

Monte Carlo Methods for Detector Simulation

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based on slides from Makoto Asai (Jefferson Lab)

Outline

- History and applications of Monte Carlo methods
- Monte Carlo basics
- Examples of Monte Carlo particle transport
- Biasing - speeding thing up

History

- Fermi (1930): used random sampling to study neutron moderation
- Ulam and von Neuman (1940s): simulation for weapons development (coined the term “Monte Carlo”)
- Metropolis (1948): first Monte Carlo calculations done on a computer (ENIAC)
- Berger (1963): first complete, coupled electron-photon transport code (became known as ETRAN)
- Rapid growth since the 1980s with availability of digital computers

Monte Carlo in HENP

- Detector design
 - test scenarios too complex or expensive to do in lab
 - assists in rapid prototyping
 - no modern detector is built without simulation
- Data analysis
 - simulate experimental results with and without new physics added
 - reduce systematic errors
 - increase confidence in results

Many Other Applications

- Astrophysics
- Molecular modeling
- Semiconductor devices
- Financial markets
- Traffic flow
- Optimization problems
- ...

Monte Carlo Basics

Monte Carlo: Stochastic Method for Numerical Integration

- Generate N random points \mathbf{x}_i in the problem space
- Calculate a “score” $f_i = f(\mathbf{x}_i)$ for the N points
- Then calculate $\langle f \rangle = \frac{1}{N} \sum_{i=1}^N f_i$ and $\langle f^2 \rangle = \frac{1}{N} \sum_{i=1}^N f_i^2$
- Central limit theorem: for large N , f will approach the true value \bar{f} with an error σ
- Formally:

$$\bullet \quad p(\langle f \rangle) = \frac{\exp\left[-\frac{1}{2\sigma^2}(\langle f \rangle - \bar{f})^2\right]}{\sigma\sqrt{2\pi}}, \quad \sigma^2 = \frac{\langle f^2 \rangle - \langle f \rangle^2}{N-1}$$

Probability Density Function (1)

- A variable is random (stochastic) if its value cannot be predicted before observing it
- Suppose x is a single continuous random variable defined over some interval
 - can't predict its value, but $Prob\{x_i \leq X\}$ represents the probability that an observed value x_i will be less than or equal to some specified value X
 - generally, $Prob\{E\}$ represents the probability of event E
- The Probability Density Function (PDF) of a single stochastic variable is a function that is
 - defined on the interval $[a, b]$
 - nonnegative on that interval
 - normalized such that $\int_a^b f(x)dx = 1$, a, b real

Probability Density Function (2)

- $f(x)$ is a density function - it specifies probability per unit x
 - $\rightarrow f(x)$ has units that are the inverse of x
- For a given x , $f(x)$ is not the probability of obtaining x
 - infinitely many values x can assume
 - probability of obtaining a single specific value is zero
- instead $f(x)dx$ is the probability that a random sample x_i will assume a value between x and $x + dx$
 - $\rightarrow f(x) = \text{Prob}\{x \leq x_i < x + dx\}$

Mean, Variance, Standard Deviation

- Two important features of a PDF $f(x)$ are its mean μ and variance σ^2
- The mean is the expected or average value of x

- $\langle x \rangle \equiv E(x) \equiv \mu(x) \equiv \int_a^b x f(x) dx$

- The variance describes the spread of the random variable x from the mean:

- $$\begin{aligned} \sigma^2 \equiv \langle [x - \langle x \rangle]^2 \rangle &= \int_a^b [x - \langle x \rangle]^2 f(x) dx = \int_a^b [x^2 - 2x\langle x \rangle + \langle x \rangle^2] f(x) dx \\ &= \int_a^b x^2 f(x) dx - 2\langle x \rangle \int_a^b x f(x) dx + \langle x \rangle^2 \int_a^b f(x) dx = \langle x^2 \rangle - \langle x \rangle^2 \end{aligned}$$

- using $\int_a^b x^2 f(x) dx = \langle x^2 \rangle$, $\int_a^b x f(x) dx = \langle x \rangle$ and $\int_a^b f(x) dx = 1$

