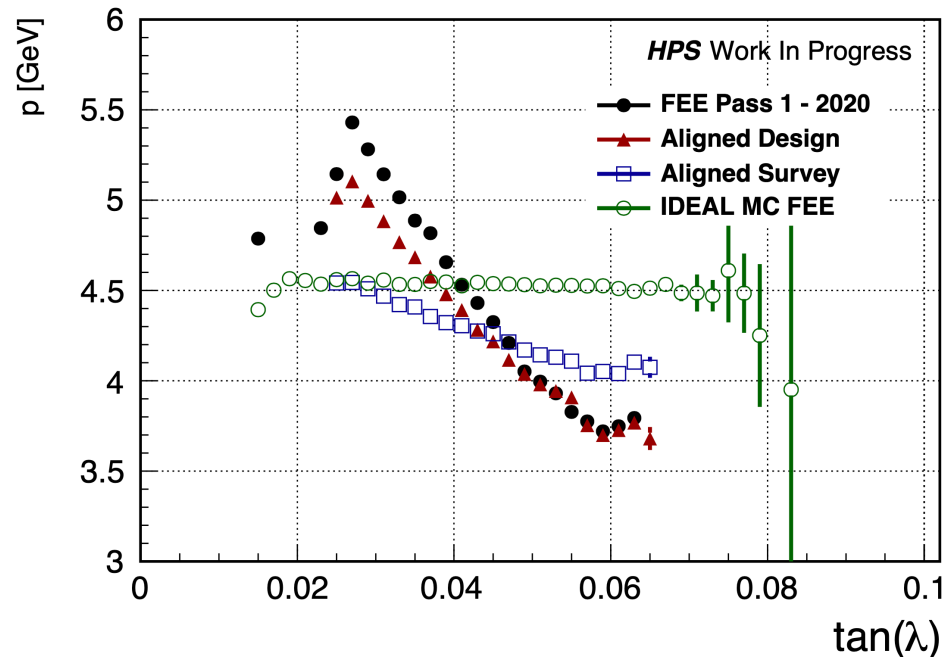
Momentum Biases

- After the re-alignment procedure on Surveyed detector the momentum bias due to $\tan L$ is of the order of **$\sim 10\%$ in $[0.025, 0.06]$ interval** [4.5 to 4]
 - **FEE Pass 1 - 2020 was $\sim 50\%$, $\sim 30\%$ in Aligned Design**
 - A dedicated look to 2016 run7800 shows $\sim 6\%$ [2.28 to 2.15]
- There is a left-over bias that can be removed by simple translation of stereo sensors.

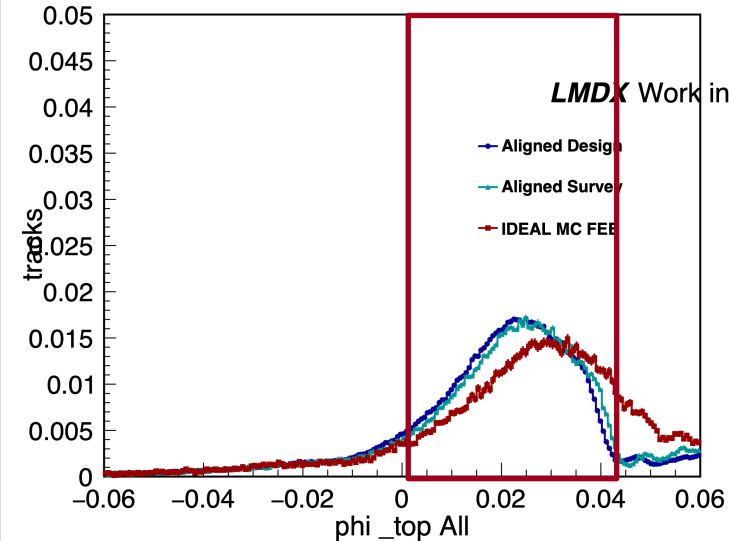
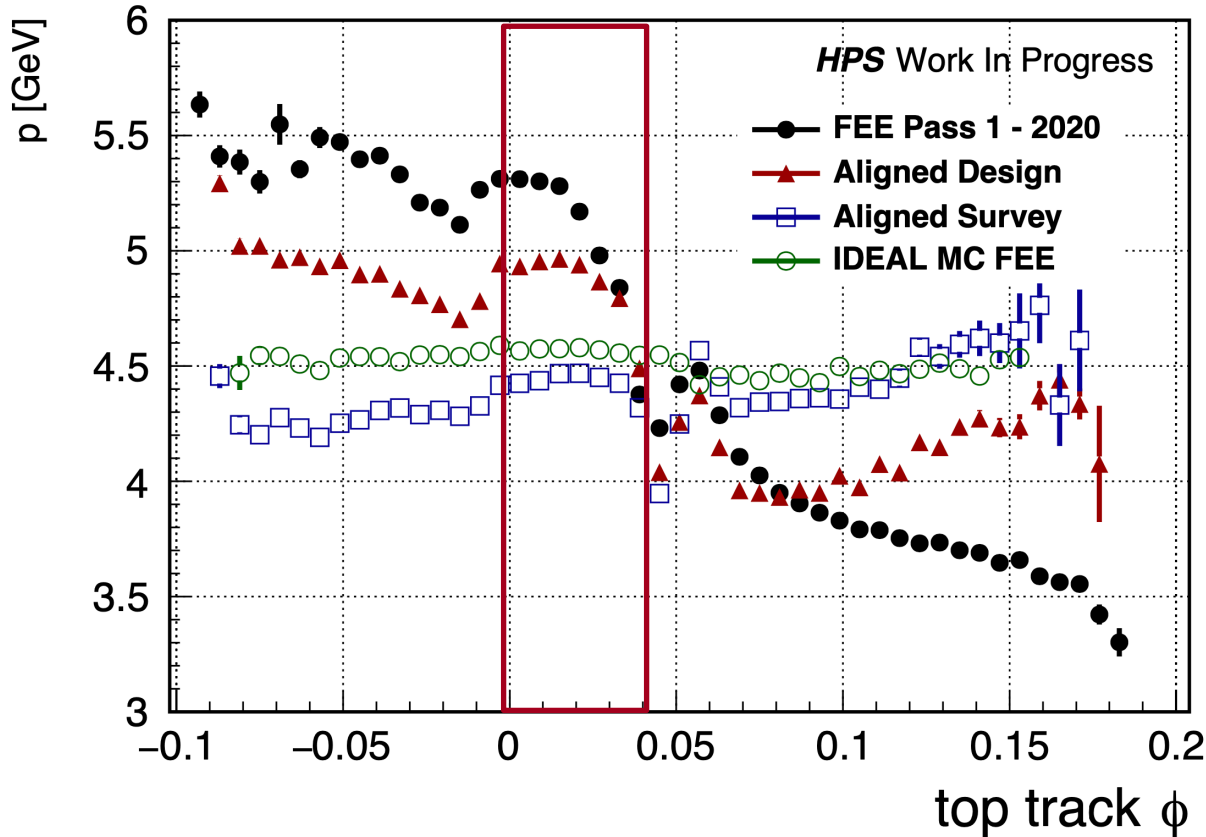


Momentum Biases

- There is some tension between p and d_0
- As discussed it can be eliminated by moving stereo sensors in the front in w
- The d_0 is flat at 200 μm corresponds to a target at -7.5 mm as shown by FEE MC. Momentum vs $\tan L$ is completely flat in MC.



Momentum Biases

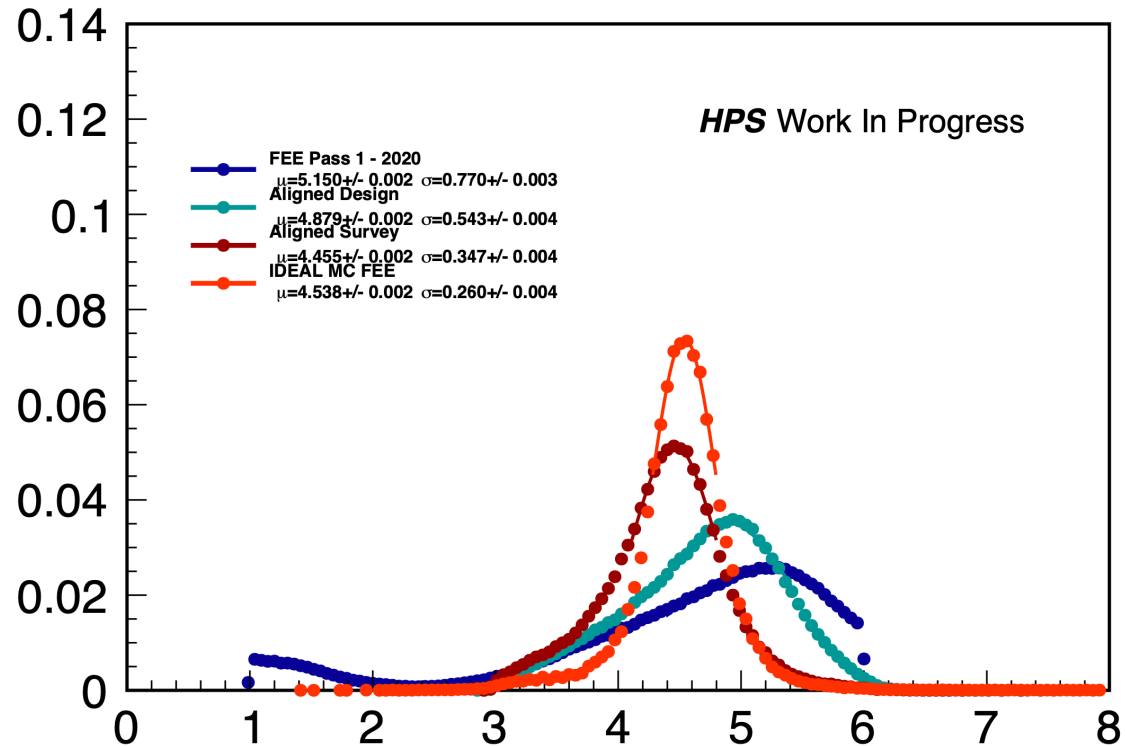


• Most of FEEs are central, phi biases don't matter too much in this study

- Phi dependence largely improved sensors wrt previous iterations
- Smoother MC at $\phi \sim 0.05$ due to ≥ 5 hits requirement instead of $=6$
- Can be improved a bit in Data with additional work, or corrected in analysis by $\tan L/\phi$ bias map.

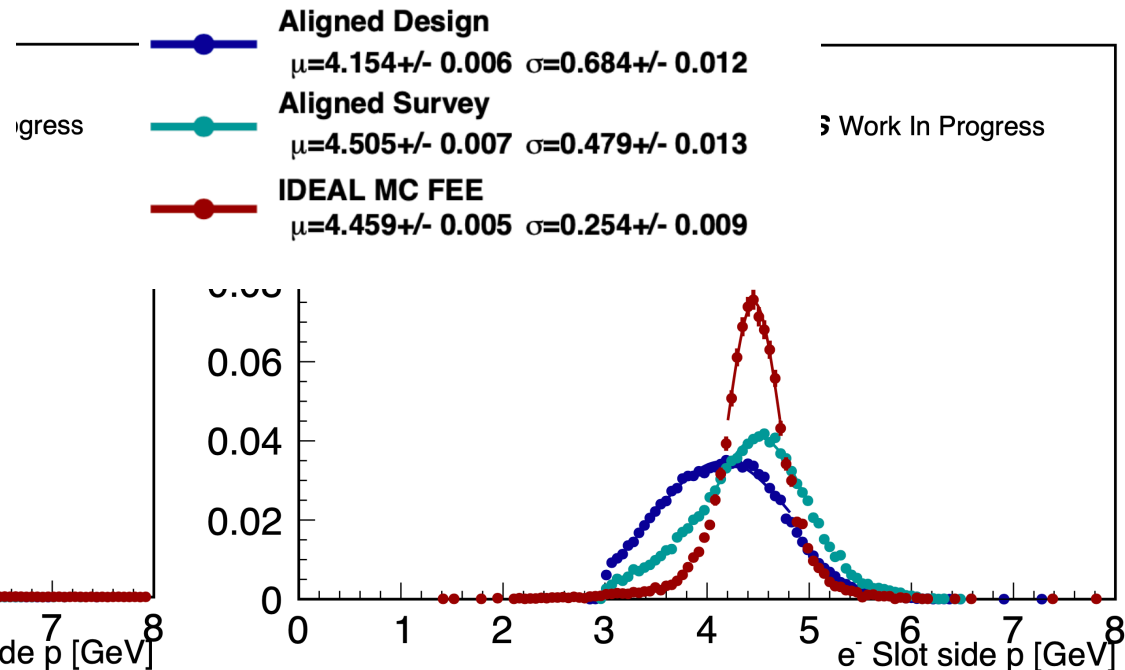
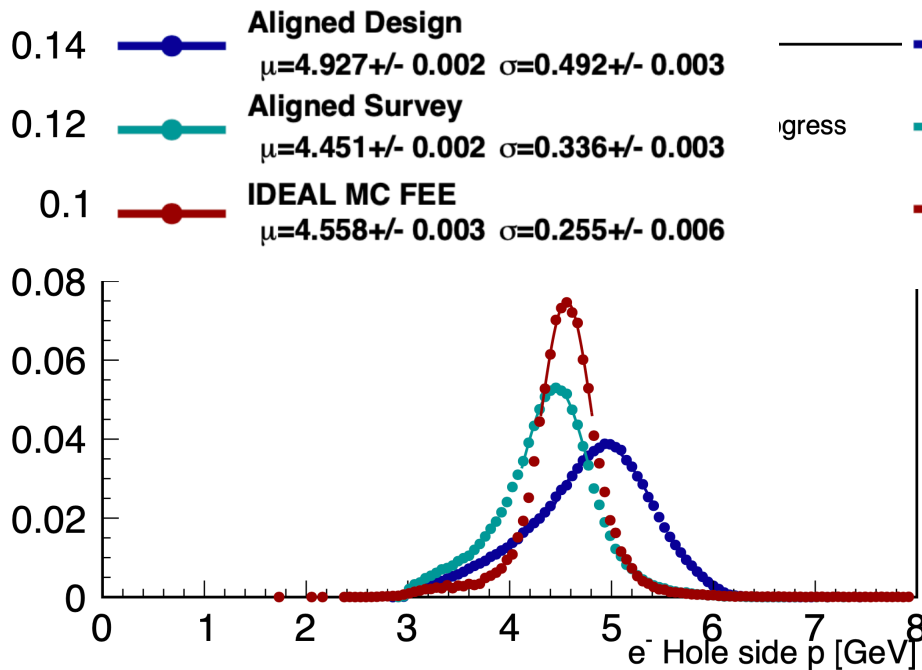
Momentum Resolution

