



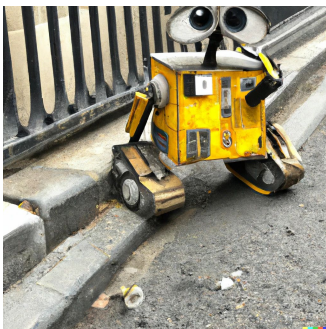
Transformers for Generalized Fast Shower Simulation

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Realistic photo of wall-e on the streets of London

<https://dalle2.gallery>

Foundation models

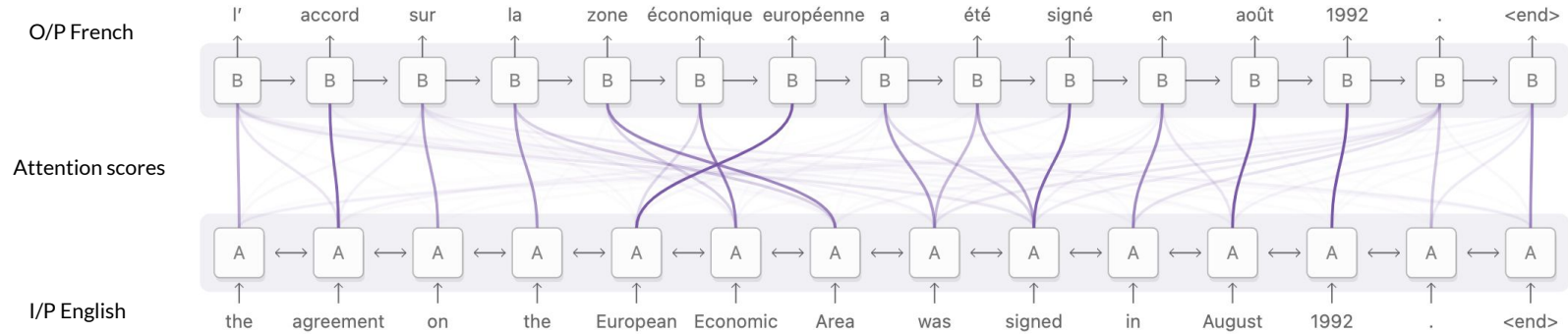
- The idea of foundation models started from very large pre-trained language models.
- Examples:
 - BERT, GPT-3, ChatGPT (Generative language models)
 - DALL-E, DALL-E 2, Imagen (Text to Image models)
- These models are typically **trained on very large & diverse datasets and variety of tasks** allowing them to learn patterns and represent common concepts and relationships.
- Generally, their architecture is **transformer-based**.

Motivation

- Development of machine learning models for fast shower simulation is computationally expensive.
- Moreover, designing model for each experiment requires dedicated expertise.
- Therefore, **train once, then adapt** to new detectors, quickly.

- **Transformers** as building blocks in foundation models:
 - A **generalized architecture** that works with any type of data, e.g., text, images, audio, etc.
 - Models long-range dependencies (**Attention** mechanism).

Attention in transformers



- **Dynamically focuses on important parts** in the input.
- Helps in modelling correlations between energy deposits.

Our roadmap



1. Check if the transformers can learn good representations of our shower data.



2. Build a generative model for fast shower simulation.

- 1. **Autoregressive**
- 2. **Diffusion**



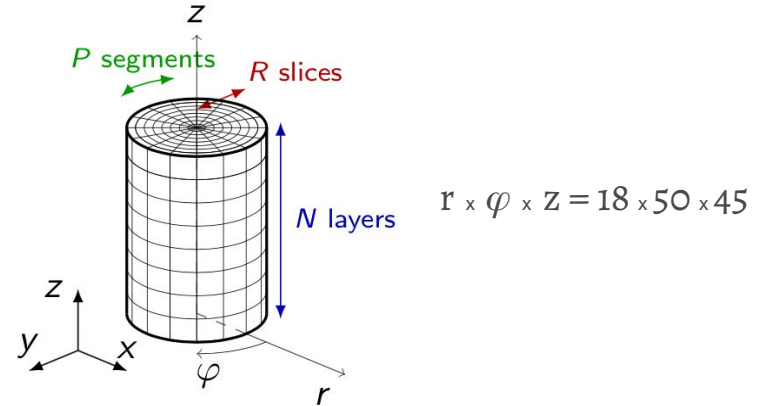
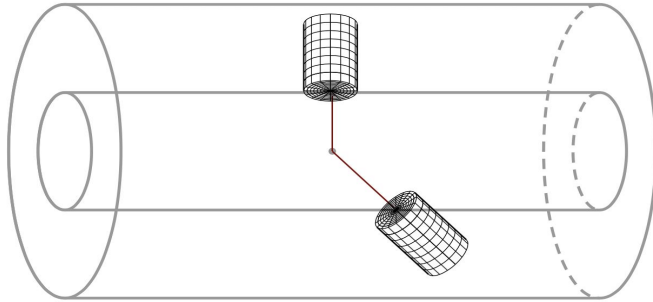
3. Scale in both model (size) and dataset (size & variety).