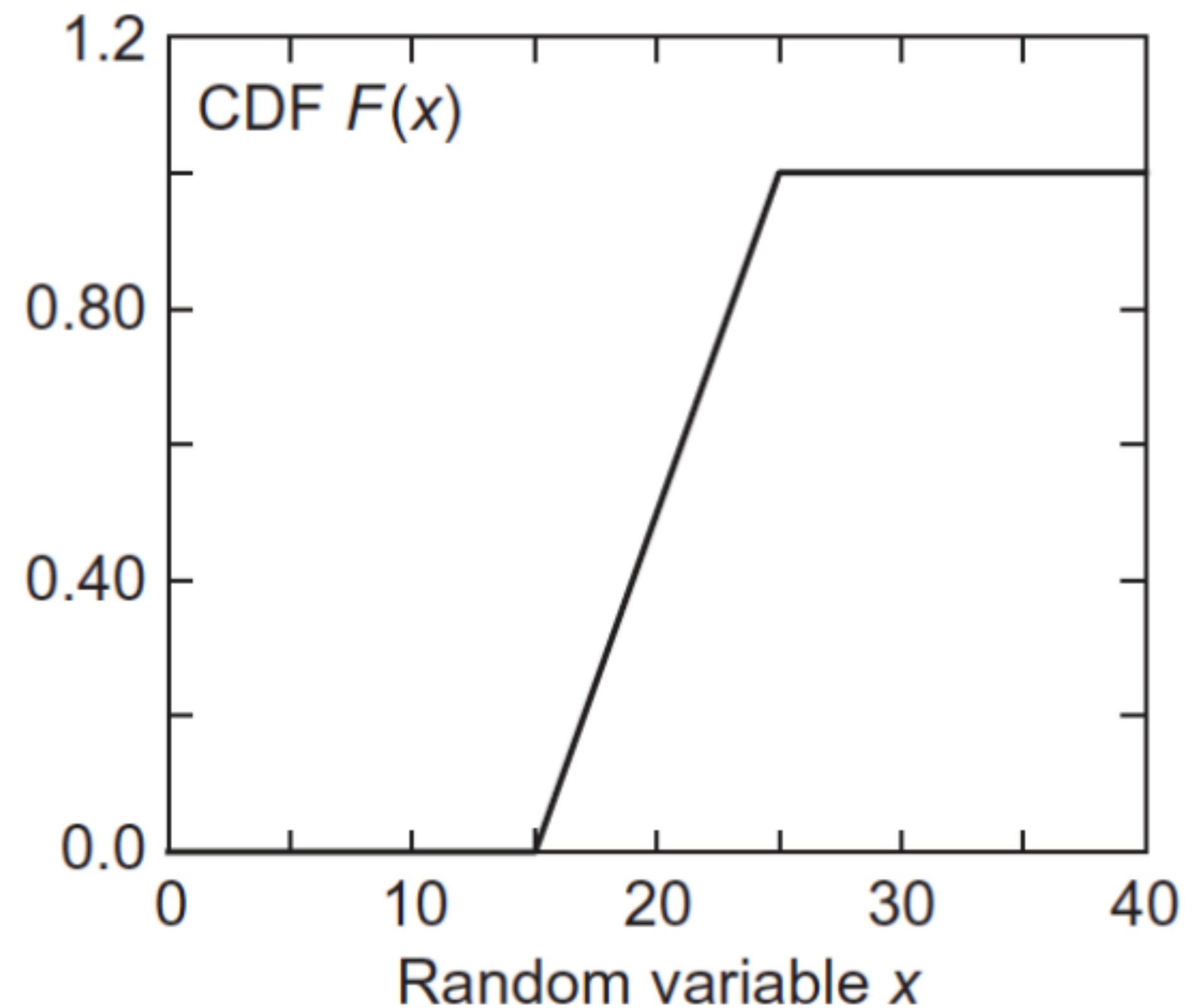
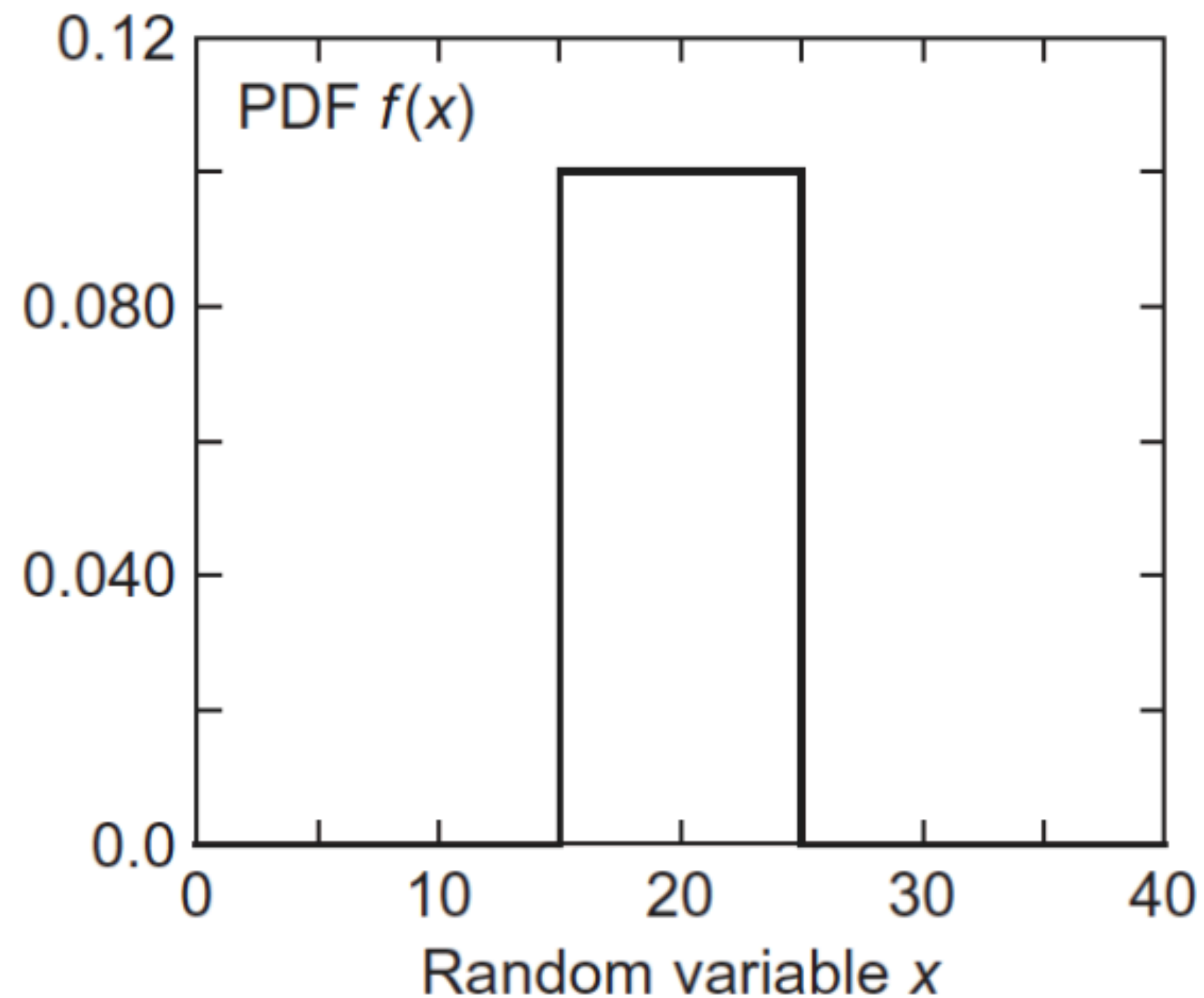
- The square root of the variance is the standard deviation

Cumulative Distribution Function (CDF)

- The CDF is $F(x) = \int_a^x f(x')dx'$, where f is the PDF over the interval $[a, b]$
- and has the properties:
 - $F(a) = 0., F(b) = 1.$
 - monotonically increasing because $f(x)$ is always nonnegative
- CDF is a direct measure of probability. $F(x_i)$ represents the probability that a random sample of x will assume a value between a and x_i , that is $Prob\{a \leq x < x_i\} = F(x_i)$
- More generally, $Prob\{x_1 \leq x \leq x_2\} = \int_{x_1}^{x_2} f(x)dx = F(x_2) - F(x_1)$

