

Towards Smart Detectors and Experiments: ML in Nuclear Physics

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AI/ML at JLab

Multiple groups are working to implement AI/ML at each step of NP workflows.



For some projects, EPSCI collaborates with the Data Science Department and Physics Division

EPSCI at JLab

Experimental Physics Software and Computing Infrastructure

Mission Statement: Identify, develop, implement, and maintain software and computing technologies in support of the Jefferson Lab Science Program



Test relocation of computing workflow from resources close to the experiment to remote data center for near real time data quality, calibration, and/or alignment.

Al for Experimental

a detector in near real time

Framework for training and

Quality Monitoring

managing AI for real time Data

Dynamically control and calibrate

Controls

Hydra

JIRIAF

EJFAT

Program FPGA for efficient network data routing of UDP packets, enabling low-latency, balanced distribution to compute farm endpoints.

PHASM

Al-based surrogate models of scientific code

AIOP

Control and optimized polarization for polarized targets and photon beams

Streaming DAQ

Developing the next generation of DAQ for Nuclear Physics

Experiment operations



Data quality monitoring: "On Shift" at JLab

Shifts are required as part of your membership to experimental hall collaboration



Responsible for

- DAQ operation
- Logging and responding to alarms
- Data quality monitoring
- Filling out BTA
- and much more

Online monitoring is **tedious**.

Varying levels of expertise

Inconsistent monitoring

Multiple plots per detector system

Too many plots to look at



Approximate **number of individual histograms per experiment per run**, monitored by the shift crew for each experimental hall.

What makes these images bad?

It's hard to tell right away if an image is bad!

9.0 8.0 7.0 6.0 5.0

3.0

2.0 1.0

10.0 9.0

8.0 7.0

9 6.0

5.0 4.0 3.0

> 2.0 1.0

DIRC, TDC North (Upper) Pixel Occupancy: LED trigger

DIRC, TDC North (Upper) Pixel Occupancy: Non-LED triggers



fADC TDC 12000 10000 8000 6000 4000 2000 25 30 Channel Number BST Layer 6 **BST Laver** BST Laver 100 150 200 250 **Strip** BST Layer 1 100 150 200 250 **Strip** BST Layer 5 50 50 100 150 **Strip** BST Layer 3 200 250 50 100 150 200 250 Strip 50 100 150 200 250 50 100 150 200 Strip 250 50 Strip

ST fADC250 DigiHit Occupancy

Can we utilize computer vision for data quality monitoring?

Thomas Britton's idea as a post doc in GlueX



MaxPool Concat Dropout

Google's Inception V3

Why InceptionV3? It was available and had good performance on standard image data sets.

HYDRA

An extensible framework for training, managing, and evaluating AI for real time data quality monitoring.



1/ MySQL back end

Unique plot identifiers, model training parameters, classifications, user permissions, labels, and more are all stored in MySQL database.

Showing 80 / 80 images	Last Update:	4.00 (s) ago		
FTOF_tdcOccupancy Run Number: 18704 2023-11-05 19:51:11 NoData @ 72.97% confidence	FTOF_adcOccupancy Run Number: 18704 2023-11-05 19:51:10 Good @ 99.57% confidence	Image: Constraint of the second sec	CTOF_tdc Run Number: 18704 2023-11-05 19:50:50 Good @ 99.73% confidence	CTOF_adc Run Number: 18704 2023-11-05 19:50:49 Good @ 99.94% confidence
		TimeJitter_phase	HEL_signals	
RICH_occupancy2d	Run Number: 18704	Run Number: 18704	Run Number: 18704	Run Number: 18704
Run Number: 18704	2023-11-05 19:37:36	2023-11-05 19:47:09	2023-11-05 19:47:08	2023-11-05 17:51:13
2023-11-05 19:51:29	Good @ 88.66% confidence	Good @ 99.91% confidence	Good @ 99.99% confidence	Good @ 99.88% confidence
Good @ 99.82% confidence				

2/ Web based front end

Web based front end for labeling, monitoring, and model validation.

EPSCI develops and maintains Hydra in all Halls in collaboration with Users

HYDRA: Back End

• Hydra system

Written in python Images move through Hydra via OMQ Can utilize multiple predicts if necessary

• MySQL database

Supplies information needed for UI Stores all relevant information for every image it sees



HYDRA: Front End

FTC

Run



Data Labeler

Efficiently label hundreds (thousands) ofimages

Library

Contains enhanced confusion matrix, thresholds, active model designations 😥 H Y D R A 18704 showing 80 / 80 images FTOF_tdcOccupancy Run Number: 18704



Run

See predictions in real time

HYDRA close Contact

I last received images from Run: with a current, average processing Feeder Feeder is responsible for getting images, resizing them, and moving them to the appropriate directory such that they can be fed to the appropriate model



Status

Monitor heartbeats for back end processes and image processing time

eneral / HallD_Hydra ☆ 🧠 BCAL_occupancy ST_occupancy



Grafana

Dashboard displays all predictions over time



HYDRA close Contact

19600

19599

ECAL

HEL

FTOF

HTCC





Log

Display concerning plots sorted by detector from previous day

Can the model tell us what about the image is bad?

