





Accelerated demonstrator of electromagnetic Particle Transport

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Simulation on GPU - can we do that?

GPUs are today widely available in HPC centers

- Silicon that we have to use to increase HEP detector simulation throughput
- A major challenge given the code complexity for particle transport (Geant4)
- Two main R&D projects spawned ~ 3 years ago
 - <u>AdePT</u> (CERN/SFT + collaborators) & <u>Celeritas</u> (ECP: ORNL, FNAL, Argonne, LBL)
 - Looking at the problem from different angles & learning from each other (++)
 - Inter-project meetings and a community <u>mini-workshop</u> one year ago
 - marking the completion of a first R&D phase
- We can actually run complex (LHC level) simulation on GPUs now
 - Standalone, but also integrated in a Geant4-driven workflow (see this talk)

The AdePT project

Putting together all pieces needed to run EM shower simulation on GPU

ant-sim / AdePT Publ

- GitHub <u>repository</u>, initial commit in Sep 2020, **0**(10) contributors
- Strategy: integrate gradually features as new examples
 - Core infrastructure, physics and geometry as external services
 - Lightweight transport stepping loop evolved gradually in examples
 - Not a framework approach at this point, to maximize flexibility to change/adapt/integrate
- Minimal external dependencies
 - Geometry: <u>VecGeom</u> library, enhancing its GPU-related features
 - Physics: <u>G4HepEm</u> library, a compact GPU-friendly port of Geant4 EM interactions
- A first integration approach with Geant4 available (via fastsim hooks)
 - Discussions/evaluation with ATLAS, CMS and LHCb for testing and integration

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Stepping loop at a glance

- Simulation is done in steps as in Geant4
 - Difference: All active tracks available are stepped at once (exposing the parallelism to the GPU)
 - A step may be limited by physics
 - All EM physics calculations delegated to the external G4HepEm library
 - Modeling all <u>interactions</u> for e⁺, e⁻ and γ,
 verified against Geant4
 - ... or geometry
 - Calculations delegated to the VecGeom library
 - GPU port not GPU-friendly ...
 - The main bottleneck (see <u>this talk</u>)
 - Radical changes for geometry GPU support: main optimization work during last year



CopyToHost

copy simulation products (hits, leaked tracks) back to host

36 SM GPU (consumer class)≃32 CPU cores in HT mode (dual socket CPU) for simple setups (see backup)

AdePT-Geant4 integration

AdePT only provides EM physics for e⁺, e⁻ and γ

- Cannot be used standalone for simulating a full experiment
- In a first phase it could be used as accelerator for the EM part, in the same way as fast simulation models can be used in Geant4
- Developed an integration interface allowing a Geant4 region to become the "GPU region"
 - Intercepting and buffering for GPU particles sent asynchronously by Geant4 threads
 - Available from Geant4.11.1, patches available for older versions
 - Sensitive detector code run on device, hits+leaked tracks sent back to host
 - This approach is under evaluation by several experiments



Integration performance

- Performance in this approach increases with :
 - Fraction of time spent in the GPU-accelerated region (Amdahl's law)
 - GPU buffer size (up to 5x impact)
- Performance degrades with :
 - Number of exchanges CPU-GPU per event
 - Number of CPU threads (GPU saturation, CPU transport stalled while GPU loop running)
- Why not the full EM on GPU?
 - Not limited by geometry or physics
 - Lepto-nuclear processes are rare and can be delegated to CPU

Higher is bette

- Limited by sensitive detector code GPU awareness
 - Incentive to write GPU-friendly sensitive detector scoring even for e.g. trackers



#workers

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Towards integration with experiments

CMS: targeting Phase 2 setup, in particular CMS HGCal

- First steps already made
 - Loading the CMSSW-exported geometry setup in AdePT integration example
 - Configure HGCalRegion to offload electrons, positrons and gammas
 - ▶ Load *HepMC3* file with minimum bias events
 - Integrate G4HepEm in CMSSW builds, usable in an optional physics list
- Particularly challenging due to the large number of channels, so sparsity needs to be used
- Other challenges: requesting GPU resources and handling CPU-GPU exchanges in CMSSW
- ATLAS: typical "try out and adapt to my framework path", see next
- LHCb: initial discussions and an integration project started
 - Discussed the possibility to stop particles entering LHCb EMCAL and run AdePT via Gaussino outside the Geant4 simulation step

Trying out AdePT

- Forked AdePT & modified example14(17)
 - Taking a test beam setup geometry GDML
 - Scintillator as active element
 - Modifying BasicScoring.cu
 - Adapting to specific Geant4 scoring code
 - Scanning with electron gun tilted along Y axis
 - Getting same results + speedup GPU vs. CPU
 - Main challenge: adapting G4Step-based scoring
 - Take-away & next steps
 - "Ideal environment to build a sensitive detector" (working on GPU), "a couple of days effort to have something running"
 - More complex scoring (e.g. Birk's law on device)
 - How to avoid code duplication CPU/GPU?
 - Thinking about integration with *FullSimLight*