- Momentum resolution improved from 770 MeV to 350 MeV (7.7% @ 4.55 GeV vs 5.7% in perfect MC)
- Data 35% worse resolution than MC, 50% in 2016.
 - Not fair comparison, different kinematic regimes and sources of uncertainties as discussed yesterday.
 - Known dependence from tanL can be removed during analysis.
- 2% bias wrt perfect MC can be removed by back layer translations



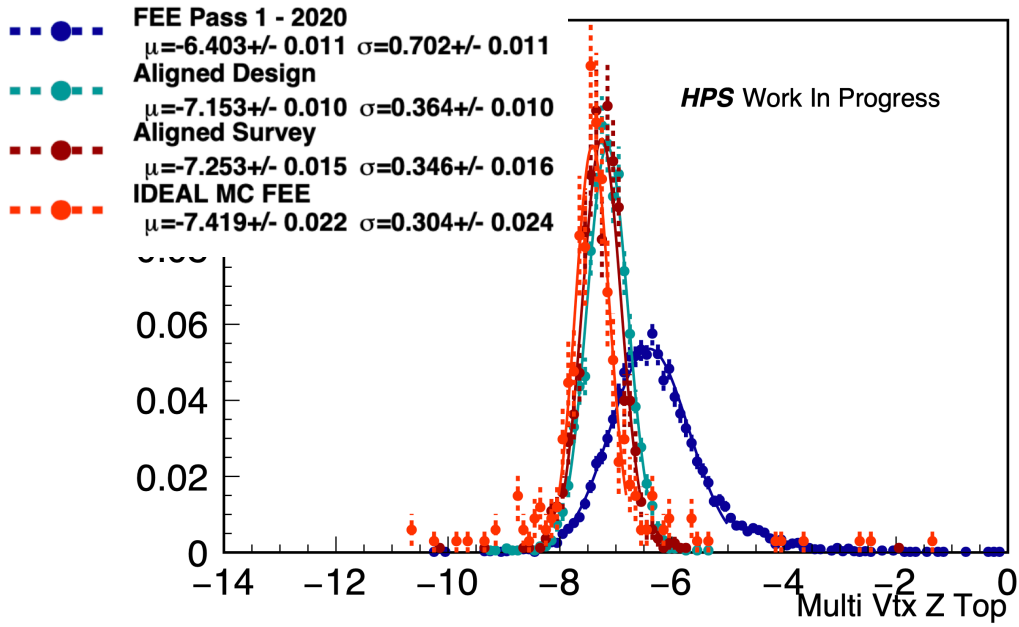
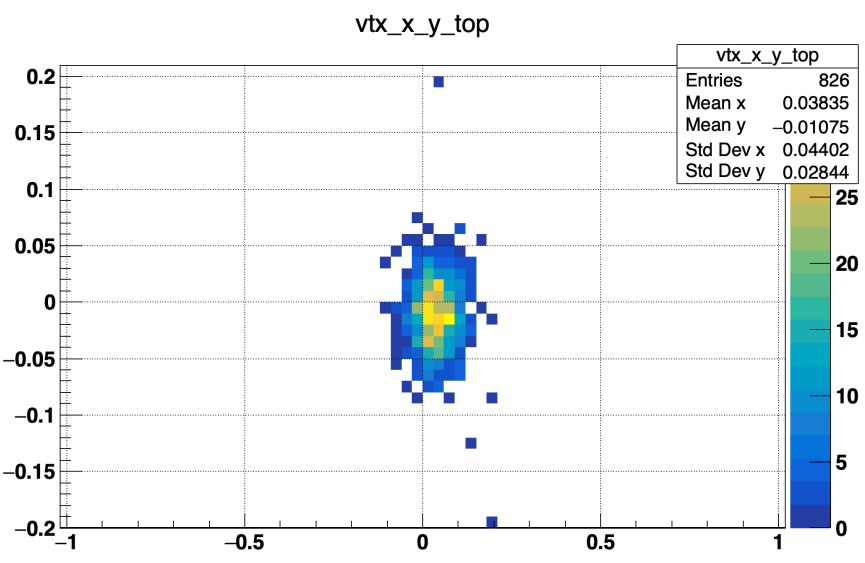
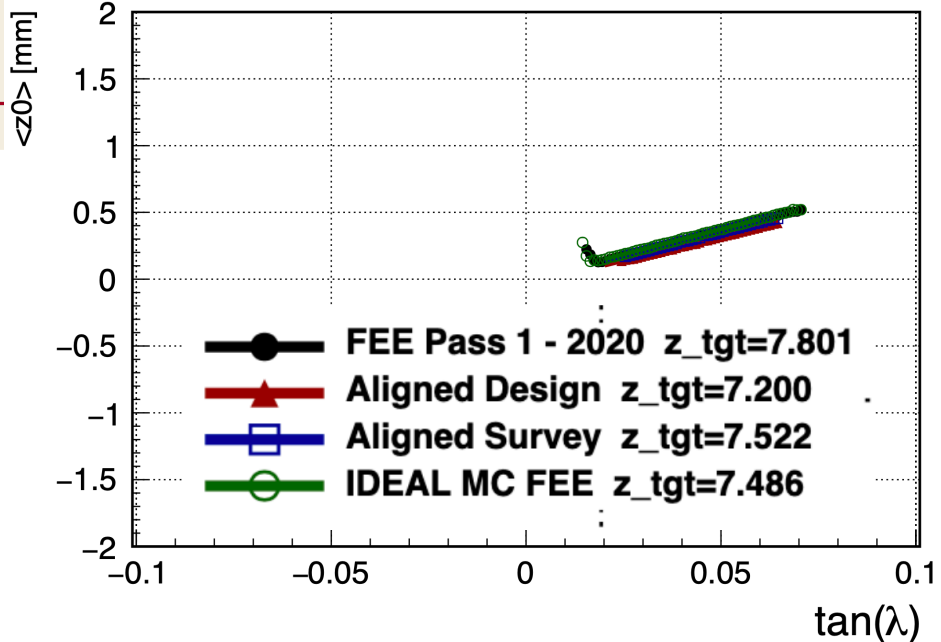
SLOT / HOLE Momentum

- Momentum scale compatible between Hole and slot side
- Resolution could be improved.
 - More difficult than hole side due to stat. More driven by phi dep than hole side
 - E/p on e+ probably helps



Vertex location

- Z0 vs TanL and multiVtx location provide compatible locations to the Z target
- Discrepancy up to O(700-800um) between the methods observed in the past



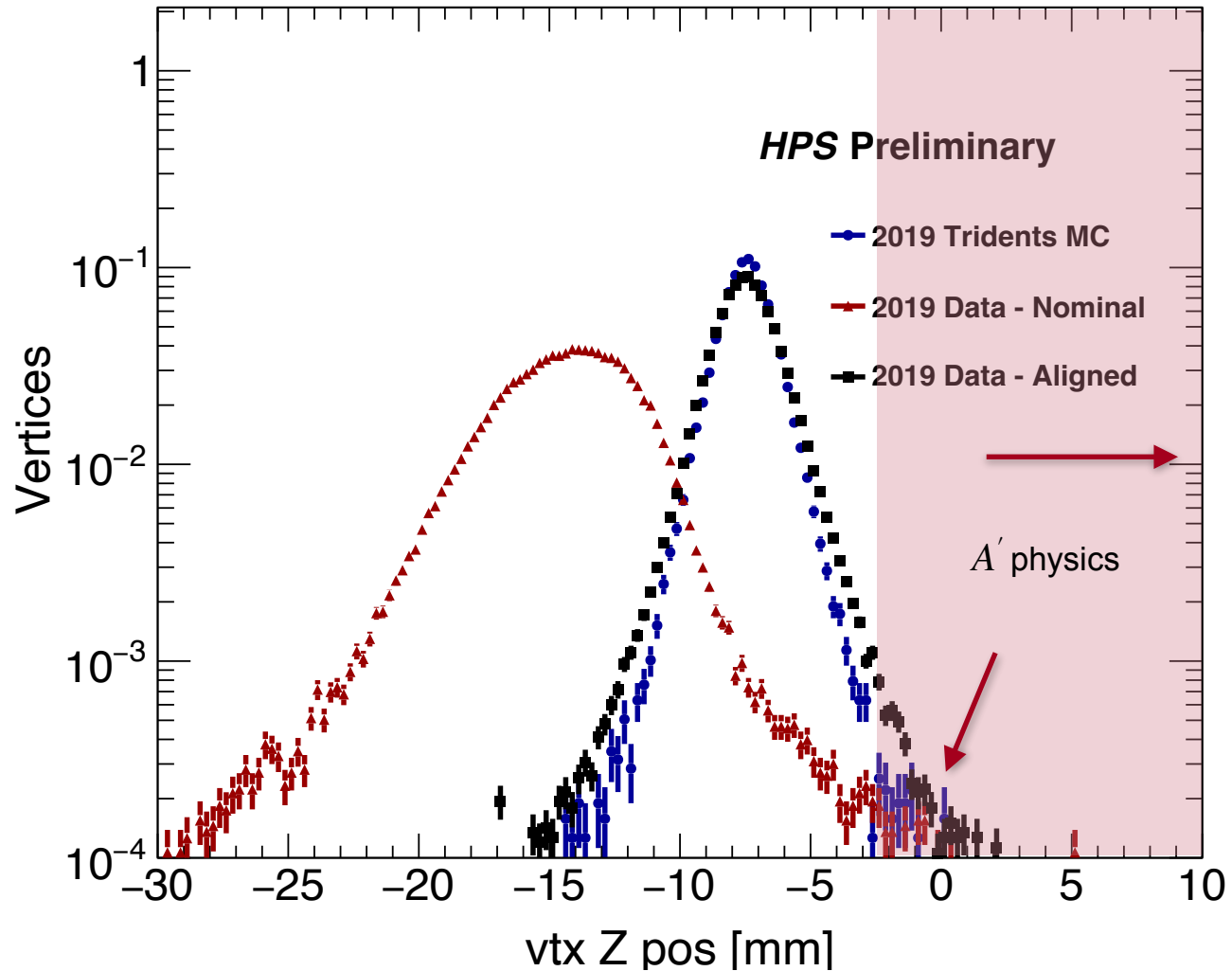
Summary

- The p vs $\tan L$ in 2019 seems like it's a pretty though bias to be removed
- Difficult detector deformation that could be :
 - **Real**: Some misalignment of the detector arisen at a certain point or sensors out-of-plane deformations
 - **Fictitious**: Introduced by our reconstruction or all single alignment procedures followed in the past years (I lost count how many I did)
- I am arriving at the exhaustion of my ideas
 - Larger corrections can be done to fully recover the bias if wanted
- Solution found provides not perfect, but in my view, acceptable performance as well as a procedural approach on how to improve it further
 - Fixes can be done also from analysis side.
- **Necessary next steps:**
 - **Validate on e^+/e^-**
 - **Apply same approach to bottom**
- **Release, some run-by-run studies, move to 2021**

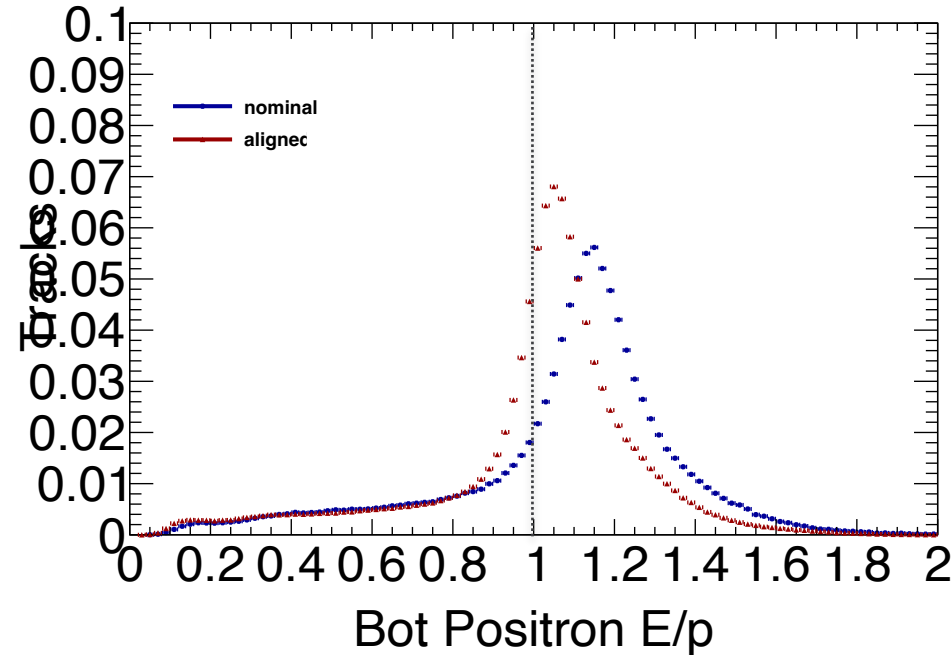
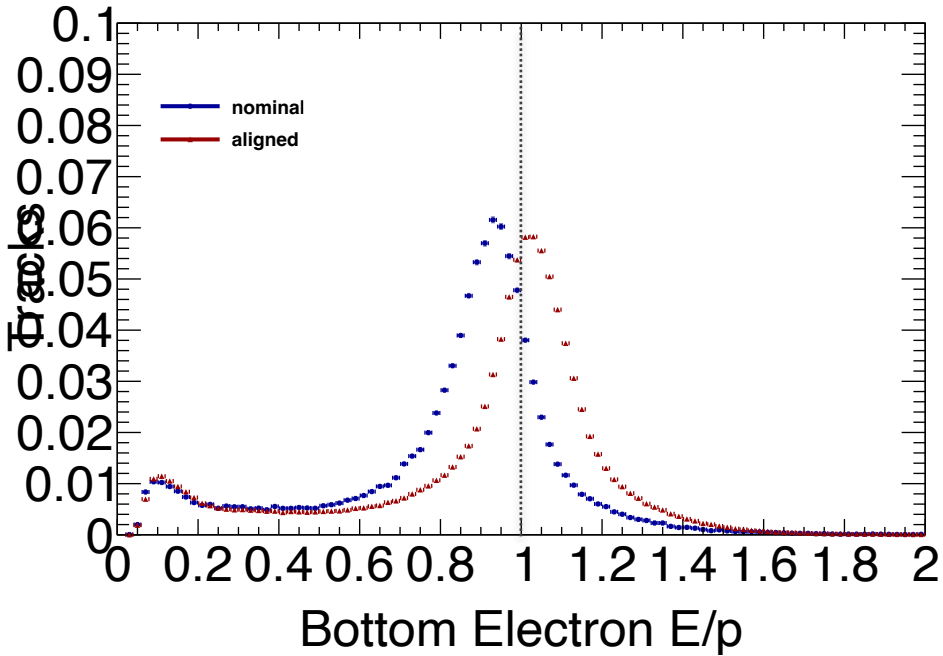
Some personal thoughts