Sometimes! With Gradient-Weighted Class Activation Maps





Original image

Image + GradCAM heatmap

The generated heat maps may not always coincide with what we expect.

Hydra Run + GradCAM

What you might see in your counting house :)



Dynamic Ordering \swarrow

'Bad' images are moved to the top.



Where is Hydra looking when it makes its prediction?

Optional overlay*

Transferable skills with HYDRA

sometimes it's nice to take a break from ROOT histograms ;)

• System written entirely in python

Tensorflow, pandas, SciKit Learn, etc

Web based front end

Javascript, HTML, CSS

 MySQL database used for back end PHP, SQL



There is Hydra related service work in Hall B for those interested.

Experiment operations



Offline calibrations

Iterative and time consuming



Time scale for calibrations is on the order of months, increasing the time between data taking and publication.

GlueX Central Drift Chamber

Used to detect and track charged particles with momenta > 0.25 GeV/c

Detector specs

1.5 m long x 1.2 m diameter cylindrical, straw tube chamber
3522 anode wires traditionally held at 2125 V
50:50 Ar/CO2 gas mixture

• Two main calibrations:

Chamber gain and drift time to drift distance Affects PID selection in analysis via dE/dx



Standard operation

HV is set to 2125 V

Gain fluctuates *mostly* with atmospheric pressure

Can we train a model to predict the gain correction factor?



The gas gain fluctuates during data taking.

Challenges

There's a lot of them!

Offline vs Online Calibrations

- 1. Safety constraints
- 2. Control policies
- 3. Trustworthiness
- 4. There's always a bug we didn't account for

User Interface/ Experience

- 1. Interpretable UI for shift takers
- 2. Easy control ON/OFF button
- 3. Physics based evaluation metric

Data Science

- 1. Quick training and inference time
- 2. Readily available input features
- 3. Robustness to out-ofdomain inferences
- 4. Uncertainty Quantification

What features should we include?

somewhat determined by calculating Shapley values

• The Kitchen Sink

Every possible input feature obtained from reconstruction, EPICS, other detectors, etc

• Input features that are readily available

fetched from EPICS archive

 Input features that are closely related to the CDC In hindsight, probably the most obvious approach

Interpretability

Shapley Values

Lloyd Shapley, Nobel Prize in Economics 2012

How does an individual input feature contribute to a prediction?

Based on 'fairness' properties from Game Theory Model agnostic, but can be slow to evaluate



A) EXPLAINED RISK OF HYPOXEMIA IN THE NEXT 5 MINUTES DURING A SURGICAL PROCEDURE. B) EXPLAINED RISK EVOLVING OVER TIME.

Model Performance

Metric: Mean Absolute Percent Error

Used data from 2018 and 2020 run periods

	# Features	MAPE	MAX PE
Linear regression	11	1.3	19.1
MLP- 7 layers	122	1.8	11.4
GPR	5	1.5	9.1
RF	82	1.7	18.5
XGBoost corr > 0.2	82	1.44	11.8

Gaussian Processes

Supervised learning method used to solve regression and probabilistic classification problems

Suited for small datasets

~430 training runs, 106 testing Existing calibrations used as target values

Provide uncertainty quantification

GPs give mean and standard deviation of the output when predicting

• Fast training and inference

Inference is obtained in ~3 ms



Online Calibration and Control

ML system to calibrate and control the GlueX Central Drift Chamber

Stabilize the response of the detector during the experiment

Successful collaboration of physicists and data scientists!



Control Policies

As they are now, not an exhaustive list

Defined range of allowed HV settings

Determined by detector expert

• High Uncertainty

Determine closest point to region of certainty, use that HV setting OR

Revert to 2125 V and take more data

"Trusting humans"

If roboCDC detects a HV setting outside of our allowed range, we do nothing and assume there is something else going on (e.g., high current tests)



Results and Current Status

The CDC HV is set run-by-run based on the GP predicted gain correction factor.



Initial Cosmics test, 2021

Orange points indicate the gain correction factor using a **fixed** HV. Blue points indicate the gain correction factor while using the **tuned** HV setting.



Primex-Eta Run Period, 2022-2023

Orange indicates tuned HV depending on environmental conditions. **Blue** indicates fixed HV.

The gray points are the ratio of atmospheric pressure and gas temperature. The horizontal lines indicate our error tolerance as determined by the detector expert.



Data Science Pipeline