Final goal - A generalizable foundation model for fast simulation adaptable to new data

Dataset



We utilize a [dataset](#) similar¹ to “CaloChallenge Dataset 3”. ([Talk](#) at CHEP’23)



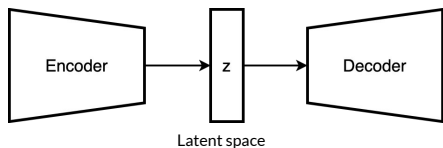
For the shown preliminary results, we use the following subset (~100k samples):

- Angle of incident $e^- = 70^\circ, 80^\circ, 90^\circ$
- Energy of incident $e^- = 64, 128, 256$ GeV
- Sampling calorimeter with silicon and tungsten layers² (SiW)

¹More incident angles and discrete energy spectrum

²Layer thickness: 0.3 mm + 1.4 mm for Si & W respectively

Variational autoencoder (VAE)



Train first

*Train later keeping
VQVAE frozen*

Autoregressive model architecture

Two-stage model (both models have transformer-based architecture):

1. Vector Quantized Variational Autoencoder (VQ-VAE)

- An autoencoder with discrete latent space.
- Compresses and decompresses the shower to and from the latent space.
- Thus, reduces the computational burden on the 2nd stage.

2. Autoregressive prior

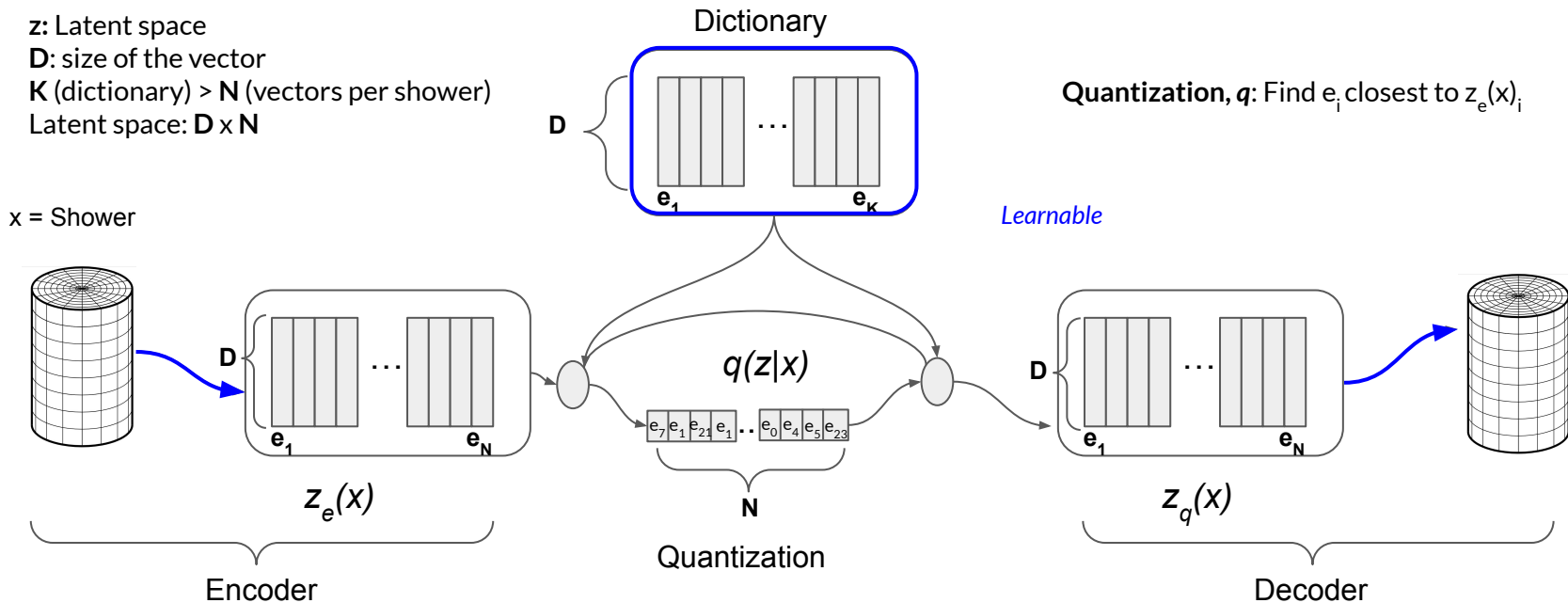
- Unlike VAE, VQ-VAE cannot generate new samples¹.
- Hence, an autoregressive prior to learn the latent space distribution.