- I found the HPS detector difficult to align to a satisfactory degree of performance using standard minimization procedures.
 - Of course, this might just be me
- Things that can be improved in advance wrt 2025
 - 2019 alignment was performed concurrently with major changes in reconstruction code and suffered of loss of continuity with previous iterations
 - Simulation studies before jumping on trying to solve the pressing issue
 - Better calibration / standardized samples
 - Norman worked in this direction but I think we could do better.
 - **Multi run e+/e- sample with flat tanL distribution would be useful**
 - Poor degree of trust on relative axial-stereo measurements
 - Would benefit to have that so modules can be aligned as composite structures (providing 3D point info).
 - Other experiments will be tackling this challenge (sPhoenix, ATLAS Itk, FASER..) we should share tools more
 - **Document things in an useful and comprehensive way**
 - A special mention to Sarah and Tom here.

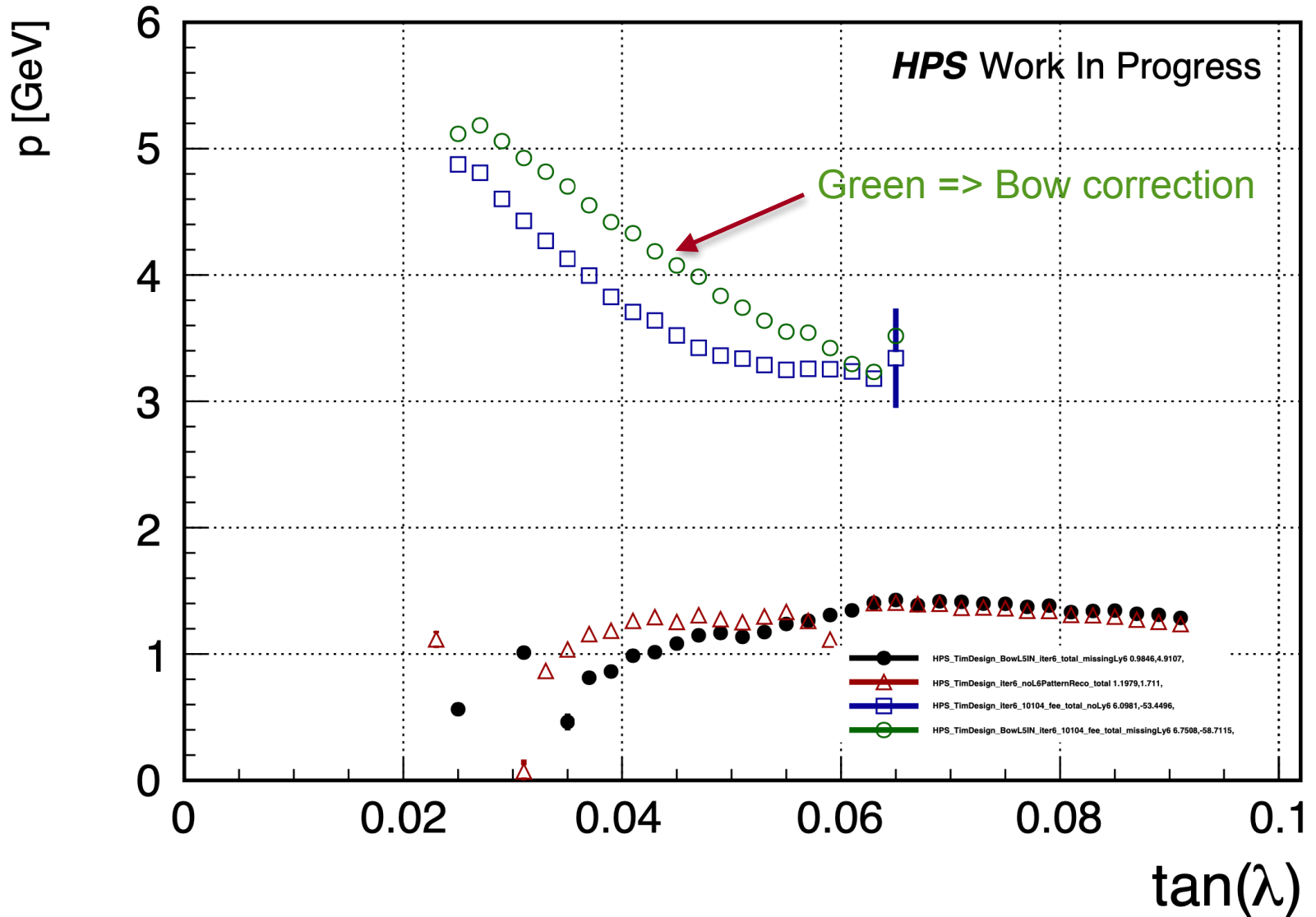
2019 - Vertex distribution



2019 - E/p from tridents

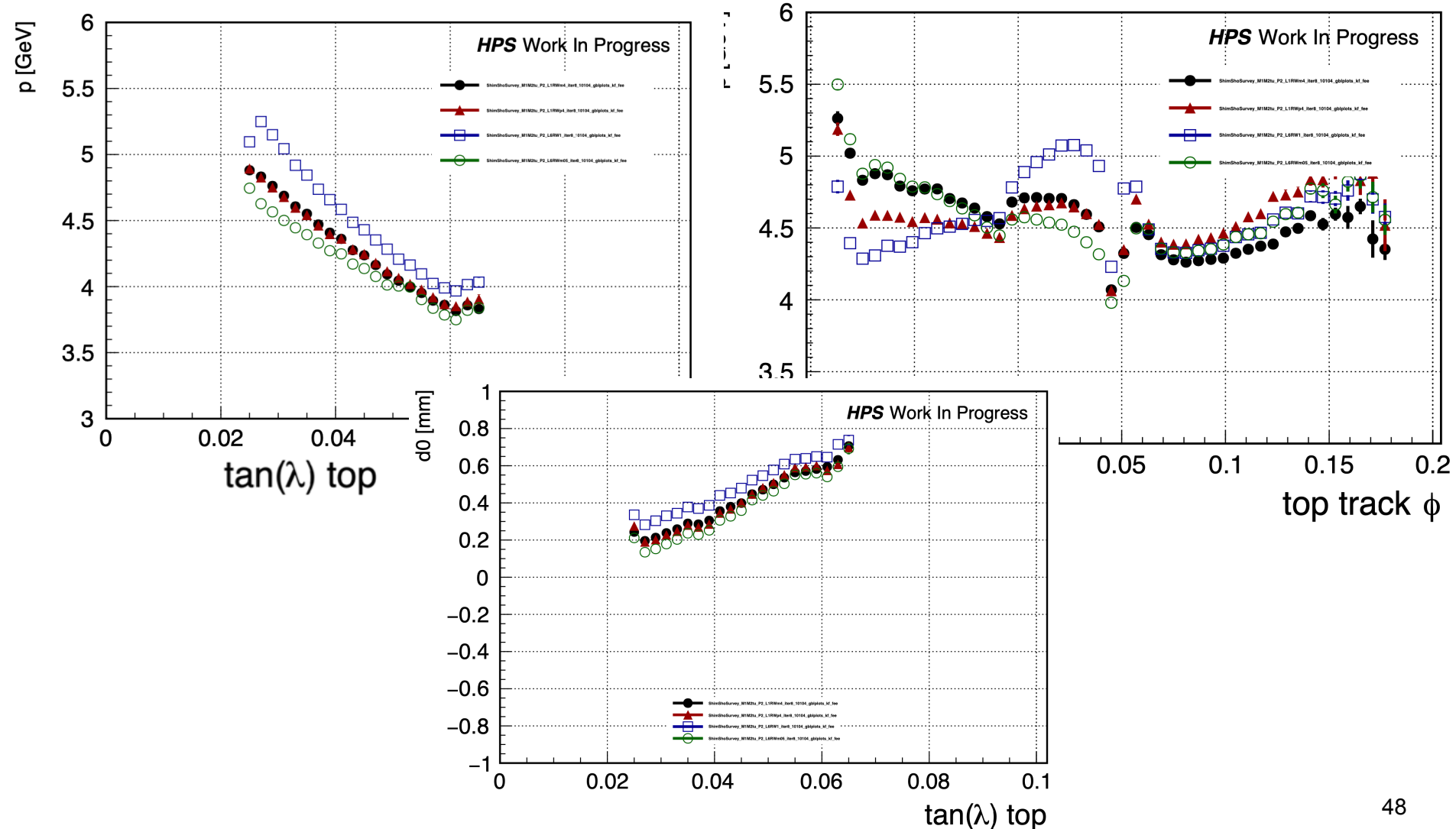


- Inclusive trident sample
- Checked Tracker vs Ecal calibration by checking tracks matched to Ecal clusters



2019 d0/Momentum - Rotations of L1 (4mrad) and L6 (1mrad)

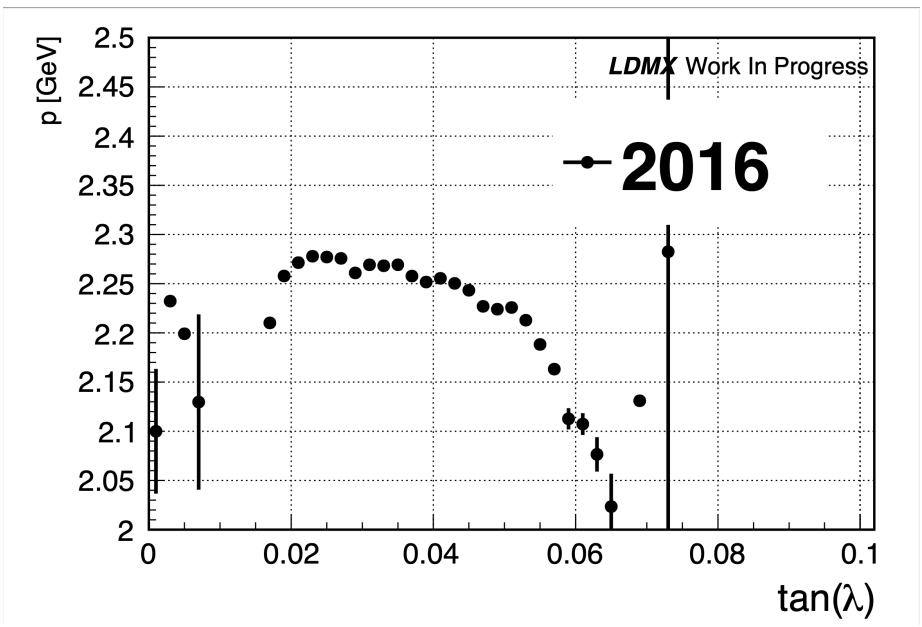
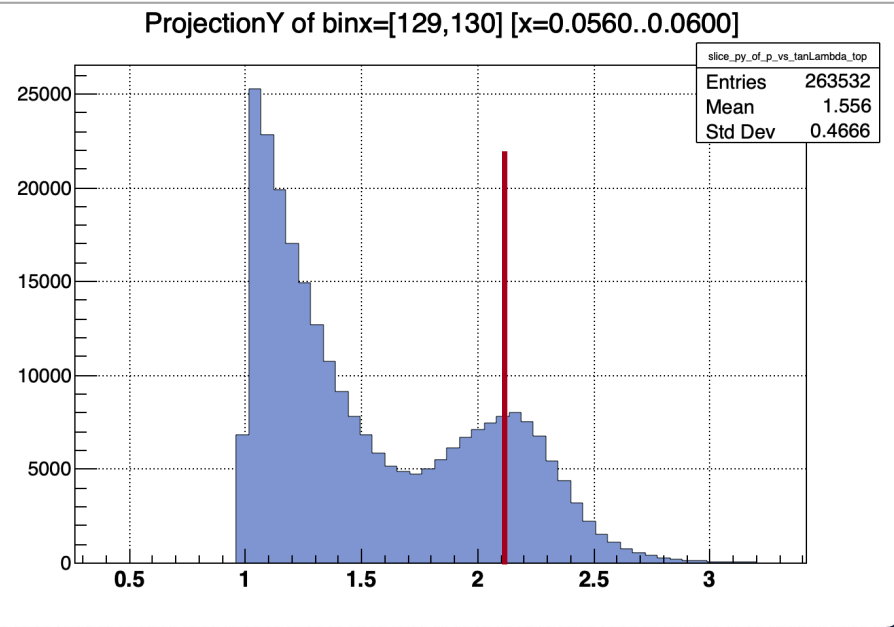
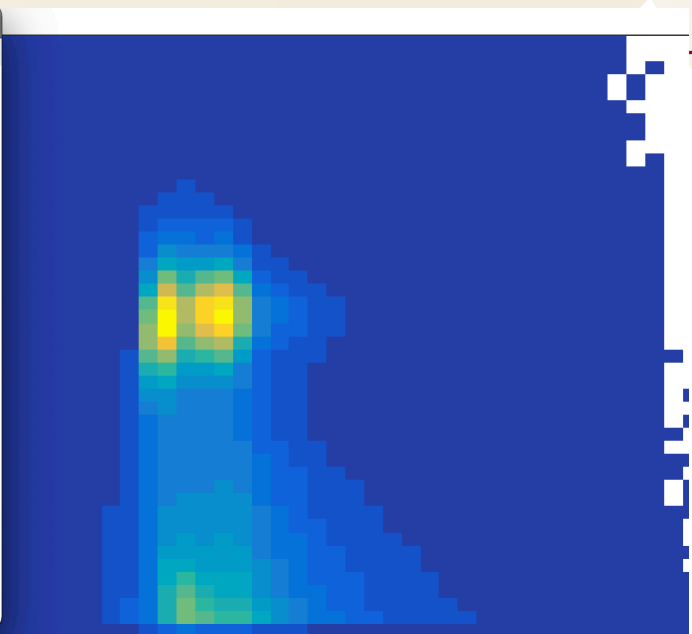
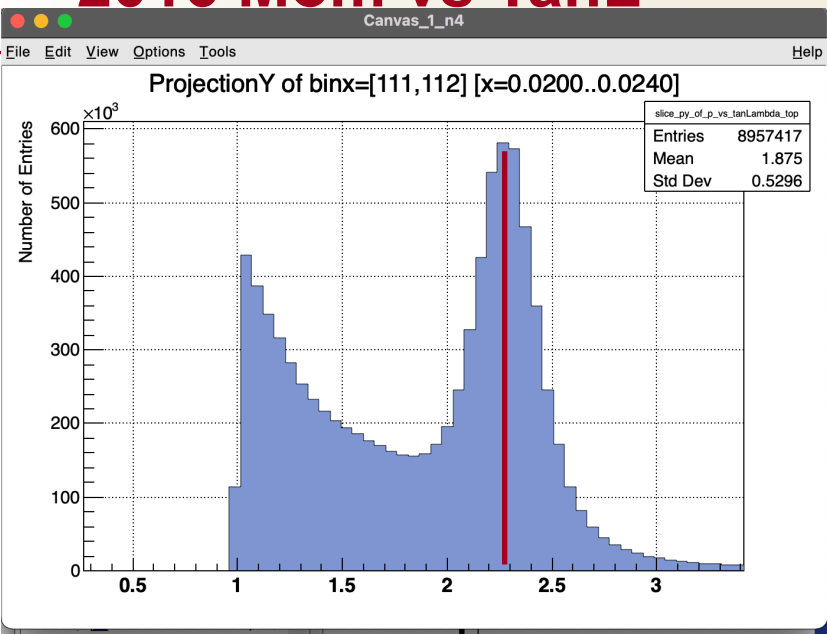
- Starting point is detector on data before any Tz, which presents the slope itself.