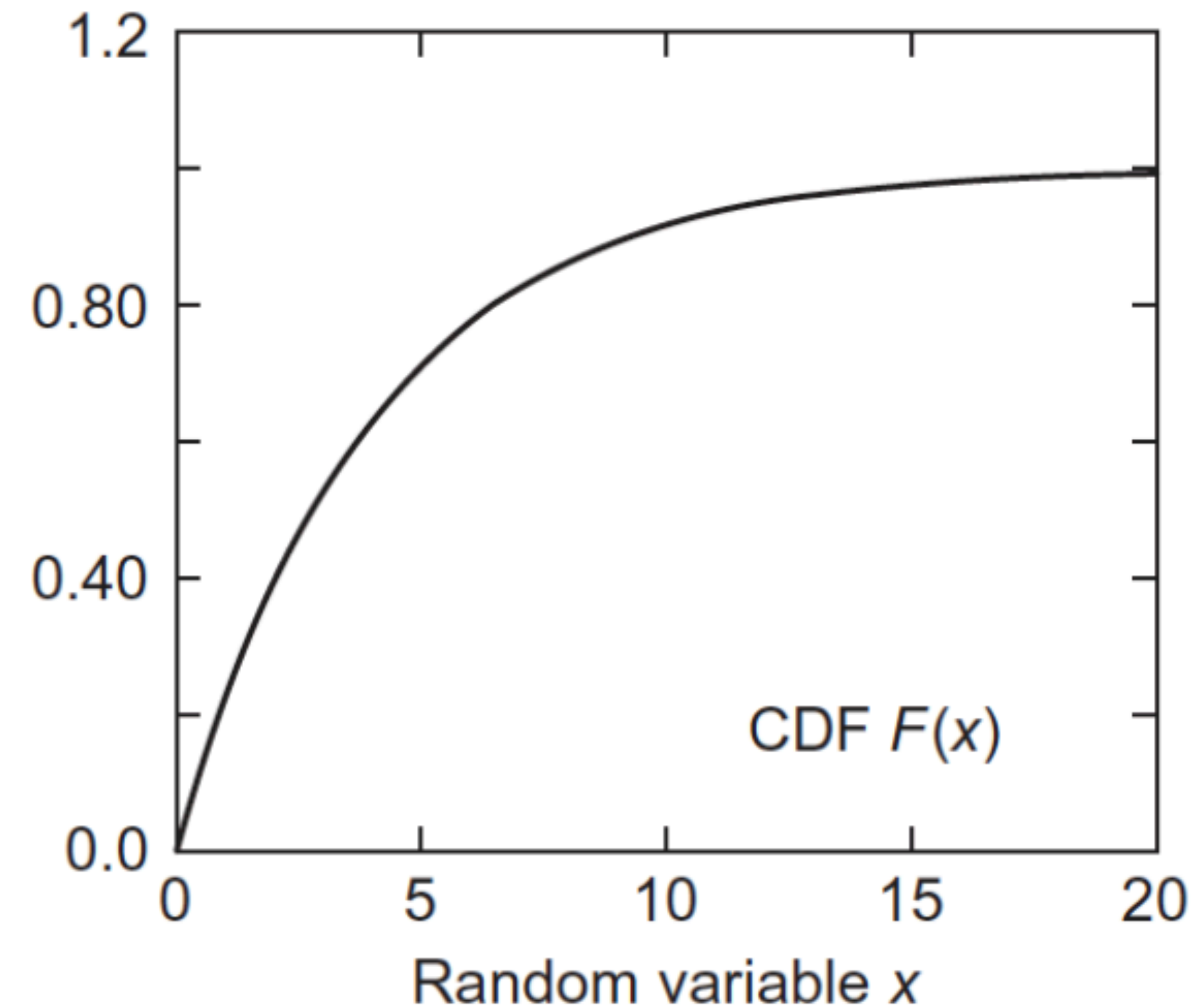
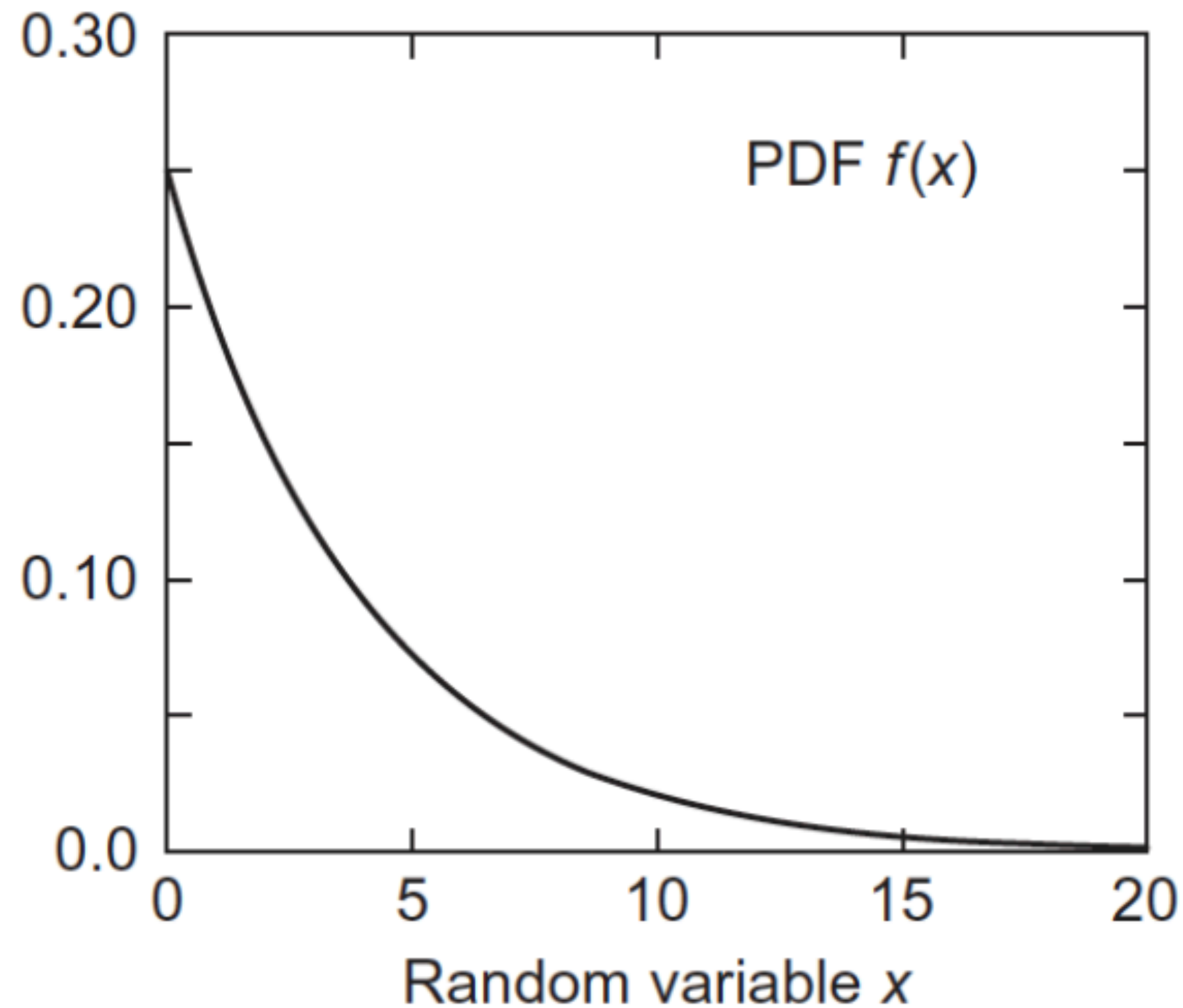
Example 1: Flat PDF