¹The latent space is discrete instead of Gaussian, thus not straightforward to sample from.

VQ-VAE

Maps the input to and from a finite set of **vectors** (latent space).

- z : Latent space
- D : size of the vector
- K (dictionary) $> N$ (vectors per shower)
- Latent space: $D \times N$

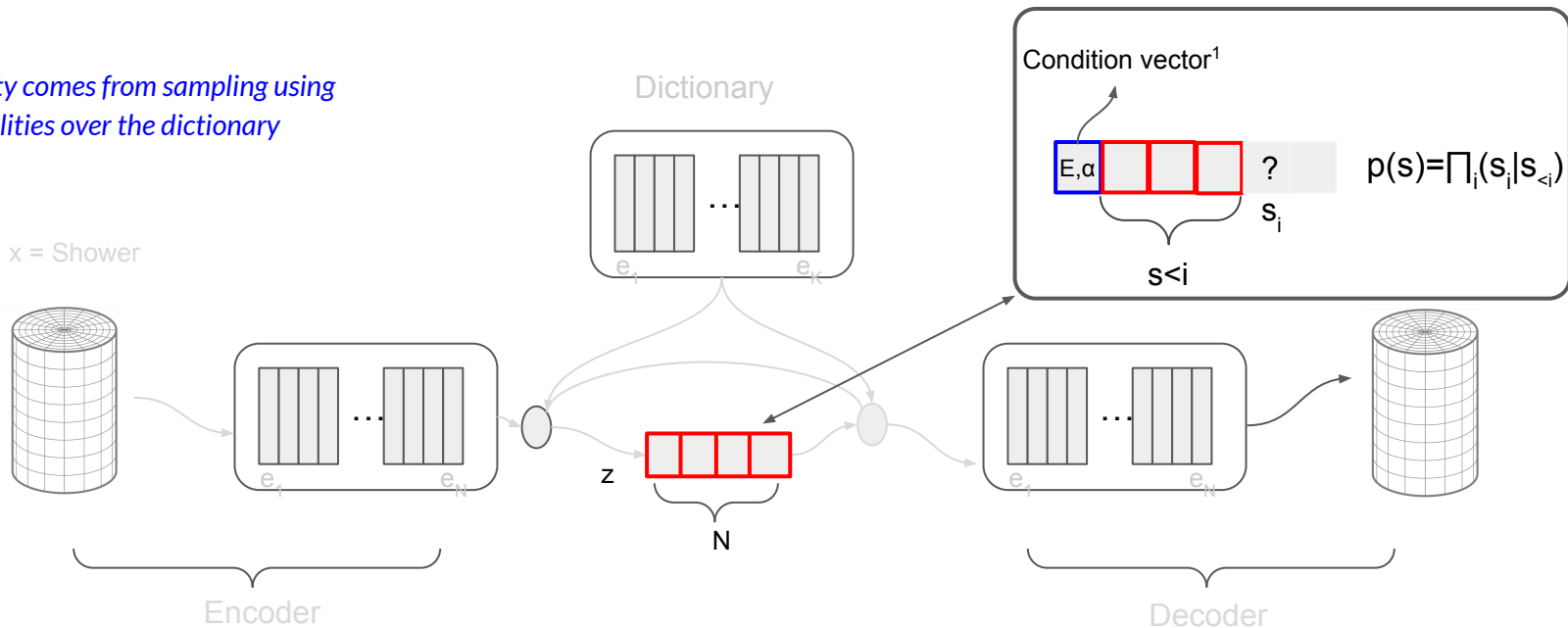


Autoregressive prior

Given previous vectors, predict the next vector.