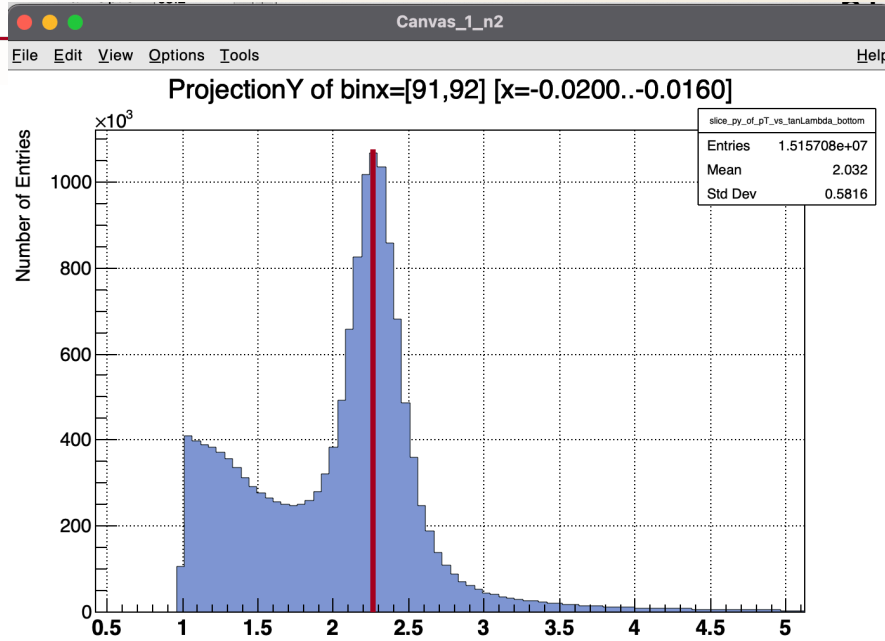
2019 Tz corrections

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```

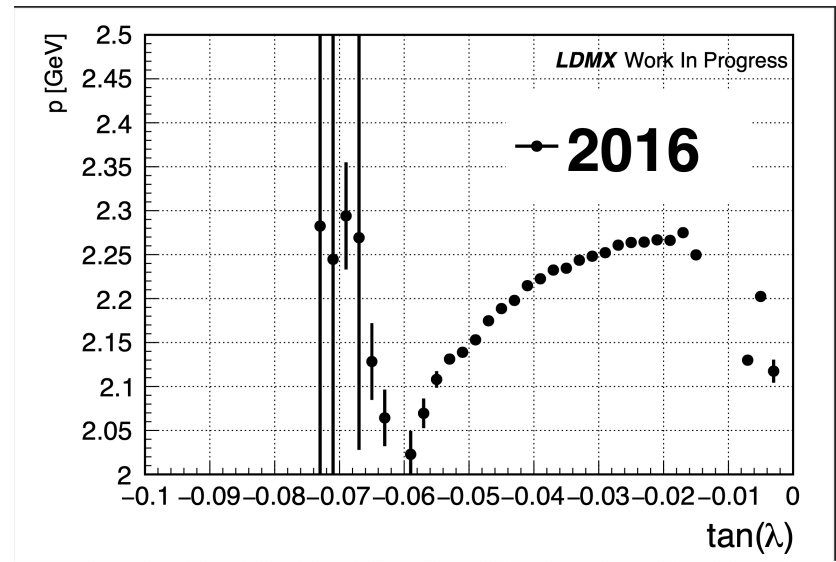
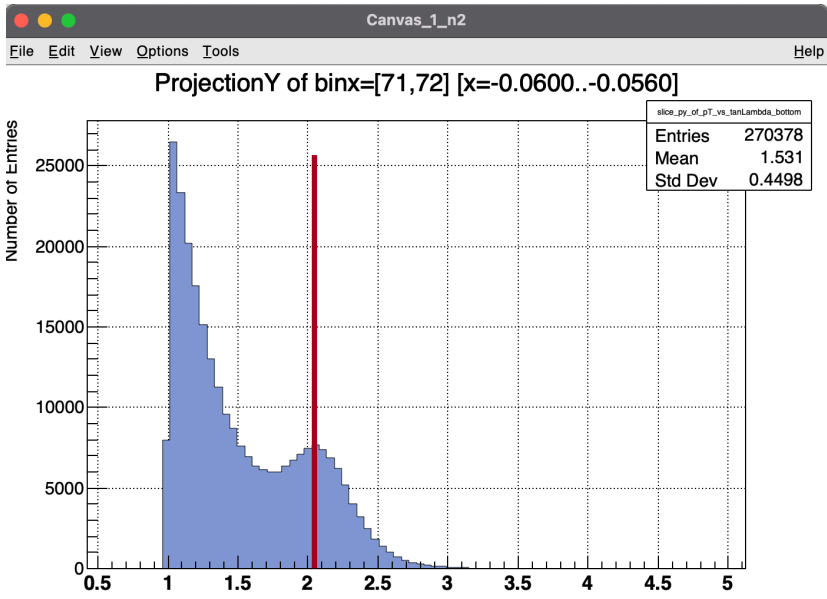
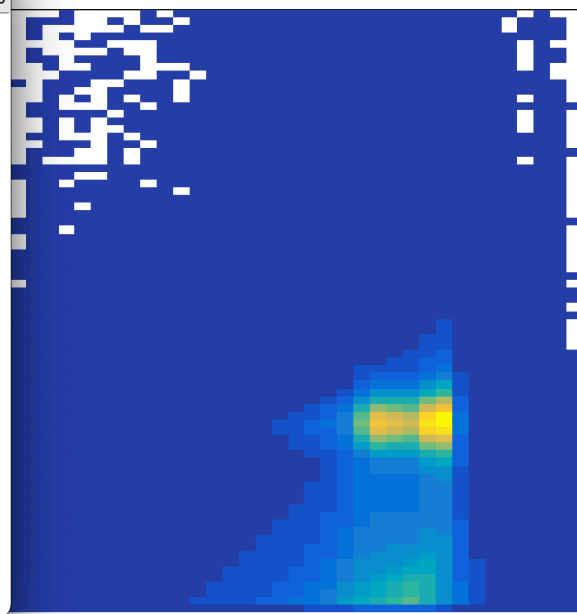
2016 Mom vs TanL



2016 Mom vs TanL



vs_tanLambda_bottom

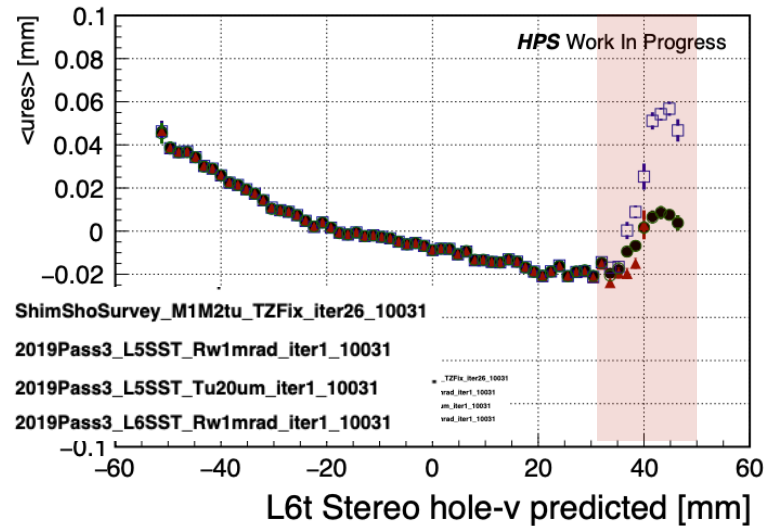
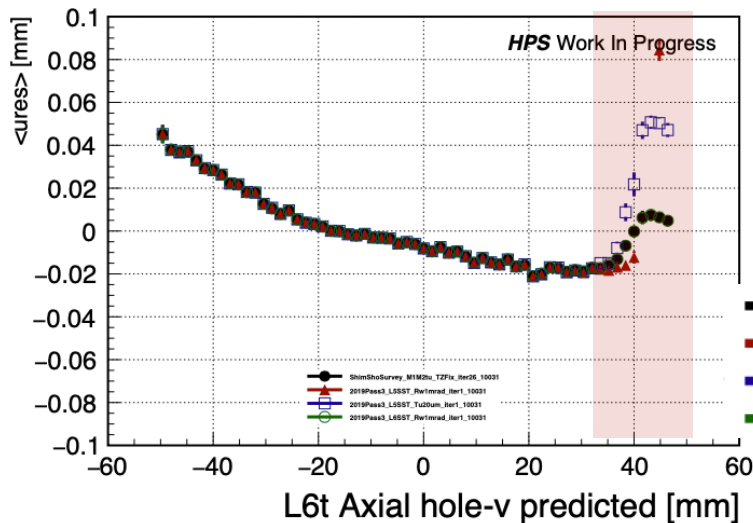


Study of impact of single sensor movements

- Used trig-trig + beam data
 - Removed Ly7Top from 10031 to simulate later detector conditions
- The idea is to study the impact of moving single sensors on
 - Unbiased residuals
 - E/p distributions
- With the aim to understand and correct observed biases in the reconstruction

Step structure in the vs-v hole residuals

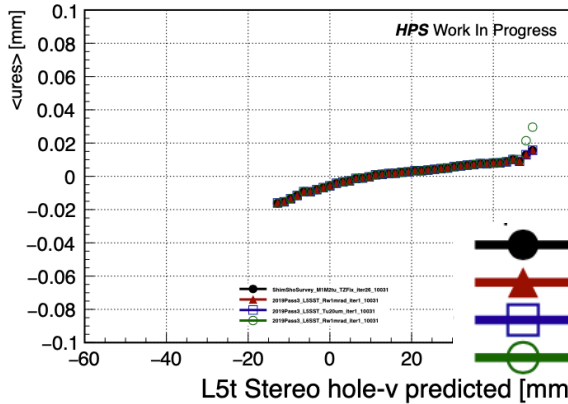
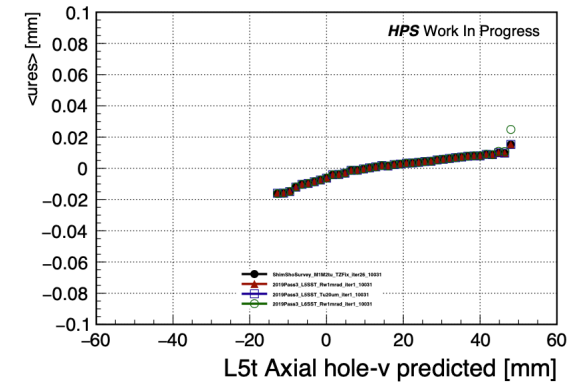
- Black - Current best detector for 2019 Top Volume
- We observe a step structure in the residuals vs v in ly6 in the hole side
see area in red
- Tested 2 movements:
 - Rotation $R_w=1\text{mrad}$ of Ly5 Stereo Slot of 1mrad ==> Kills tracks in that region, no effect outside
 - Translation $T_u=20\mu\text{m}$ of Ly5 Stereo Slot ==> Moves residuals in that region, no effect outside
- **The step in the red region of Ly6 Hole Side can be corrected via T_u of Ly5 Stereo Slot.**