- PDF is a rectangle: $f(x) = \frac{1}{b-a}$, 0 elsewhere, CDF: $F(x) = \int_a^x \frac{1}{b-a} dx' = \frac{x-a}{b-a}$



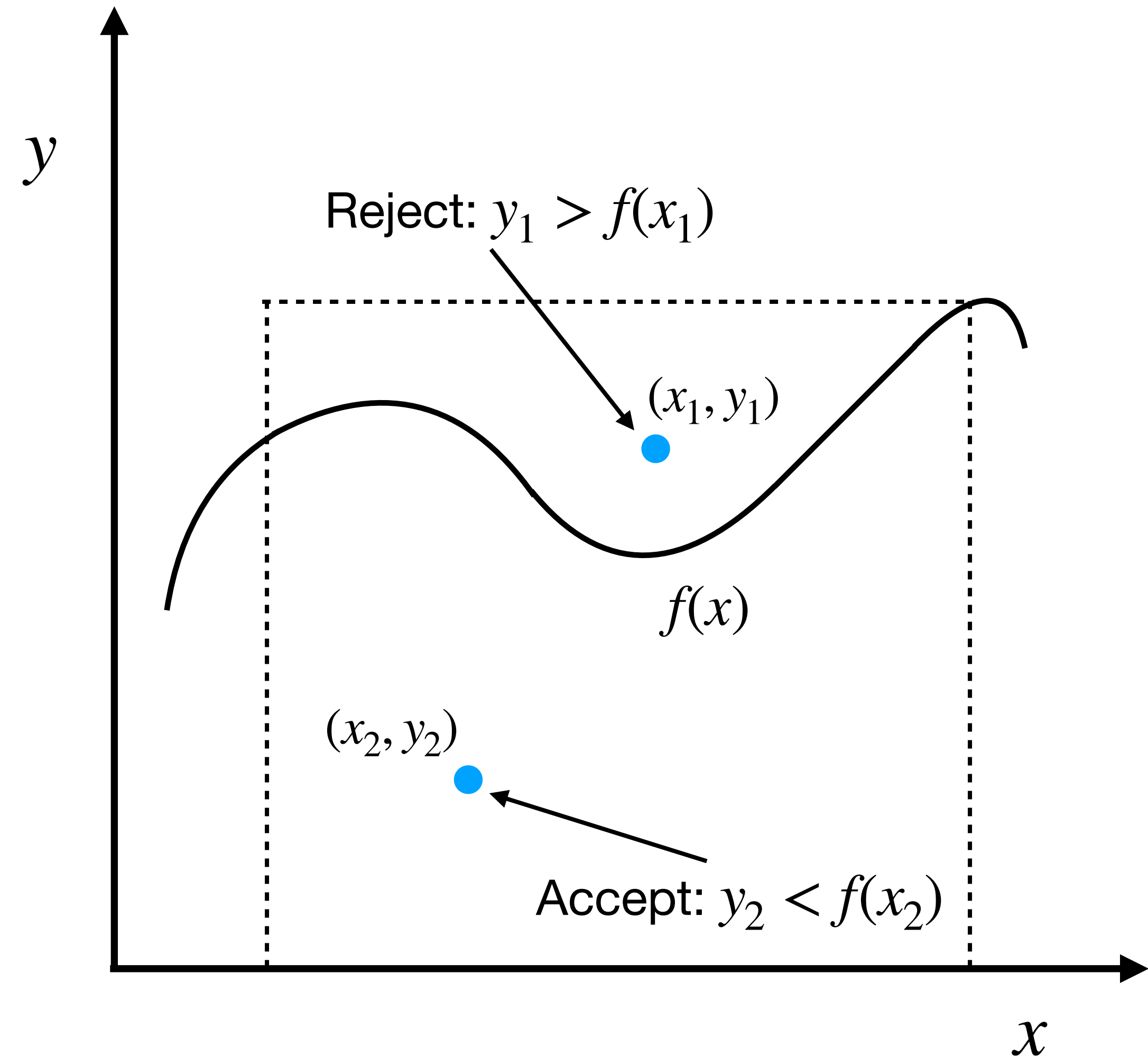
Example 2: Exponential PDF

- PDF: $f(x) = \alpha e^{-\alpha x}$, CDF: $F(x) = \int_0^x \alpha e^{-\alpha x'} dx' = 1 - e^{-\alpha x}$



Example 3: Arbitrary PDF

- A function may not have a closed-form integral, or the integral may not be invertable
- Select (x_i, y_i) randomly from range and domain of function f
- When $y_i > f(x_i)$, point lies above curve, x_i is rejected; when $y_i \leq f(x_i)$, x_i is accepted
- Fraction of accepted points is equal to area below curve -> **accept/reject method**
- For efficiency, choose bounding curve carefully



Examples of Monte Carlo Particle Transport

Decay in Flight (1)

- An unstable particle with mean life τ has momentum p (velocity v)
 - travels distance $d = vt$ before decaying
- Decay time t is a random value with probability density function

- $f(t) = \frac{1}{\tau} \exp\left(-\frac{t}{\tau}\right), t \geq 0$

- The probability that the particle decays at time t is the CDF, which is itself a random variable with uniform probability on $[0,1]$

- $r = F(t) = \int_0^t f(u) du = 1 - \exp\left(-\frac{t}{\tau}\right)$

- Because r is uniformly distributed on $[0,1]$ the value of t can be sampled using the inverse of the CDF
 - $t = F^{-1}(r) = -\tau \ln(1 - r), 0 \leq r < 1$

Decay in Flight (2)