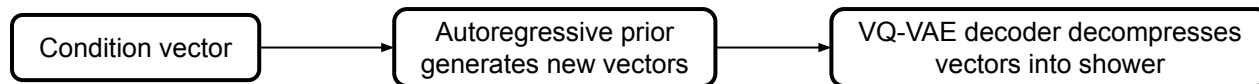
The goal is to mimic VQ-VAE's dictionary vector distribution.

Stochasticity comes from sampling using the probabilities over the dictionary



¹Condition vector ((energy, angle, (+ detector, position offset))) projected via a linear layer of dimension D.

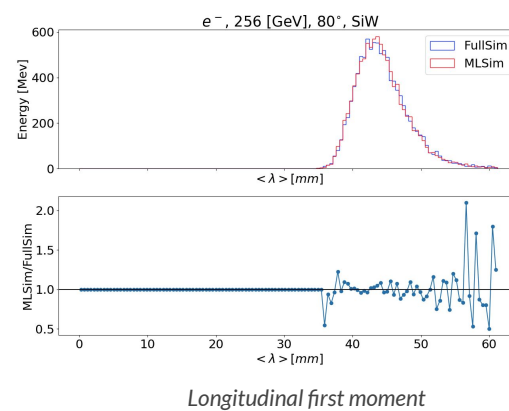
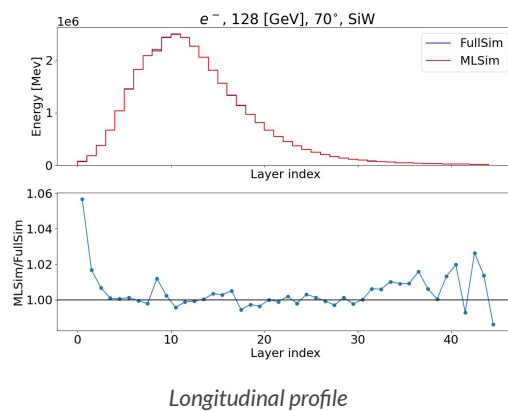
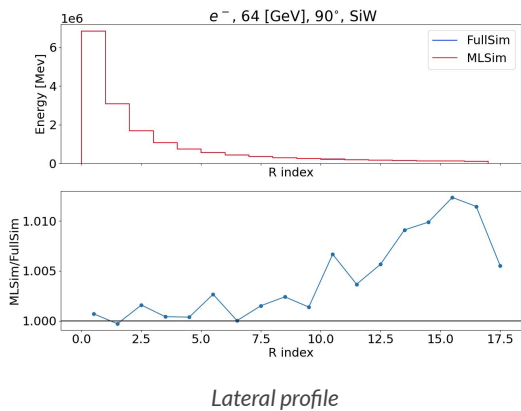
Generative model



Adaptation of generative model for new data:

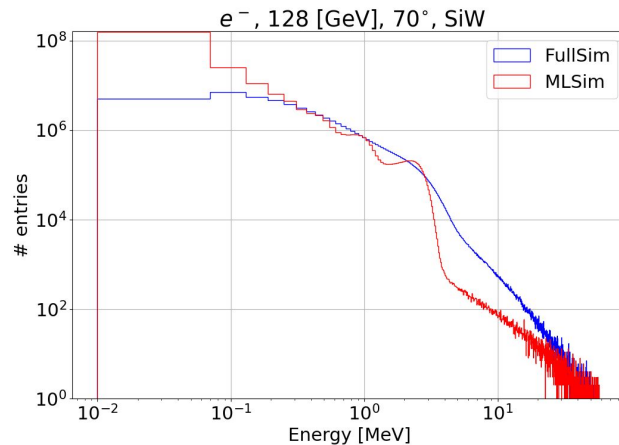
- Autoregressive prior is fine-tuned on the new detector's data.
- We believe VQ-VAE (thus also dictionary) would become robust with more data and should remain frozen. (Needs to be investigated)

Results - VQVAE



VQ-VAE was able to model lateral & longitudinal profiles,
first & second moments really well.