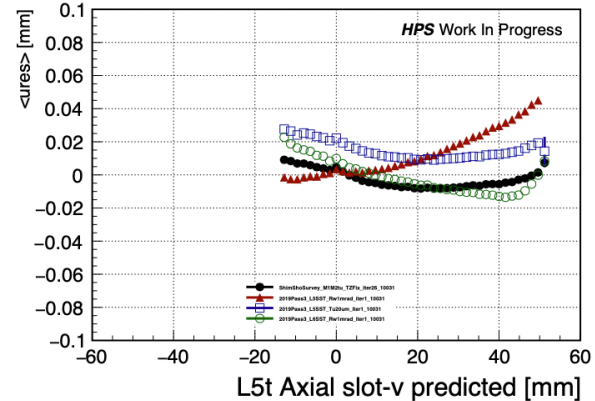
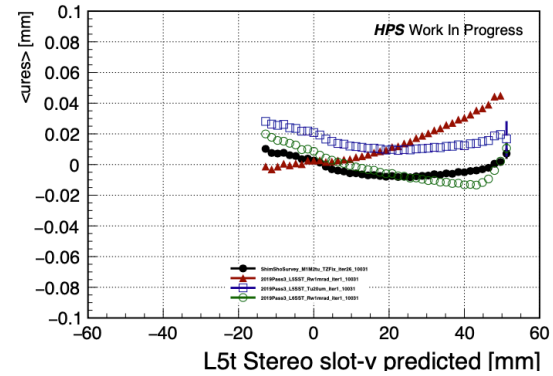
Step structure in the vs-v hole residuals

- Effect on Ly5
 - No effect on Hole side (as expected)

- Effect on Ly5
 - Large effects on Slot side

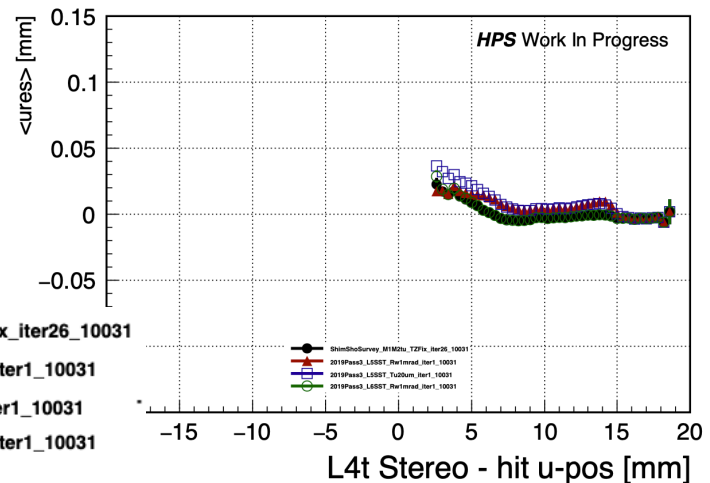
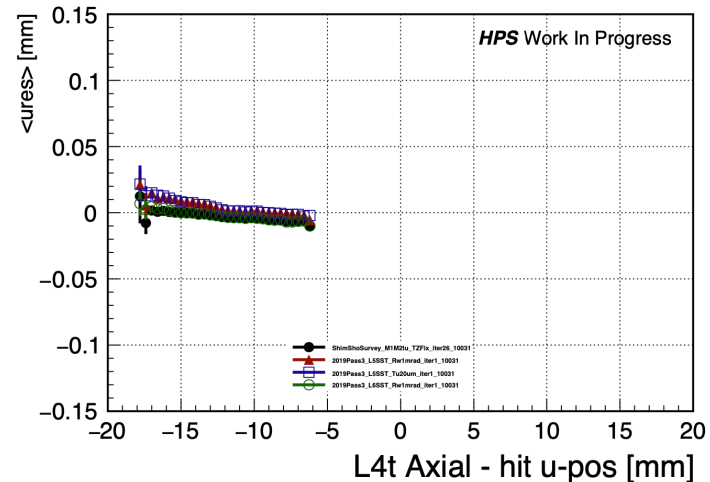
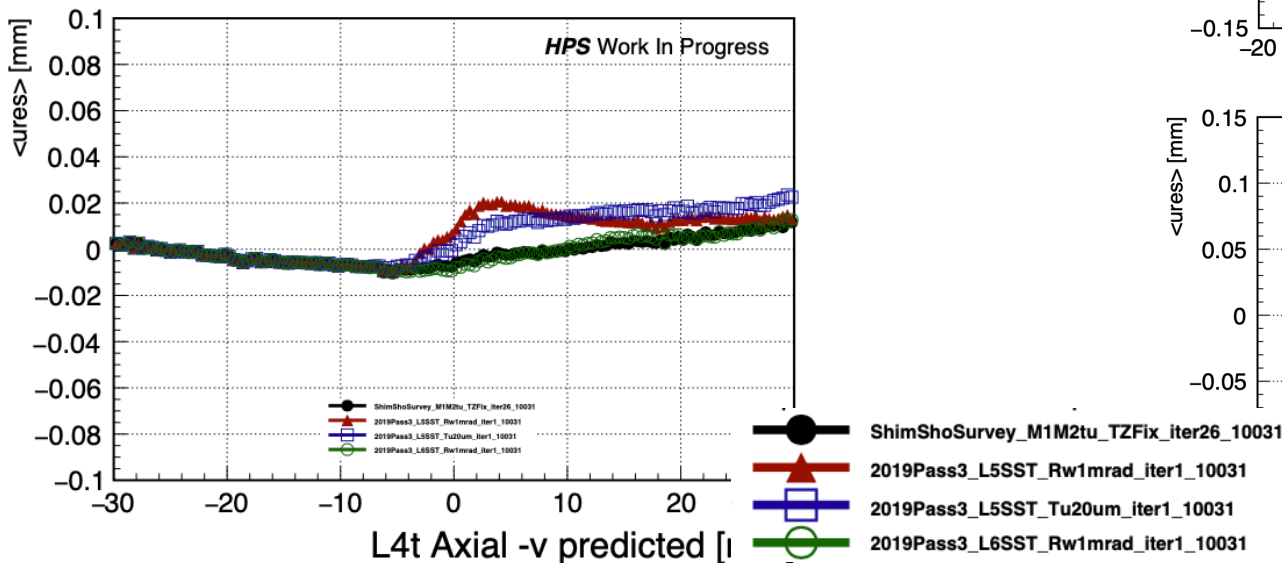


- ShimShoSurvey_M1M2tu_TZFix_iter26_10031
- ▲ 2019Pass3_L5SST_Rw1mrad_iter1_10031
- 2019Pass3_L5SST_Tu20um_iter1_10031
- 2019Pass3_L6SST_Rw1mrad_iter1_10031



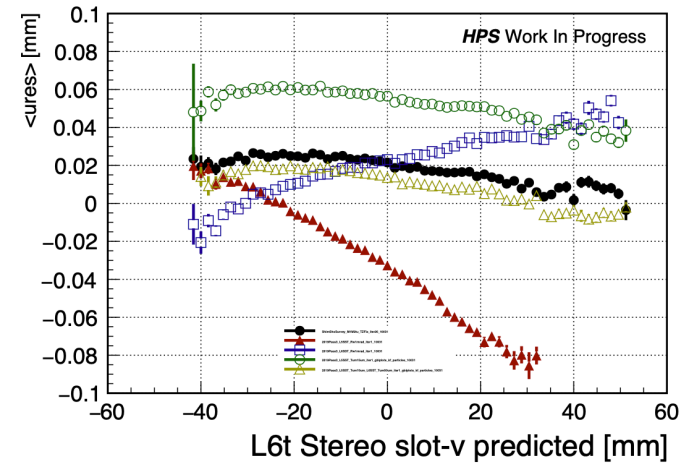
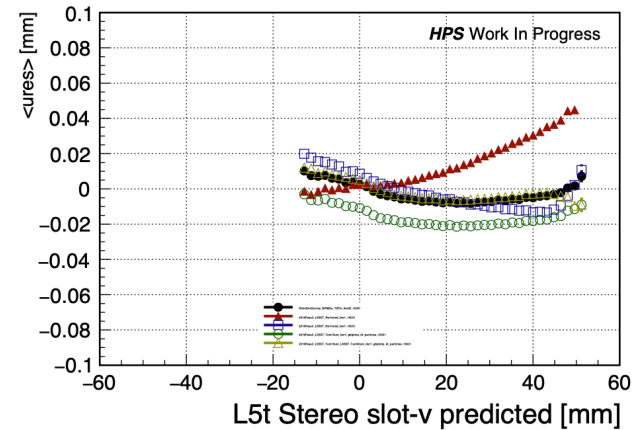
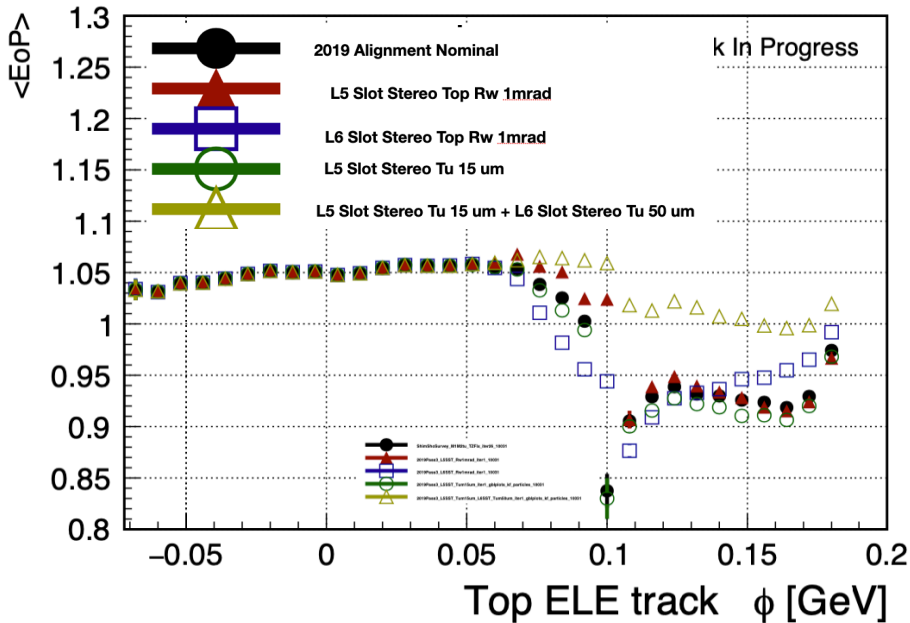
Step structure in the vs-v hole residuals

- Clear effects on Ly4 in both vs v and vs u residuals.
- The vs v Axial and Stereo look the same. The vs u has less effect on the axial and could mimic a Z movement of this sensor.



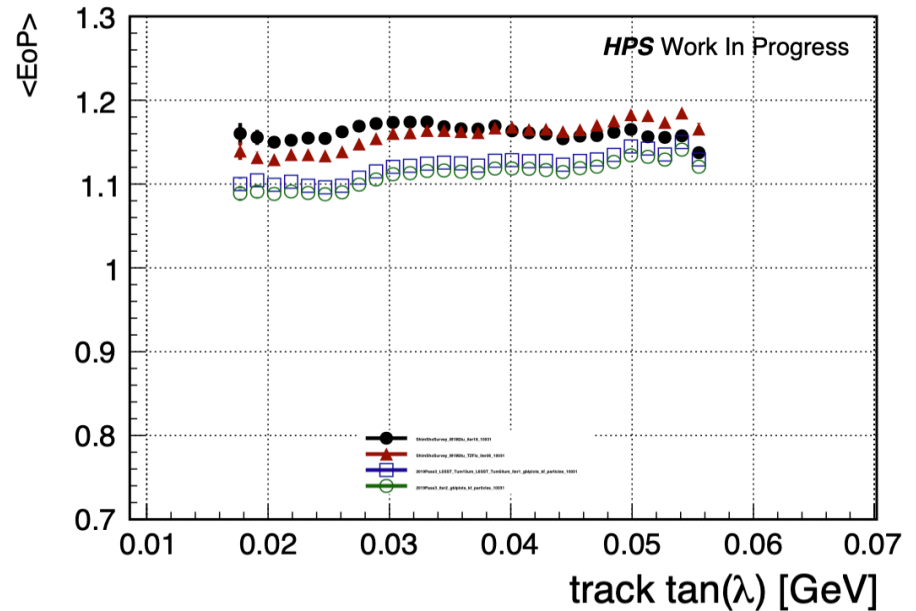
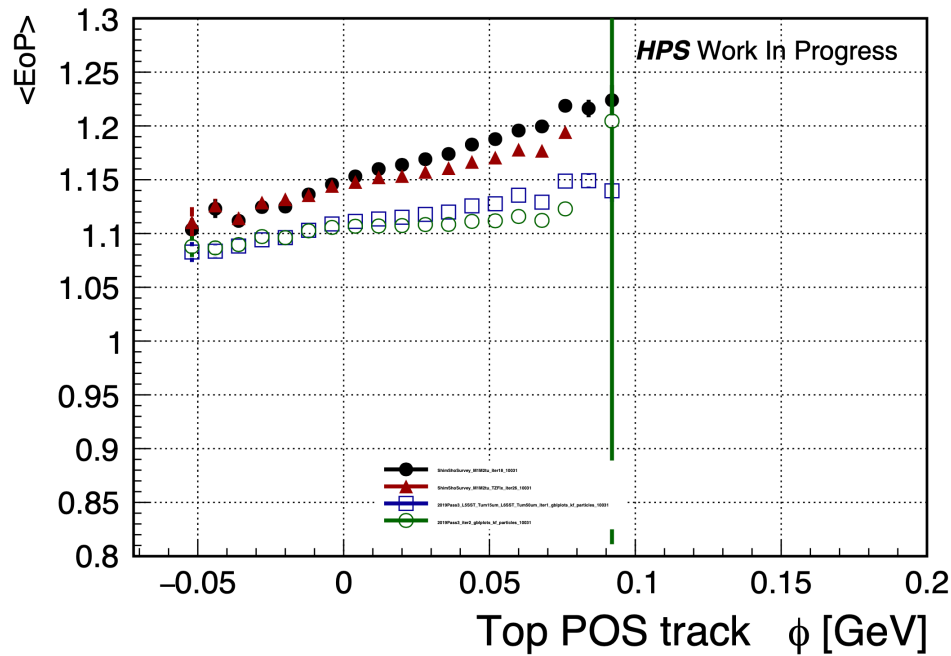
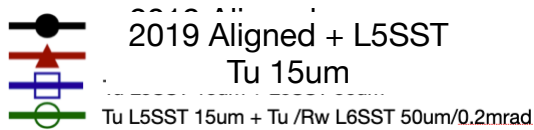
EoP effects of back layers Tu / Rw - ELECTRONS