- Final state of decay can be randomly sampled, too
 - shoot a random number, compare to table of branching ratios
 - π^+ for example:
 - $\pi^+ \rightarrow \mu^+ \nu_\mu$ (99.9877 %)
 - $\pi^+ \rightarrow \mu^+ \nu_\mu \gamma$ (2.00×10^{-4} %)
 - $\pi^+ \rightarrow e^+ \nu_e$ (1.23×10^{-4} %)
 - $\pi^+ \rightarrow e^+ \nu_e \gamma$ (7.39×10^{-7} %)
 - ...
- In rest frame of parent particle, rotate decay products in θ $[0, \pi]$ and ϕ $[0, 2\pi]$
- Then Lorentz-boost the decay products
- At least 4 random numbers needed to simulate decay in flight

Decay in Flight (3)

- Throw directions (θ, ϕ) uniformly in the solid angle

- $d\Omega = d\sin\theta d\theta d\phi = d(\cos\theta) d\phi$

- Wrong:

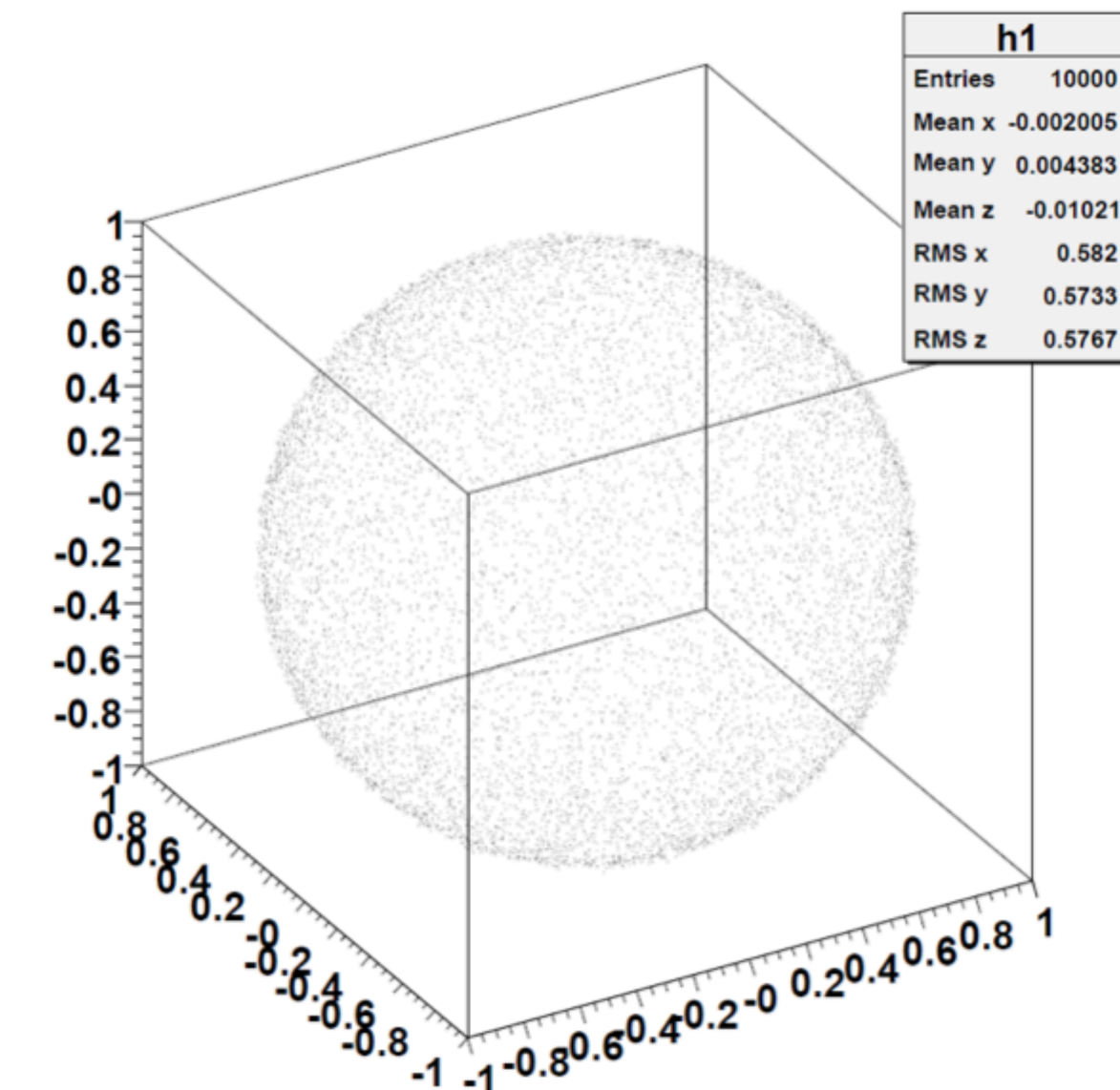
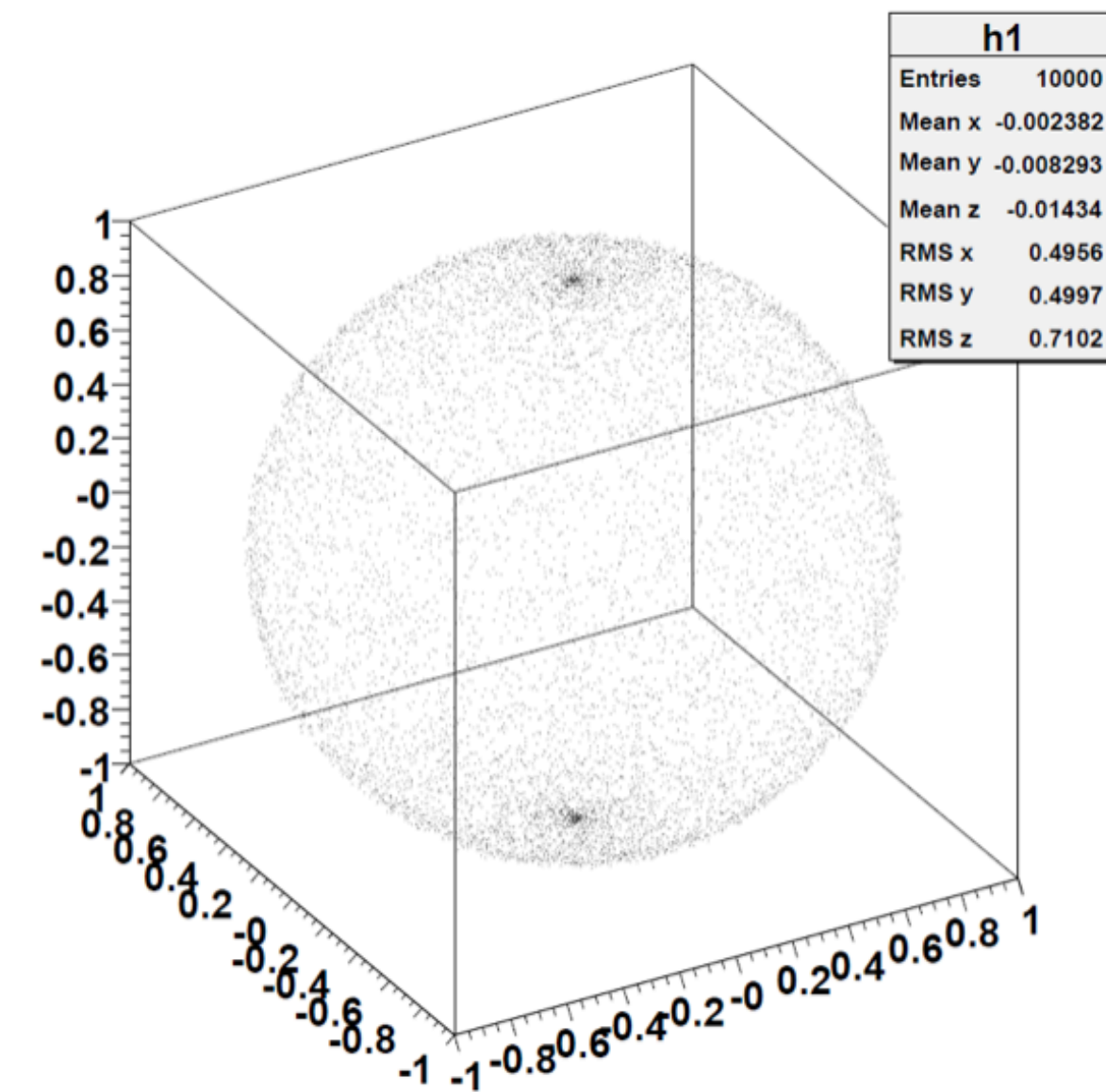
- $\theta = \pi r_1, \phi = 2\pi r_2$