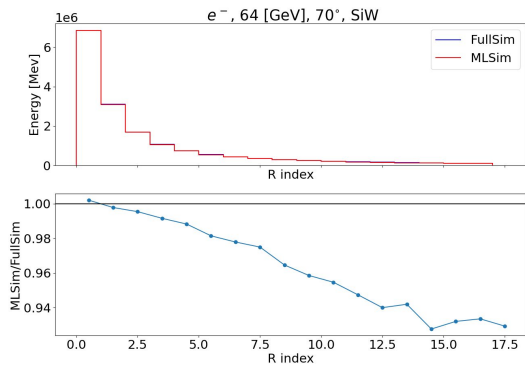
Results - VQVAE



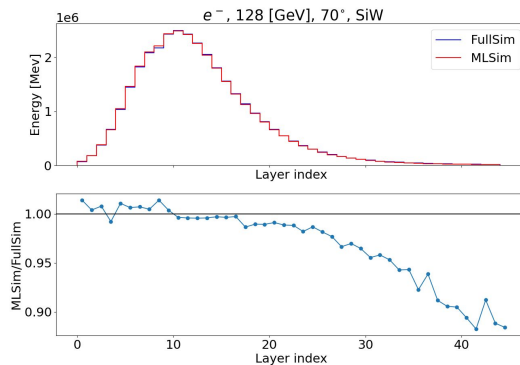
Cell energy distribution

- Accurate modelling of cell energy distribution is in progress. Currently leads to *blurry showers*.
- Introducing a GAN discriminator should help in properly modelling the cell energy distribution.
(Next step)
- This also limits the autoregressive prior as VQ-VAE acts like an upper-bound.

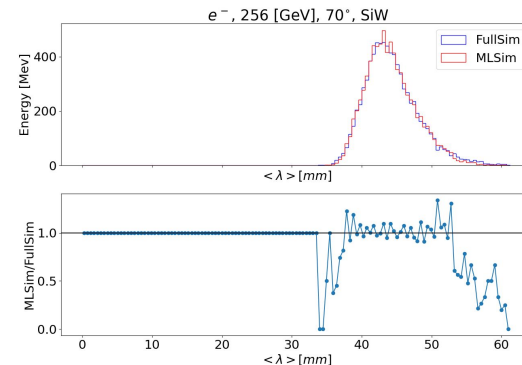
Results - Autoregressive prior



Lateral profile



Longitudinal profile



Longitudinal first moment

- Autoregressive prior mimics the VQ-VAE vector distribution fairly well.
- The longitudinal & lateral profiles deviate at the tail due to uneven distribution of dictionary vectors.
- This should be overcome by using standard tricks to improve any classification model. (Next step)

Conclusion

- Proposed a transformer-based generative model for fast simulation.
- This is a work in progress and we obtained promising preliminary results.
- We have several potential ideas to improve VQ-VAE and Autoregressive prior, e.g., GAN discriminator, Gumbel-Softmax quantizer, multi-scale architectures, which are under investigation.
- In parallel, we are exploring the diffusion model which has proven to be promising for images.
- One of the main future work is to conduct a large scale training and analyze the generalization capability of the model.

Thank you for listening!