- Movements of the back slot side have an effect on Electron E/p at high phi values
 - Tu = Flat rise,
Rw = Linear trend
- In a detector where Ly7 is missing:
 - Tu < 0 in Ly5 leads to lower E/p on the high phi region. Flat correction
Rw > 0 in Ly6 creates a trend in large phi with positive slope, .i.e. E/p increases with phi => momentum decreases with phi



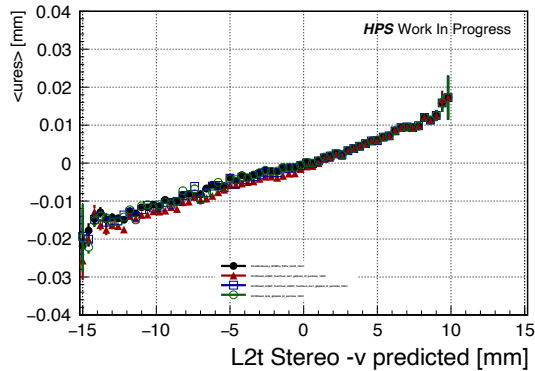
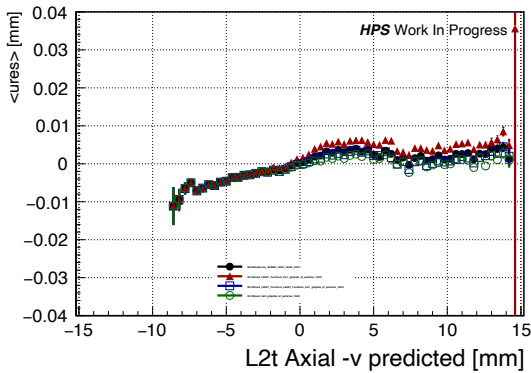
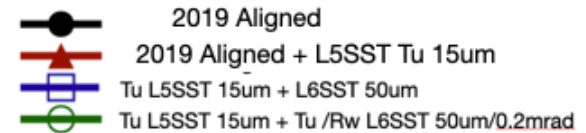
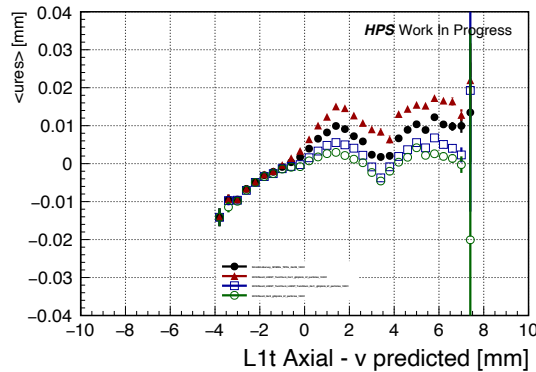
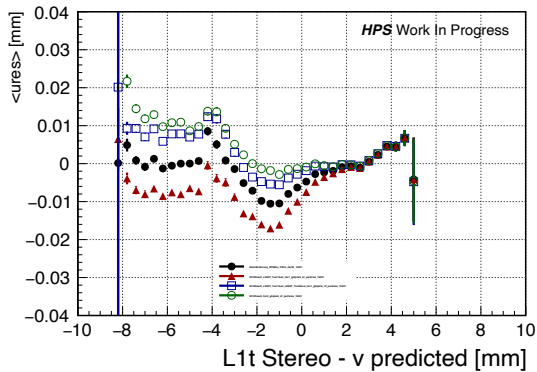
EoP effects of back layers Tu / Rw - POSITRONS

- 15um Correction L5SlotStereo Tu, L6 SlotStereo Tu60um + Rw0.4 mrad



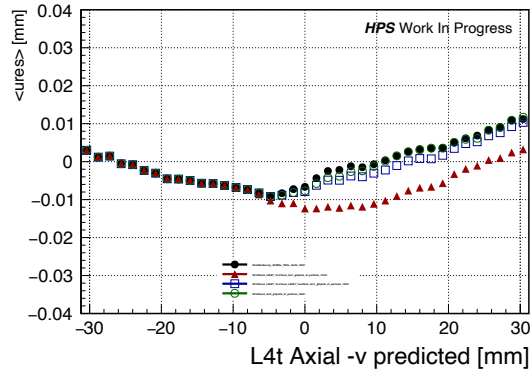
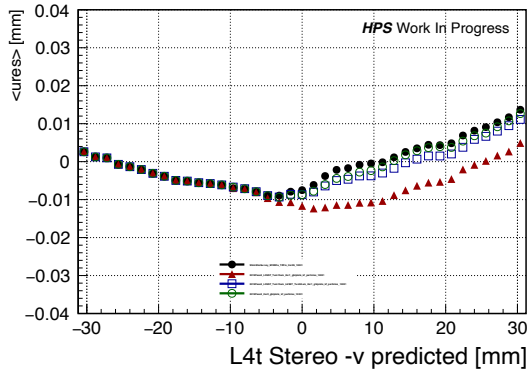
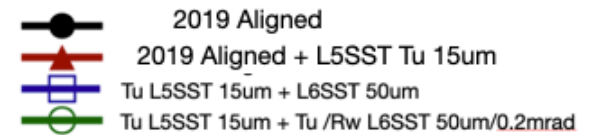
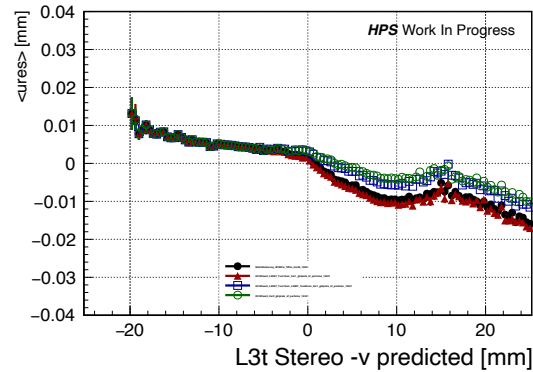
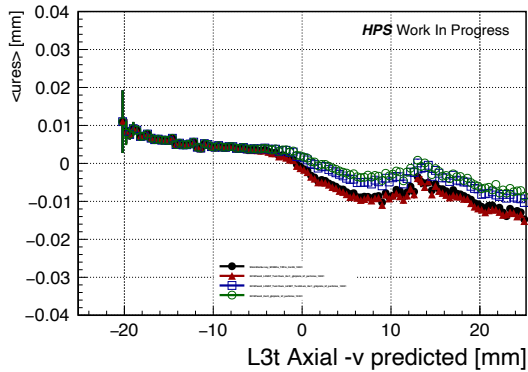
Effects on front of the detector

- 15um Correction L5SlotStereo Tu, L6 SlotStereo Tu60um + Rw0.4 mrad



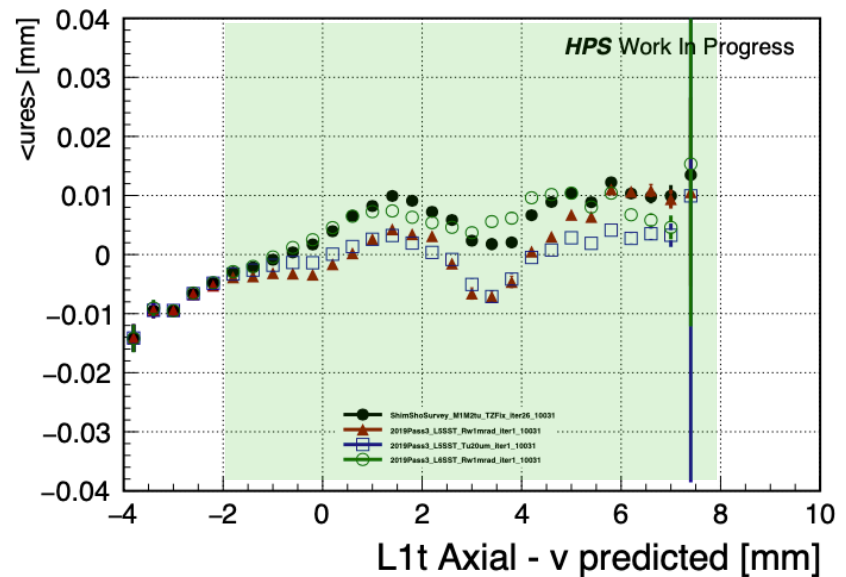
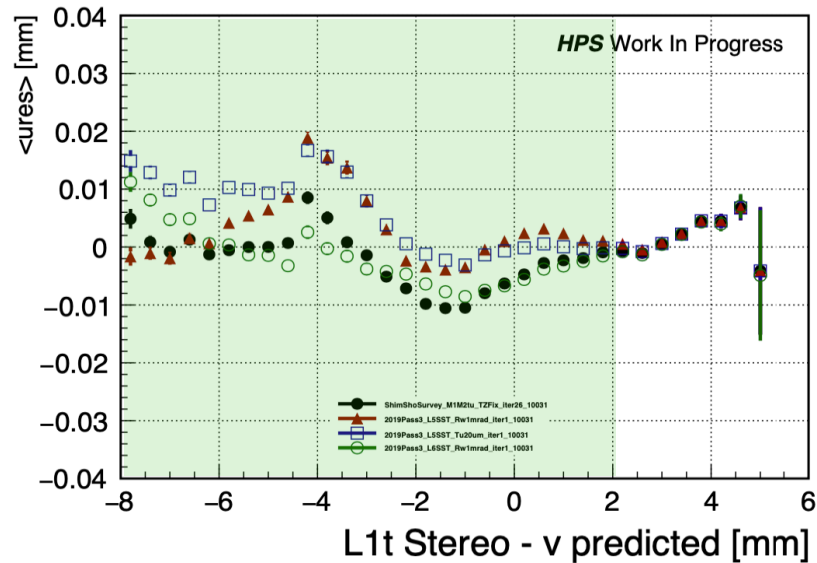
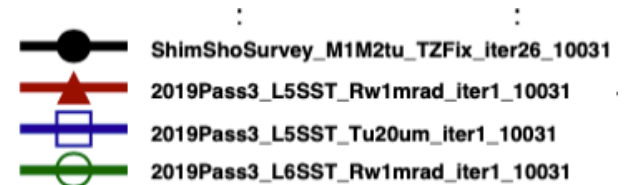
Effects on front of the detector

- 15um Correction L5SlotStereo Tu, L6 SlotStereo Tu60um + Rw0.4 mrad



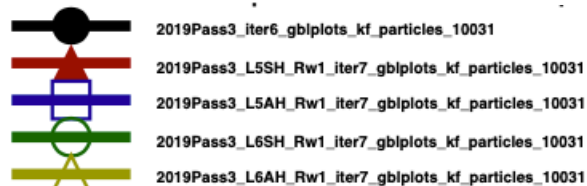
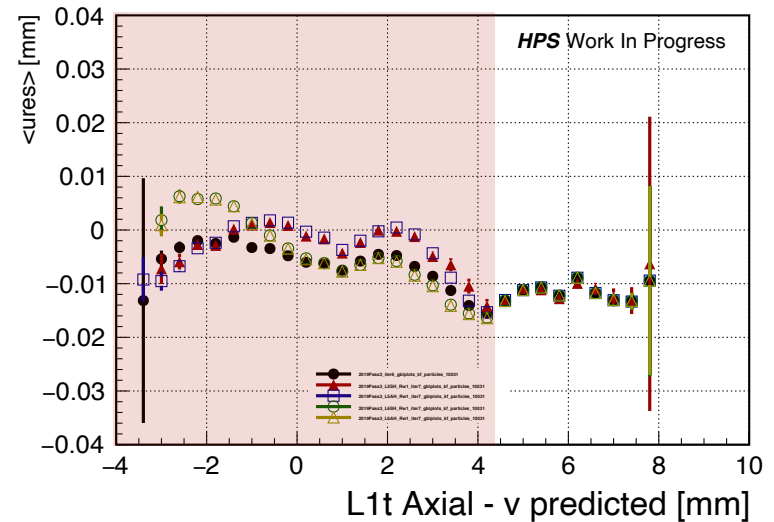
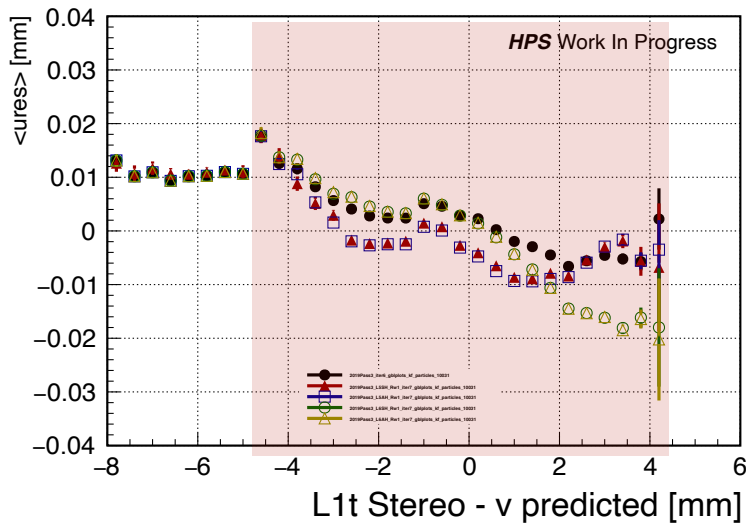
Effects on Ly1