Outlook

A challenging project, evolving through a second phase

- Two R&D projects, AdePT and Celeritas, collaborating and working on alternative strategies to tackle simulation on GPU
- A first phase completed, answering most of the initial R&D questions
 - We can now run complete EM shower simulation on GPU, both standalone and integrated with Geant4
- Efficiency bottlenecks identified
 - New VecGeom project on GPU-friendly geometry surface modeling
- Main work focused on adapting the workflow to integrate with experiments
 - Working with experiments on specific challenges
 - Framework integration, sensitive detector code requirements
 - A required step for validating GPUs as accelerating alternative for HEP simulation



At a glance: physics



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- G4HepEm: GPU-friendly compact rewrite of EM processes for HEP
 - Covers the <u>complete physics</u> for e⁻, e⁺ and γ particle transport
- Design of library very supportive for heterogeneous simulations
 - Stateless interfaces working on both CPU and GPU
 - Data: physics tables and other data structures relying on Geant4, but standalone after being copied to GPU
 - Verified against Geant4 standalone
 - At ‰ level in the sampling calorimeter test case



At a glance: geometry

Relying on the builtin VecGeom CUDA support

- Identical object model for CPU and GPU, non-specialized for the GPU use case
- CUDA-specific, non-portable
- Improved gradually the GPU support
 - Developed index-based navigation state handling, single-precision support, faster GPU init
 - Moving from a simple non-optimized to a more efficient **BVH navigator**
 - Adopting modern CMake GPU support

The current geometry approach is a major GPU bottleneck

- Strong motivation to develop a surface model for GPU support
 - Portable less complex & less divergent code, creating a surface-based view on device
 - Our major work <u>item</u> (see: <u>geometry presentation</u>)

Kernel Launch Configurations

1024 Threads / SM

- 4 schedulers x 8 warps/scheduler x 32 threads/warp
- 65536 Registers / SM
 - 4 register files x 16384 registers
 - 1 float = 1 register, 1 double = 2 registers
- 96 KB L1 Data Cache / Shared Memory
- Theoretical Occupancy (-maxregcount or __launch_bounds__)
 - 256 regs/thread (256 threads, 8 warps) \Rightarrow 25%
 - 160 regs/thread (320 threads, 10 warps) \Rightarrow 38%
 - 128 regs/thread (512 threads, 16 warps) \Rightarrow 50%
 - 96 regs/thread (640 threads, 20 warps) \Rightarrow 63%
 - 80 regs/thread (768 threads, 24 warps) \Rightarrow 75%
 - 64 regs/thread (1024 threads, 32 warps) ⇒ 100%





Higher parallelism

Faster Threads

Run Time Characteristics

- putting more work per batch does more work in the same #iterations (steps)
 - limited by available memory AND available tracks
- hints already to using strategies to fill the gaps
 - e.g. more CPU threads doing concurrent events
- performance: sweet spot at about 50% occupancy (register-hungry code)
- 36 SM GPU ≈32 CPU cores in HT mode (64 threads): a consumer card can double the throughput of a dual socket machine





Relative Performance per SM



GPU Throughput (RTX 2070)





CPU vs GPU Performance



AMD Ryzen 3950X (16 cores, 32 threads, 3.5-4.7GHz), AMD EPYC 7282 (16 cores, 32 threads, 2.8-3.2GHz)

Case Study: Thread Divergence



+640ms +645ms +650ms +655ms +660ms +665ms +670ms +675ms 2s - 35ms CPU (4) - CUDA HW (0000:00:08.0 -TransportElectrons(Track *, const adept::MParray *, Se. TransportGammas(Track *.const adept::MParray [All Streams] ransportPositrons. +315ms 25 -+290ms +295ms +300ms +305ms +310ms +320ms +325ms +330ms CPU (4) CUDA HW (0000:00:08.0 - T TransportElectrons(Track *, const adept::MPa... TransportGammas(Track void.. TransportElectrons Transpon?o. void C.. End of [All Streams] /oid step

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Problem: Threads in transport kernels diverge because of diverging interactions \rightarrow 13 / 32 threads active on average

Here: Split off interaction computations from cross-section and geometry kernels (one kernel for pair creation, one for ionisation, ...)

Result: 17 / 32 threads active for physics + geo 29 / 32 threads active for Bremsstr. Run time: $6.4 \text{ s} \rightarrow 5.5 \text{ s}$

Conclusion: Keeping threads coherent is key for detector simulation Generally difficult; stochastic processes



Hooking user code

AdePT

- AdePT advanced <u>examples</u> provide a mechanism to implement Geant4-like sensitive detector code
 - Scoring type to be implemented and aliased as *AdeptScoring*
 - Transport kernels templated on this type, calling back directly on GPU
- Fairly straightforward interfaces
 - GPU data management (hits) allocation and cleanup, copy to host
 - A very simple atomic calorimeter cell accumulator as example
 - *AdeptScoring::Score* method to intercept current step as in Geant4
- One of the main challenges for experiment code integration
 - Cannot be identical with Geant4 code (different types)
 - Working directly with experiments to understand realistic cases