- $0 \leq r_1, r_2 < 1$

- Right:

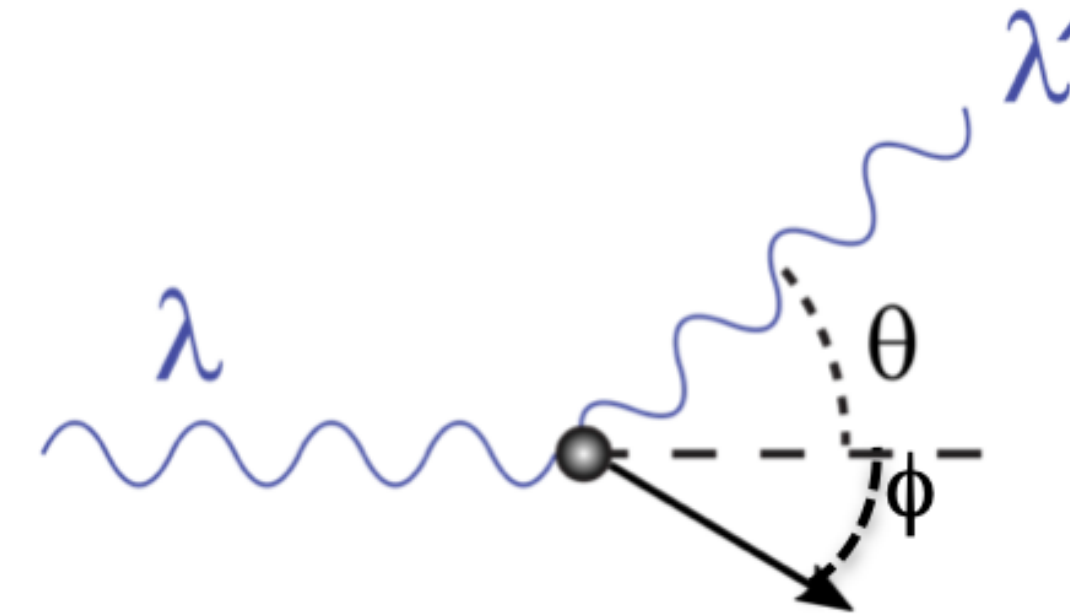
- $\theta = \cos^{-1}(2r_1 - 1), \phi = 2\pi r_2$

- $0 \leq r_1, r_2 < 1$



Compton Scattering (1)

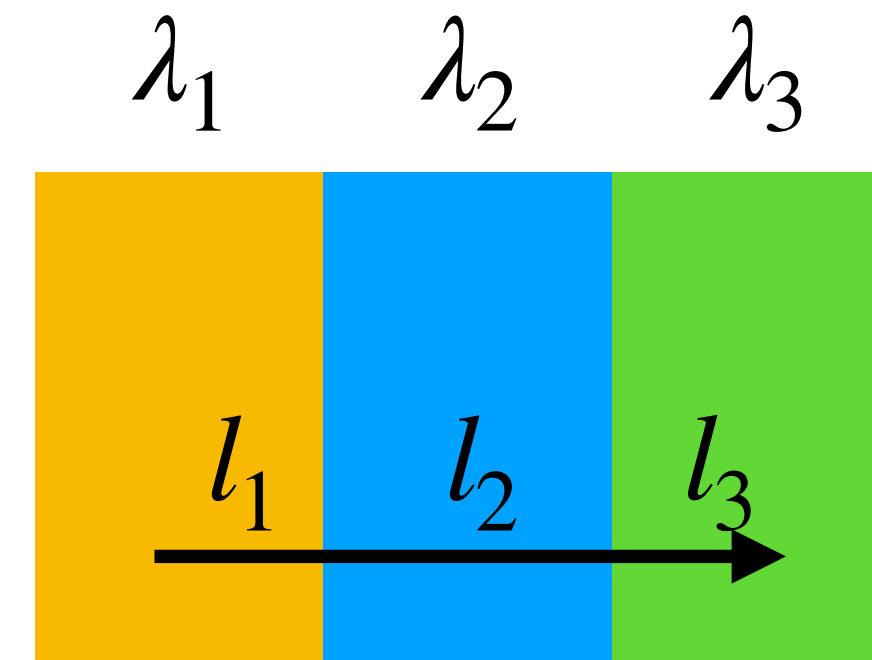
- $\gamma e^- \rightarrow \gamma e^-$
- Distance l traveled before Compton scattering is a random value
- Cross section per volume: $\eta(E, \rho) = n\sigma$
 - cross section per atom: $\sigma(E, z)$
 - number of atoms per volume: $n = \rho N_A / A$ (ρ = density, N_A = Avogadro's number, A = atomic mass)
- η is the probability of Compton scattering per unit length
- $\lambda(E, \rho) = \frac{1}{\eta}$ is the mean free path associated with the Compton scattering process
- The PDF: $f(l) = \eta \exp(-\eta l) = \frac{1}{\lambda} \exp\left(-\frac{l}{\lambda}\right)$
- With random number r uniformly distributed on $[0,1]$, sample the distance: $l = -\lambda \ln(1 - r)$