- The structures on the front layer are correlated on the back of detector movements.
- Complicated, piece-wise structures linked to Tu/Rw
- Green area only affected by SLOT side



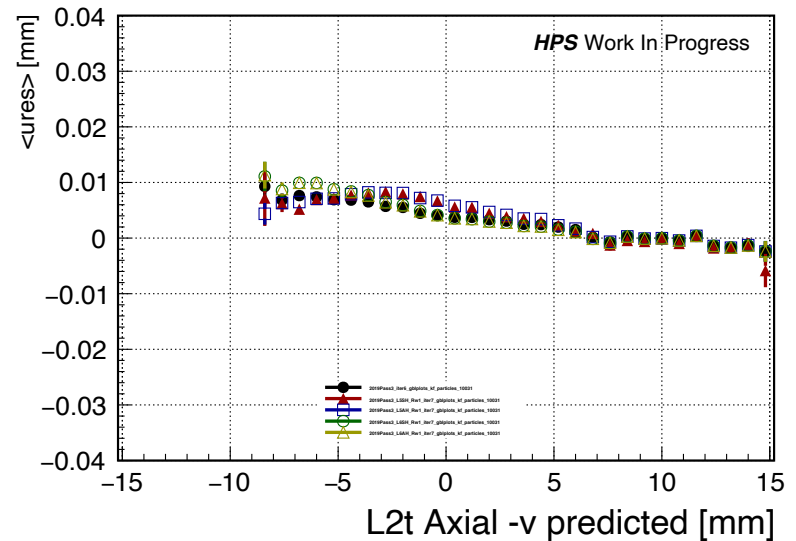
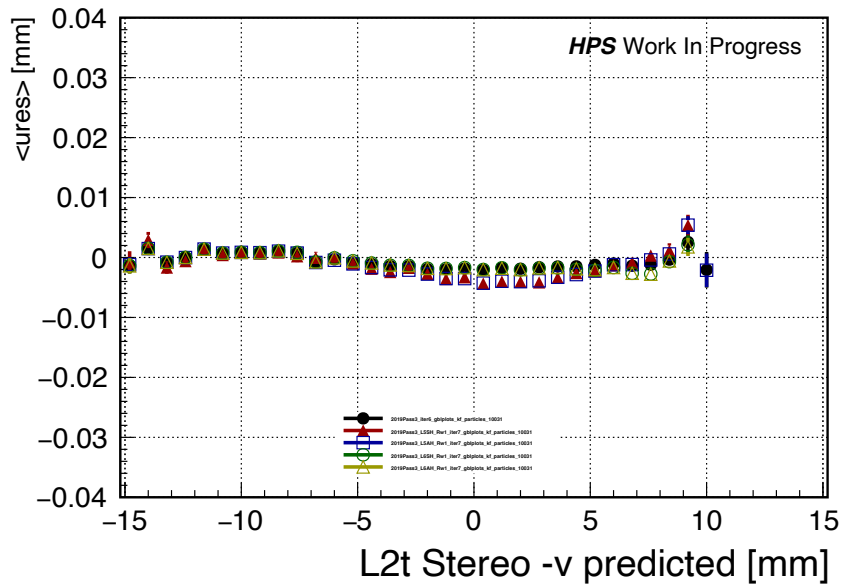
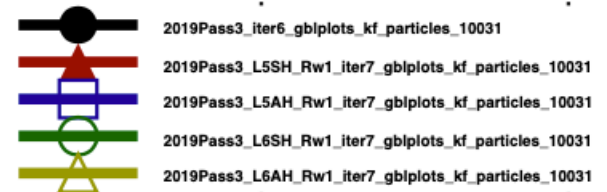
Effects on Ly1

- The structures on the front layer are correlated on the back of detector movements.
- Complicated, piece-wise structures linked to Tu/Rw
- Red area only affected by HOLE side
- Axial-Stereo is degenerate: only worth changing one.



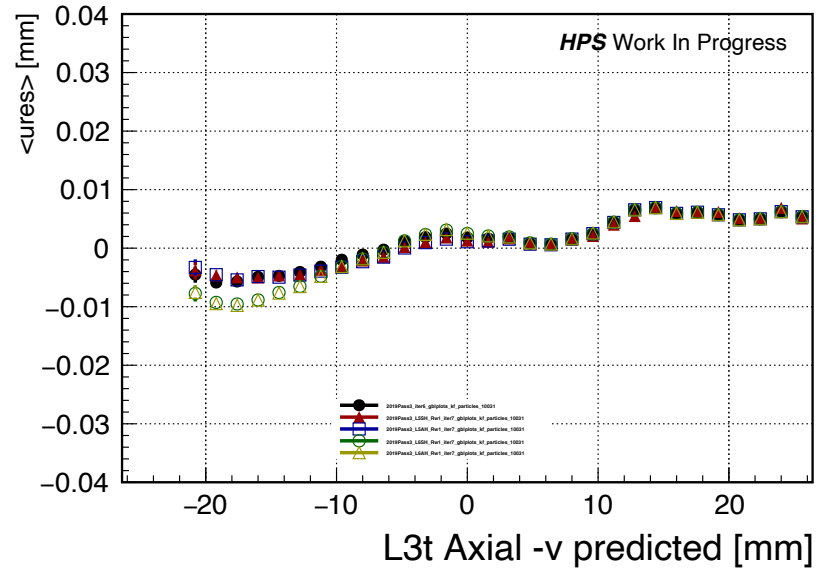
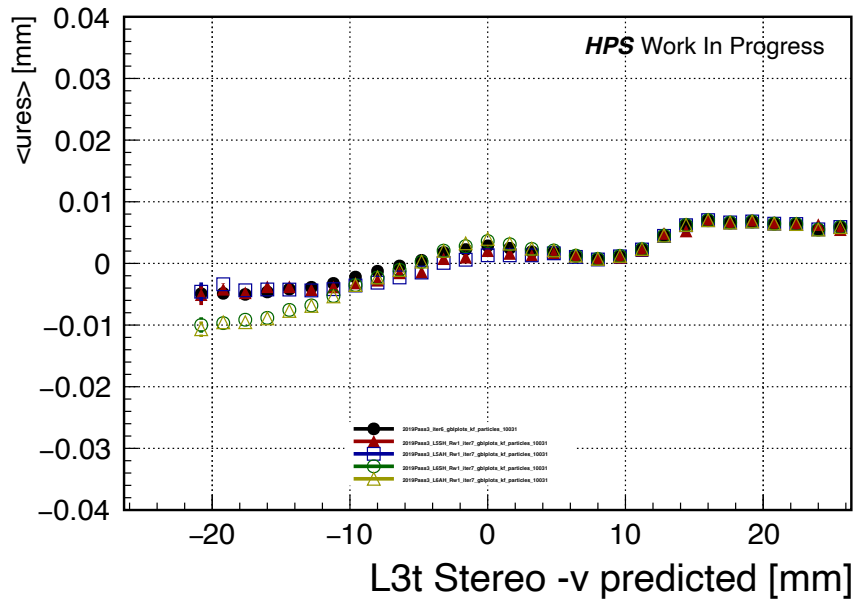
Effects on Ly2

- The structures on the front layer are correlated on the back of detector movements.
- Complicated, piece-wise structures linked to Tu/Rw
- Red area only affected by HOLE side
- Axial-Stereo is degenerate: only worth changing one.



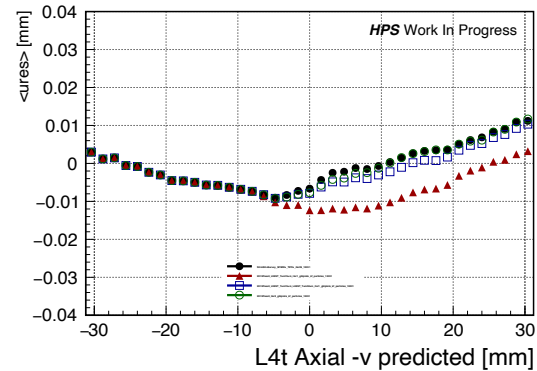
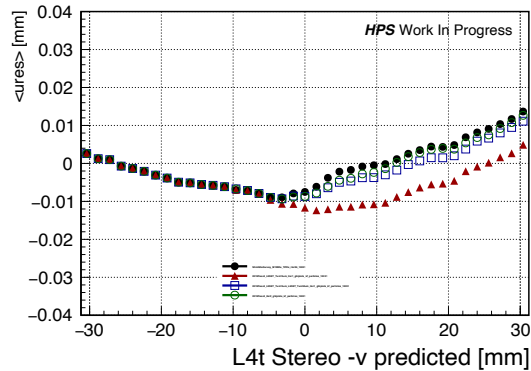
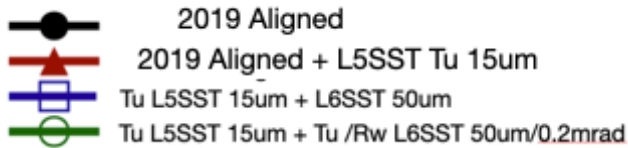
Effects on Ly3

- The structures on the front layer are correlated on the back of detector movements.
- Complicated, piece-wise structures linked to Tu/Rw
- Red area only affected by HOLE side
- Axial-Stereo is degenerate: only worth changing one.



Concentrate on Ly4Top

- We see no effects in the trend in Ly4Top, right side, where the slot stereo L5 is moved
- **These v shapes seems to be strongly linked to L5 Axial rotations for the top volume.**
 - I've tested the effects of aligning the stereo side but that has very small effect on these shapes. I suppose because the axial side kind of "washes" the effect out.
 - Additionally, I've already taken out the relative rotations in the slot side as discussed before between Ly5 and Ly6, so those shouldn't depend on this sensor much
 - Finally, there is no simple movement of Ly4 that can produce this V shape and Ly5 Top Axial is the closest one.



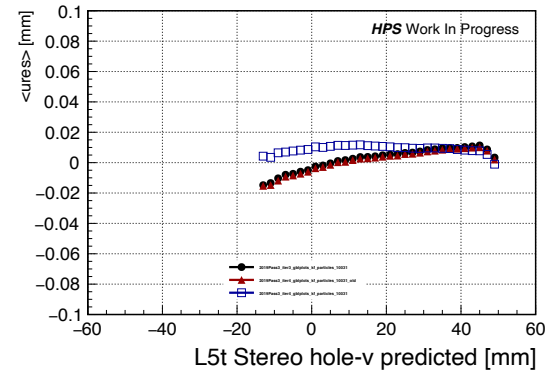
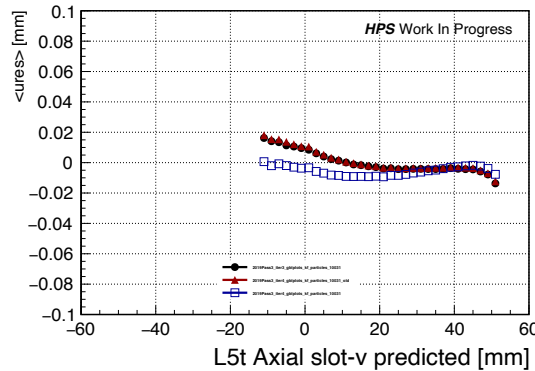
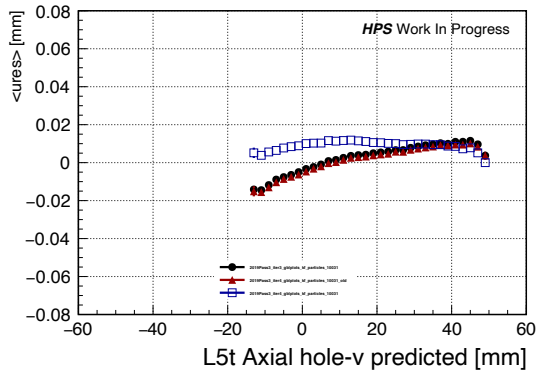
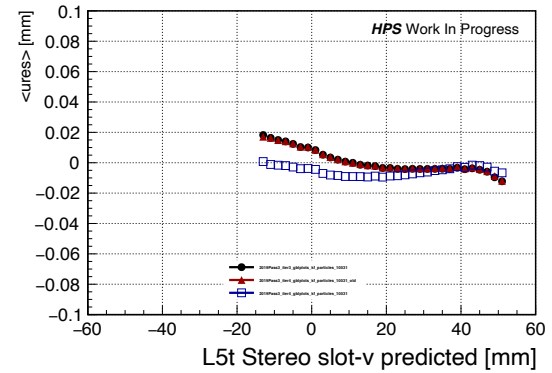
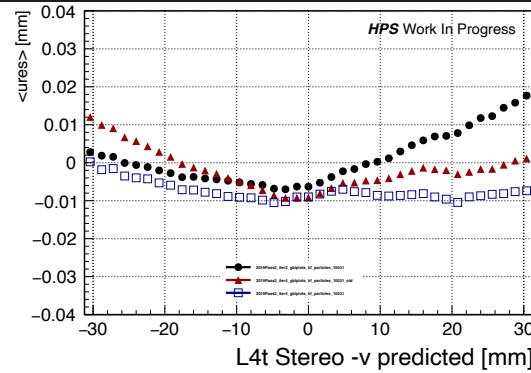
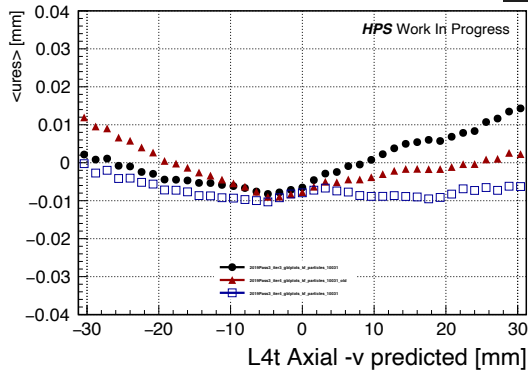
Concentrate on Lv4Top

- Alignment strategy

```

module_L2t_halfmodule_stereo 0.004079 +- 0.000033 11104 (change 0.004079)
module_L3t_halfmodule_axial 0.013253 +- 0.000033 11105 (change 0.013253)
module_L3t_halfmodule_stereo -0.018434 +- 0.000037 11106 (change -0.018434)
module_L5t_halfmodule_axial_hole -0.014911 +- 0.000081 11109 (change -0.014911)
module_L5t_halfmodule_axial_slot 0.015405 +- 0.000063 11111 (change 0.015405)
module_L2t_halfmodule_stereo -0.000098 +- 0.000013 12304 (change -0.000098)
module_L3t_halfmodule_axial -0.000413 +- 0.000005 12305 (change -0.000413)
module_L3t_halfmodule_stereo -0.000369 +- 0.000005 12306 (change -0.000369)
module_L5t_halfmodule_axial_hole 0.000391 +- 0.000003 12309 (change 0.000391)
module_L5t_halfmodule_axial_slot -0.000363 +- 0.000003 12311 (change -0.000363)
    
```

VERY GOOD
FOR L4 AND L5 STRANGE
STRUCTURES!