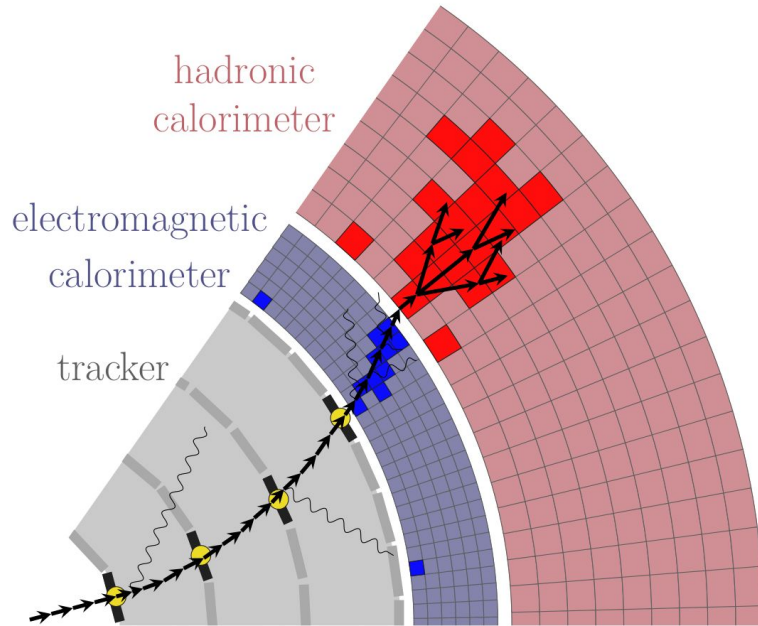
Questions?

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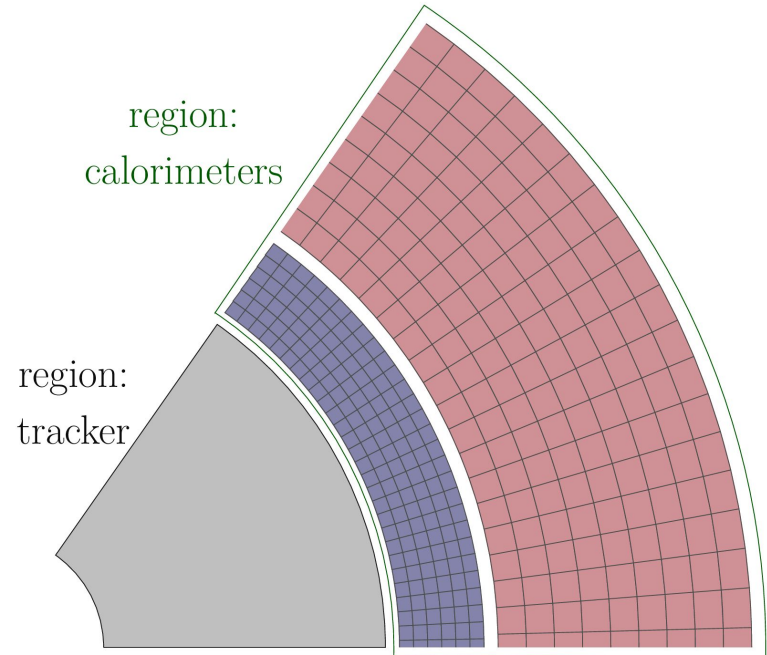
Backup

