# End-to-end, ML-based Reconstruction Chain for Particle Imaging Detectors

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## **Liquid Argon Time-Projection Chambers**



#### The modern Particle Imaging Detector



ML-based Reconstruction for Imaging Detectors, F. Drielsma (SLAC)

**LArTPC** are at the center stage of **beam** *v* **physics** in the US

### Short Baseline Neutrino program

• µBooNE, ICARUS, SBND

## **DUNE** long-baseline experiment

- Wire: DUNE FD
- Pixel: DUNE ND-LAr

## Advantages:

- **Detailed:** O(1) mm resolution, precise calorimetry
- Scalable: Up to tens of kt

## **Liquid Argon Time-Projection Chambers**



Case study: ICARUS Simulation

Realistic **BNB**  $v_u$  + **Cosmic** ICARUS simulation as a **benchmark** 

- **One v**<sub>u</sub> + Ar interaction/image
- ~25 cosmic interactions/image



- TPC boundaries



#### Challenges with LAr

#### Dense medium $\rightarrow$ Slow

Electron drift velocity  $O(1) \text{ mm/}\mu\text{s}$ 

- Long (O(1) ms) readout window
- Need light association for timing



## $\textbf{High Z material} \rightarrow \textbf{Messy}$

Argon has a large nucleus (Z=18)

- Complicated nuclear physics
- Secondary interactions



## **Reconstruction in LArTPCs**



Hierarchical feature extraction



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Hierarchical feature extraction

What is relevant to pattern recognition in a detailed interaction image?

1. Separate topologically distinguishable types of activity





#### Hierarchical feature extraction

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- 2. Identify **important points** (vertex, start points, end points)





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Hierarchical feature extraction

- 1. Separate topologically distinguishable types of activity
- 2. Identify important points (vertex, start points, end points)
- 3. Cluster individual particles (tracks and full showers)
- 4. Cluster interactions, identify particle properties in context



4.



## **Reconstruction in LArTPCs**

#### Hierarchical feature extraction

### What is relevant to pattern recognition in a detailed interaction image?

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- Identify **important points** (vertex, start points, end points) 2.
- Cluster individual particles (tracks and full showers) 3.
- Cluster interactions, identify particle properties in context





 $\rightarrow$  Pixel-level

 $\rightarrow$  Cluster-level

## **Pixel-Level Feature Extraction**



Backbone

### UResNet (<u>UNet</u> + <u>ResNet</u> + <u>Sparse Conv.</u>) as the **backbone feature extractor**





Ghost buster

In a **wire TPC**, we do not get 3D images, but rather 3 x 2D projections

- Find valid combinations of 2D hits: legitimate + artifacts (ghosts)
- Classify artificial space points as such: ghost removal



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0.8

0.6

0.4

0.2

Particle voxel class classification

### Separate topologically different types of activity

• Tracks, Showers, delta rays, Michel electrons, low energy blips







Points of interest Narrow down a region proposal all the way to a point

## Predict masks at different scales with UResNet, predict position in voxel



## Point Proposal Network (PPN)



## **Dense Fragment Formation**



Spatial embedding transformation

Transform coordinates to an space in which tracks are spatially separated

• Cluster track/shower fragments at this stage



## **Particle-Level Aggregation**



#### Graph Particle Aggregator (GrapPA)

### Graph Neural Network: fragments/particles (nodes), correlations (edges)



## Aggregation

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Graph edge classification

### Two aggregation steps: fragments $\rightarrow$ particles $\rightarrow$ interactions

• Select edges in the graph that minimize loss, find connected components



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#### Graph node classification

### Particle species much easier to infer in context

• Michel decays, secondary hadrons, shower conversion gaps, etc.









#### Takeaways

### End-to-end ML-based reconstruction chain mature and functional

- UResNet for pixel feature extraction, GrapPA for superstructure formation
- Used on ICARUS sim./data and DUNE-ND (high neutrino pileup) sim. today
- Check out this ICARUS interactive reconstructed event !



# **Backup Slides**

## **Liquid Argon Time-Projection Chambers**

#### Case study: Detector

The largest LArTPC in operation is ICARUS

- Surface-level detector
- **500 t** fiducial mass (2 cryos, 4 TPCs)
- Physics: sterile neutrinos (MiniBooNE / Neutrino-4), cross sections, BSM

### Event rates

- BNB beam: ~ 0.03 Hz neutrinos
- NuMI off-axis: ~ 0.015 Hz neutrinos
- In-time cosmic activity: ~ 0.25 Hz

# Low-rate neutrino experiment with a significant cosmic background







## **Point Proposal Network**

#### Architecture

The Point Proposal Network (PPN) uses decoder features:

- Three CCN layers to progressively narrow ROI
- Last layer reconstructs:
  - Relative position to voxel center of active voxel
  - Point type
- Post-processing aggregates nearby points





## **Graph-SPICE**



#### Architecture





#### Edge selection procedure

What the network gives you:

- Likelihood that an edge connects two objects in the same group Target:
  - Find the optimal partition

Method:

• Iteratively add the most likely edge to optimize CE loss



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Graph node classification

### Important to know which particle originate from the vertex

• Central to any exclusive analysis (study specific channels)



### BNB $v_{\mu}$ primaries only