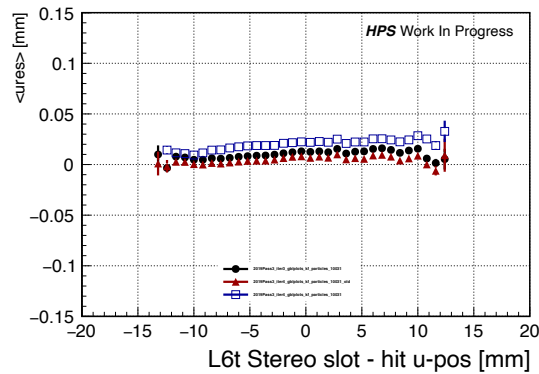
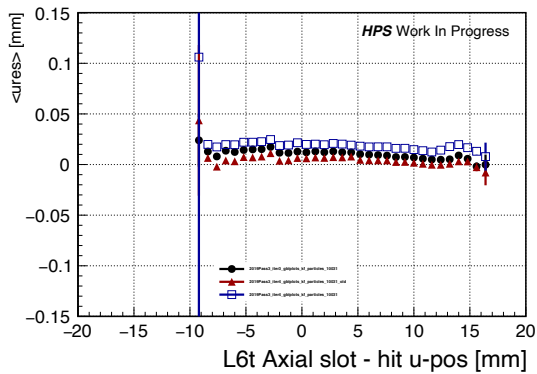
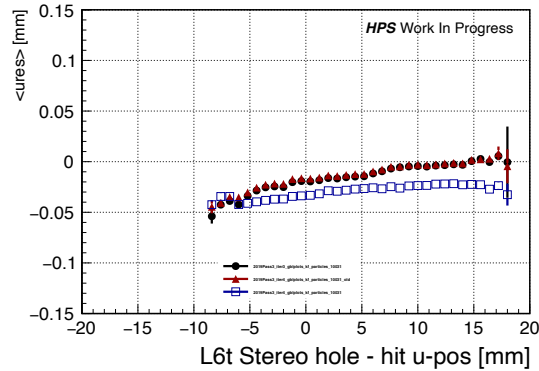
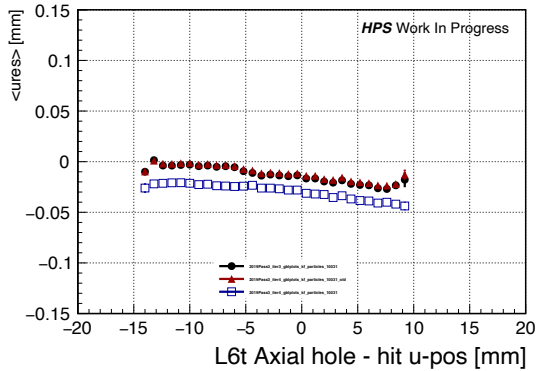


Concentrate on Lv4Top

- Alignment strategy

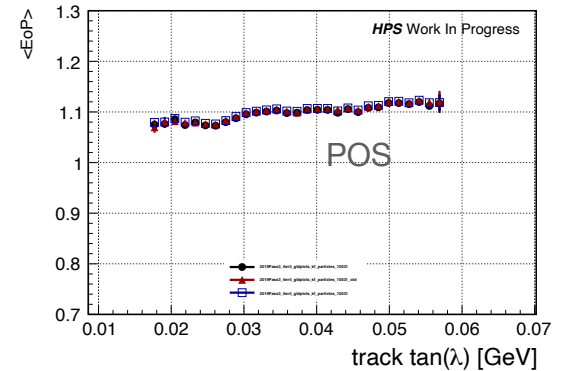
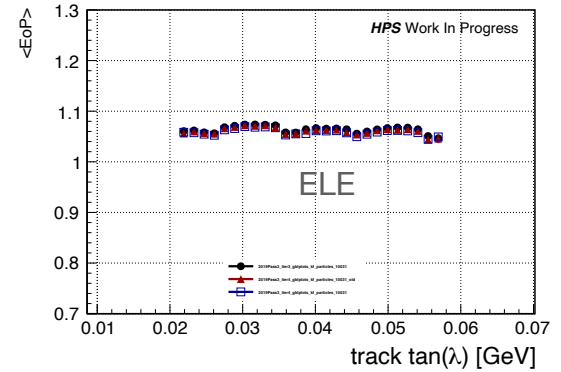
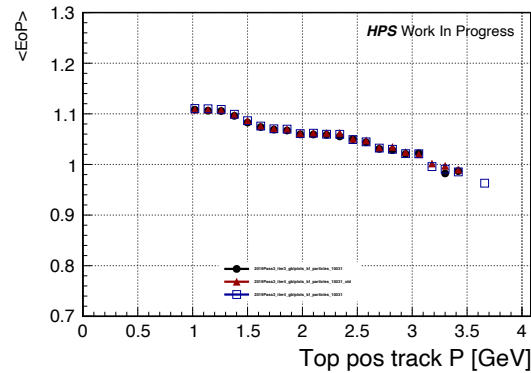
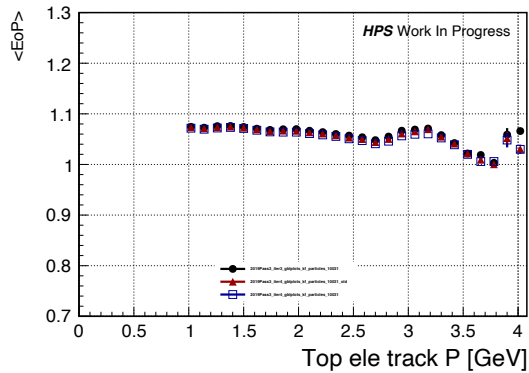
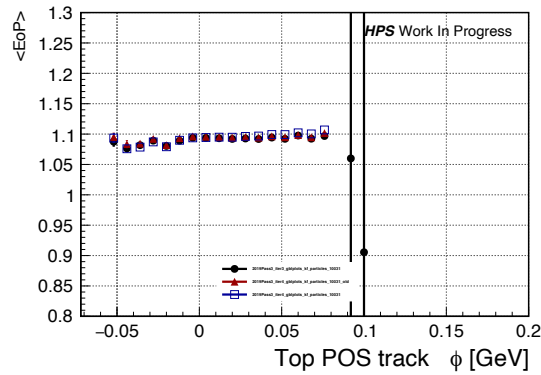
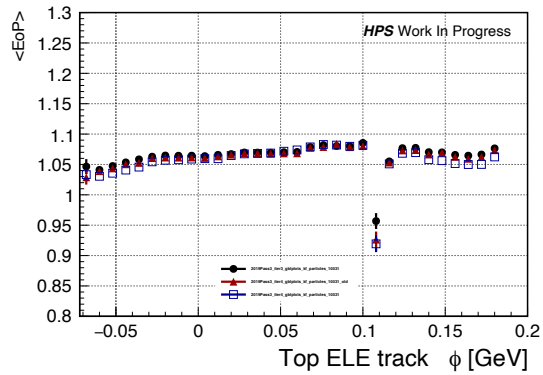
module_L2t_halfmodule_stereo	0.004079	+-	0.000033	11104	(change	0.004079)
module_L3t_halfmodule_axial	0.013253	+-	0.000033	11105	(change	0.013253)
module_L3t_halfmodule_stereo	-0.018434	+-	0.000037	11106	(change	-0.018434)
module_L5t_halfmodule_axial_hole	-0.014911	+-	0.000081	11109	(change	-0.014911)
module_L5t_halfmodule_axial_slot	0.015405	+-	0.000063	11111	(change	0.015405)
module_L2t_halfmodule_stereo	-0.000098	+-	0.000013	12304	(change	-0.000098)
module_L3t_halfmodule_axial	-0.000413	+-	0.000005	12305	(change	-0.000413)
module_L3t_halfmodule_stereo	-0.000369	+-	0.000005	12306	(change	-0.000369)
module_L5t_halfmodule_axial_hole	0.000391	+-	0.000003	12309	(change	0.000391)
module_L5t_halfmodule_axial_slot	-0.000363	+-	0.000003	12311	(change	-0.000363)

VERY GOOD
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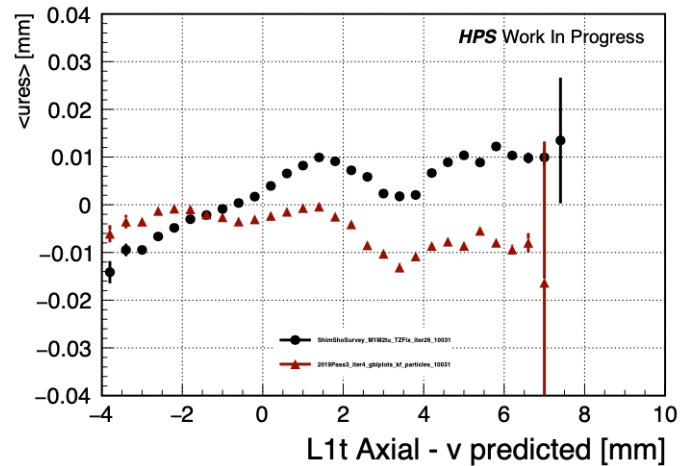
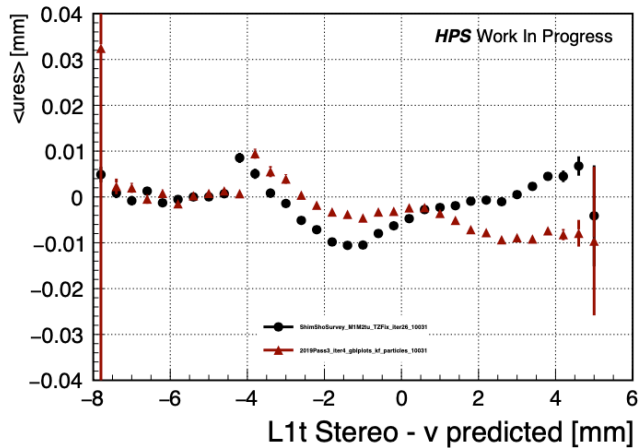
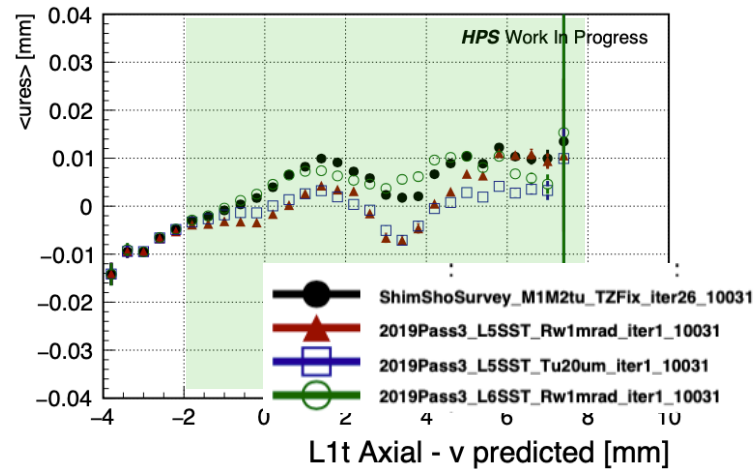
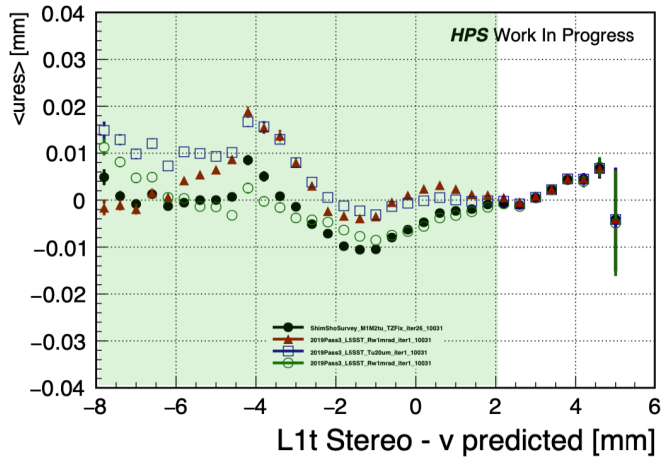
Concentrate on Ly4Top

- Alignment strategy:



Basically no effect on momentum distributions across parameters

Let's go back to the front and check the effects



EoP electron trends as function of Ly6S Rw

- Check the effect of plain Rw