Fast shower simulation

FullSim



FastSim

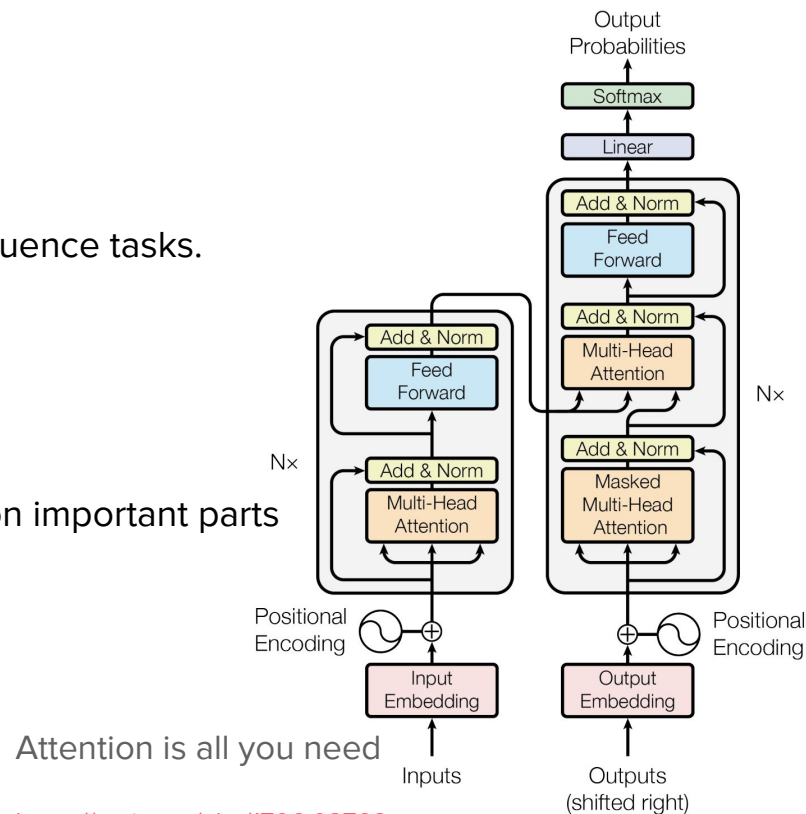


Dataset

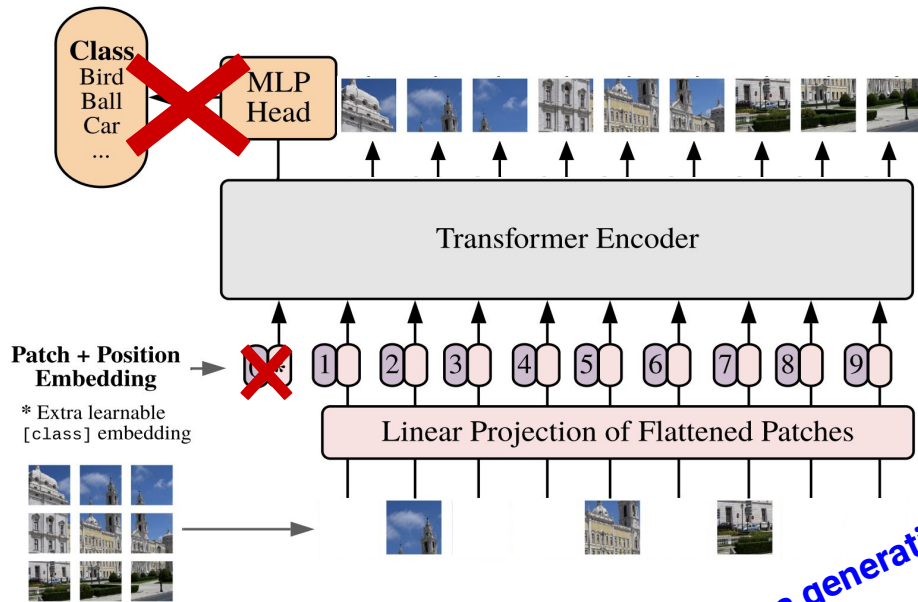
- [High Granularity Electromagnetic Calorimeter Shower Images \[zenodo\]](#)
 - Energy = 1 GeV - 1 TeV
 - Angle = 50° - 90°
 - Geometries = SiW, SciPb
 - ~10,000 events each

Transformer

- Proposed for sequence-to-sequence tasks.
- I/O is any type of sequences.
- Encoder-Decoder blocks.
- Positional embeddings.
- **Attention:** Dynamically focus on important parts in the input.
- Multi-headed attention.



Self-supervised training



Modifications to ViT (Vision transformers)

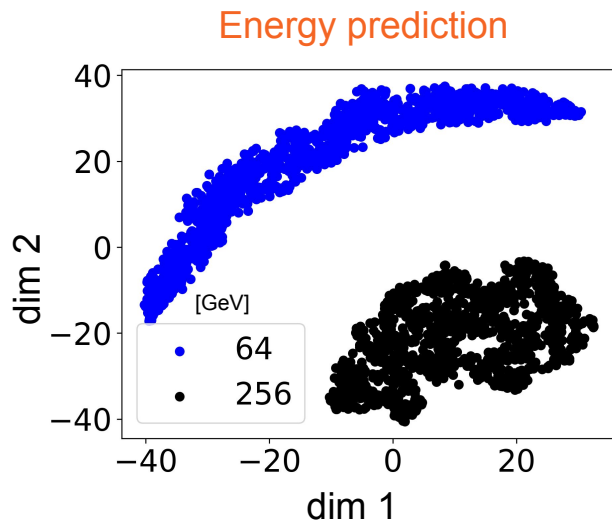
1. 3D image, 3d patches
2. 3D positional embeddings
3. Masked language modelling (MLM)
 - a. Remove “MLP Head”
 - b. Remove “class embedding”
 - c. Add masking
 - d. Reconstruct original image

Masked language modelling (MLM) is learning representations by trying to predict hidden information.