Compton Scattering (2)

- Ratio $\frac{l}{\lambda}$ (distance traveled to mean free path) is independent of material

$$\bullet n_{\lambda} = \frac{l_1}{\lambda_1} + \frac{l_2}{\lambda_2} + \frac{l_3}{\lambda_3} = \int_0^{end} \frac{dl}{\lambda(l)}$$



- n_{λ} is material-independent and a random value with PDF $f(n_{\lambda}) = \exp(-n_{\lambda})$
 - sample n_{λ} at the particle's origin: $n_{\lambda} = -\ln(1 - r)$, $0 \leq r < 1$
 - update elapsed n_{λ} along the path of the particle: $n_{\lambda} = n_{\lambda} - \frac{l_i}{\lambda_i}$
- Compton scattering happens when $n_{\lambda} = 0$

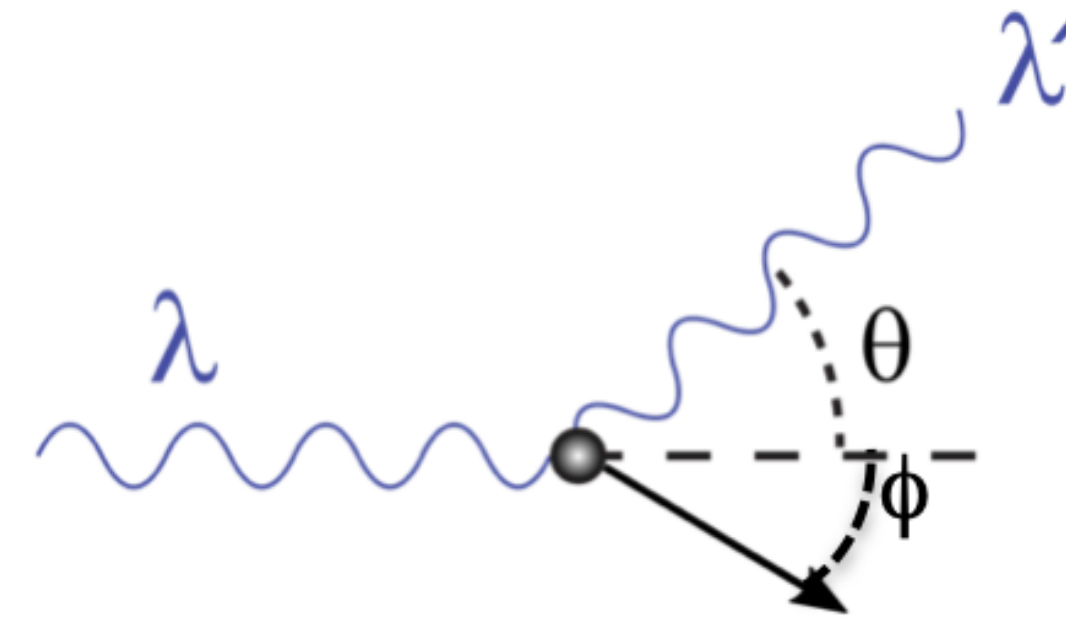
Compton Scattering (3)

- The relation between photon deflection (θ) and energy loss for Compton scattering is determined by 4-momentum conservation between photon and recoil electron

$$h\nu = \frac{h\nu_0}{1 + \left(\frac{h\nu_0}{m_e c^2}\right) (1 - \cos \theta)},$$

$$E = h\nu_0 - h\nu = m_e c^2 \frac{2(h\nu_0)^2 \cos^2 \phi}{(h\nu_0 + m_e c^2)^2 - (h\nu_0)^2 \cos^2 \phi},$$

$$\tan \phi = \frac{1}{1 + \left(\frac{h\nu_0}{m_e c^2}\right)} \cot \frac{\theta}{2},$$



- For unpolarized photons, the angular distribution is given by the Klein-Nishina formula

$$\frac{d\sigma_c^{KN}}{d\Omega}(\theta) = r_0^2 \frac{1 + \cos^2 \theta}{2} \frac{1}{[1 + h\nu(1 - \cos \theta)]^2} \left\{ 1 + \frac{h\nu^2(1 - \cos \theta)^2}{(1 + \cos^2 \theta)[1 + h\nu(1 - \cos \theta)]} \right\}$$

$$= \frac{1}{2} r_0^2 \left(\frac{k}{k_0}\right)^2 \left(\frac{k}{k_0} + \frac{k_0}{k} - \sin^2 \theta\right) \quad (cm^2 sr^{-1} electron^{-1}),$$