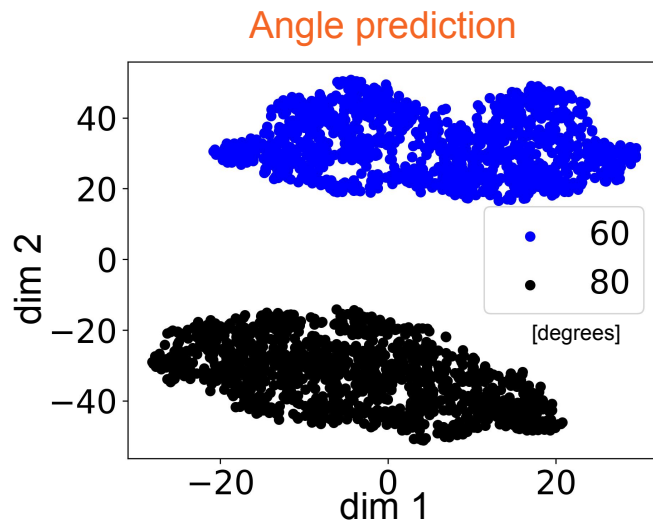
Checking representations

Q: How to validate that the transformer model is learning a good representation of our shower data?

A: Use a “fake” downstream task: predict the energy/angle of the incoming particle using the transformer’s representation



99% accuracy

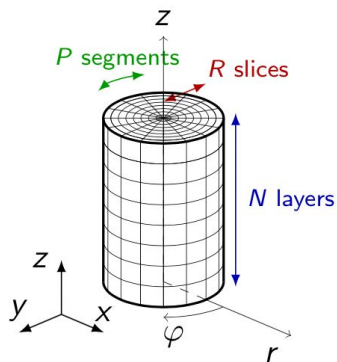


99% accuracy

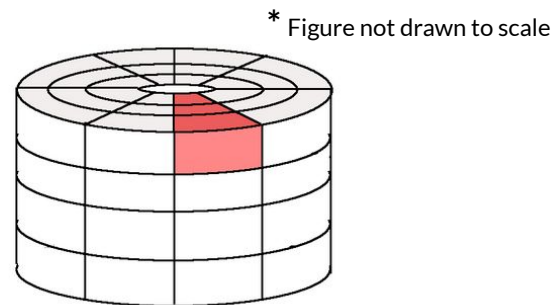
From shower to 3d sequence

Transformers needs the input to be in the form of a sequence. Therefore,

- Patches are formed by making splits in r , φ and z direction
- Patch configuration: 1 patch in r , 10 in φ and 15 in z



1 shower = a set of patches



$$r \times \varphi \times z = 18 \times 50 \times 45$$

$$\text{Patch size } r \times \varphi \times z = 18 \times 5 \times 3$$

Positional embeddings

Transformers are permutation invariant. Positional embeddings gives an understanding of position to the model.

Explored

- 1D learnable keras embedding layer.
- Fixed 3D positional embeddings
 - Alternate sine-cosine.
 - Each direction takes $1/3^{\text{rd}}$ of the embedding dimensions.
- Phi-rollover

Observation

- Fixed 3D positional embeddings perform better (*default*).

Preprocessing & Loss function

Preprocessing

Division by energy value of the incident particle.

Loss function

- **VQVAE:** Binary crossentropy + VQVAE specific losses
- **Autoregressive prior:** Crossentropy

Two stages

- VQ-VAE is not a generative model (discrete latent space).
- Hence, needs autoregressive prior to model to learn the latent space.
- Autoregressive prior due to sampling is a generative model.
- Autoregressive prior cannot be used alone:
 - It needs to predict a class. We have continuous energy deposits.
 - Sequence (voxels) would be too long.
- Since autoregressive prior needs to predict a class, it needs a discrete (finite) latent space from the autoencoder. Hence, VQ-VAE over VAE.
- TLDR - **both VQ-VAE and autoregressive prior depends on one another.**