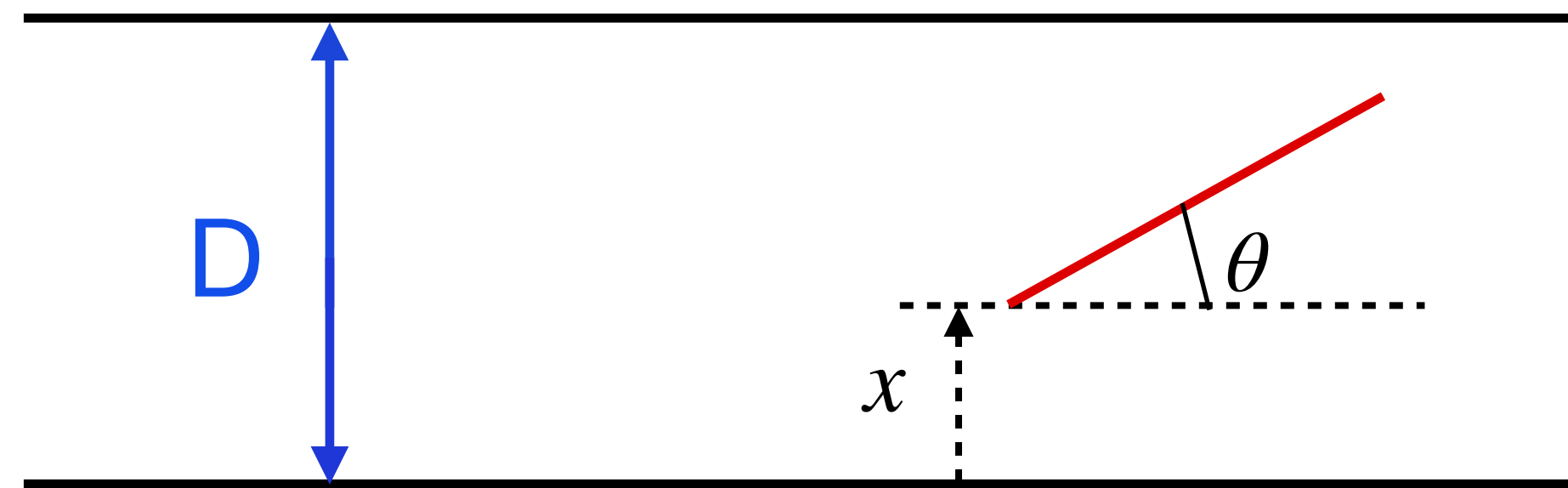
$$k_0 = \frac{h\nu_0}{m_e c^2}, \quad k = \frac{h\nu}{m_e c^2}$$

- Use accept-reject method to sample the distribution

Boosting the Simulation

Buffon's Needle

- Calculate π by dropping a needle on a lined sheet of paper and determine the probability that the needle crosses one of the lines
- Probability is directly related to the value of π



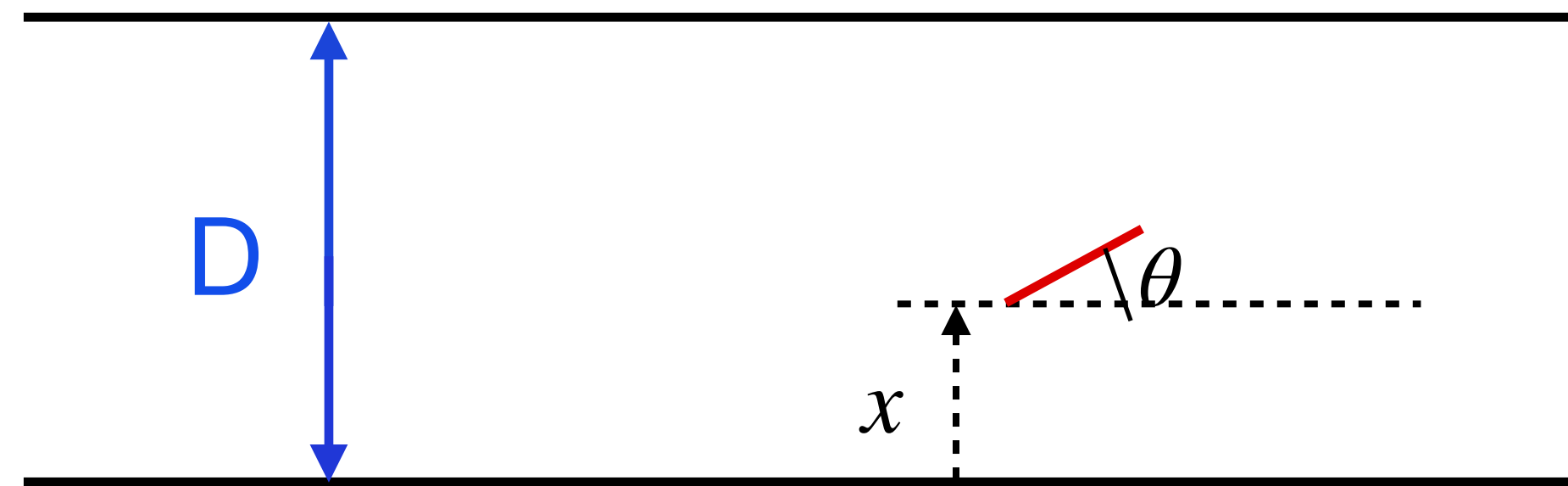
- Needle of length L will cross line if $x \leq L \sin\theta$. Assuming $L \leq D$, the probability of a line crossing is

$$\bullet P_{cross} = \int_0^\pi \frac{d\theta}{\pi} P_{cross}(\theta) = \int_0^\pi \frac{d\theta}{\pi} \frac{L \sin\theta}{D} = \frac{2L}{\pi D}$$

- Dropping a needle N times and counting N_c , the number of crossings, gives P_{cross} and thus π

Boosting Buffon's Needle

- If the length of the needle is much smaller than the spacing of the lines, the estimate of π will take a long time
 - $\pi \sim (2L/D) * (N/N_c)$, x sampled uniformly over $[0, D]$



- Speed things up by sampling x over the interval $[0, L]$ instead
 - probability that $0 \leq x < L$ is $\frac{L}{D/2}$
 - each successful count should be multiplied by a weight $\frac{2L}{D}$
 - then, $\pi \sim (2L/D) * \frac{N}{N_c(2L/D)}$

Biasing (Variance Reduction)

- In boosting Buffon's needle, we biased the simulation
 - by sampling over a subset of the original interval that was of more interest
 - applying a weight to successful events to correct for bias
 - significantly speeding up the simulation
- Called variance reduction because the variance of the result for a given simulation effort is reduced (precision increased)
- Very useful for sampling events which are rare due to physics or geometry
- Can make otherwise impossible Monte Carlo problems solvable
- Care is required - use of variance reduction techniques requires skill and experience
- See talk on biasing and fast simulation for some of these techniques

Summary

- Detector simulation an essential part of nuclear and high energy physics
 - Monte Carlo methods widely used outside HENP, too
- Stochastic methods used where deterministic methods don't apply
 - Central limit theorem: get close to the answer with large enough statistics
- Many methods to sample functions of random variables
 - integrate PDF to get CDF, invert CDF to get sampling formula
 - complicated PDF -> use accept/reject method
- Simulating physical processes involves throwing lots of independent random numbers
 - sample number of mean free paths, momentum, angular distributions, ...
 - increase confidence in results
- Biasing can really speed things up
 - care is required