



Machine Learning Tools for the CMS Tracker Data Quality Monitoring and Certification

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Outline



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- A brief introduction to CMS Data Quality Monitoring (DQM) and Data Certification (DC)
 - Online and Offline DQM
 - Challenges
- Machine Learning Tools for DQM/DC
 - Taking on the challenges with anomaly detection
 - Dedicated dataset
 - Data exploration and integration
 - ML studies
- Prospects and Summary





BROWN CMS Data Quality Monitoring and Certification

- Ultimate goal: highest data quality for CMS publications
- Shifters, on-call personnel and experts scrutinize hundreds of histograms for each of the CMS subsystems to provide data quality (sub)flag(s)



CMS Integrated Luminosity, pp, $\sqrt{s} = 13$ TeV

- Typical run lasts several hours and made of several hundreds of lumi-sections (LS), the atomic unit of data-taking, lasting about 23 seconds
- For offline data certification, DQM histograms harvested with 'run' granularity
- Beam and detector data sources complement the information from DQM histograms
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 3 CHEP2023, Track 3 Offline Computing, May 9th 2023





- Two offline data reconstruction tiers:
 - Express (available within a few hours) used for calibrations

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• PromptReco (available within 48hrs) used for physics analysis





CMS DQM and DC processes



- Online DQM: monitor detector performance live to ensure efficient data collection
 - Reduced set of histograms, central shifters, real-time reaction time
- **Offline DQM**: data certification to ensure good quality for physics analysis
 - Full set of histograms
 - Each subsystem handles certification for their flag
 - Additional sources of data (beam and detector status, calibrations)
- Challenges:
 - Large number of people involved
 - Large number of histograms and other data to inspect and correlate
 - Human error
 - Time granularity
 - Changing beam and detector(s) conditions
 - Anomalies may be unexpected







Machine Learning for DQM/DC



- Explore the use of ML for anomaly detection, automating part of the process
 - Tools to facilitate certification tasks for shifters and experts
 - Automate the evaluation of DQM histograms
 - Alarms/flags
 - Provide outputs robust against changing conditions and low statistics
 - Enable scaling to larger number of histograms
 - Standardize certification easing human interface issues
 - Leverage other data sources integration and anomaly detection techniques
 - Provide algorithmic **insight** to experts
- Basic anomaly detection idea:
 - "Learn" how to reconstruct an histogram (or set of them)
 - "Reconstruct" the input histogram (inference)
 - Use Mean Squared Error (MSE) to measure deviation (anomaly) between the reconstructed and the input histogram
 - Flag anomalous LSs







Machine Learning for DQM/DC



• Offline dataset:

- Run 2 data (specifically **2017** and 2018, after the Pixel Phase-1 upgrade installation)
- PromptReco (ReReco) datasets for **Pixel**, Strip, Tracking, Muon and JetMET certification
- Subset of histograms (~100)
- Highest time granularity DQM harvesting: per lumi-section (LS), ~23 seconds
- Several studies were conducted on the tracker dataset:
 - Data exploration and integration at the LS level
 - Principal Component Analysis (PCA), t-distributed Stochastic Neighbor Embedding (t-SNE), Convolutional Neural Networks (CNNs), 1D AutoEncoders, 1D Non-negative Matrix Factorization (NMF), 2D Residual Network (ResNet) AutoEncoders
- The following featured studies are all based on **pixel (Phase-I)** [1] tracker inputs











Data Exploration and Integration



Inputs:

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- CSV files with **DQM histograms** bin contents, run number/LS number
- Data integration of **additional sources** •
 - Luminosity, pileup, trigger rate, beam conditions •
 - Certification information •
 - Official certification flags (**AND** of all subsystems/histos, perLS)
 - Tracker certification information (reference runs, problem classification)
- Common tools to streamline access to data, facilitate development and data exploration with Jupyter . notebooks (SWAN+EOS at CERN)
- Caveats about training datasets (statistics, homogeneity) ٠
 - Lack of **histogram-level** labelled data: ٠
 - Preference for semi-supervised/unsupervised approach
 - Resampling tool developed to address scarcity of data flagged "bad"
 - Use certification information to extract "bad" data •
 - Key for both unsupervised and supervised approaches
- Standardize:
 - Training and testing of algorithms ٠
 - Handling of inputs (data cleaning) ٠
 - Anomaly definition and reporting ٠
- MSE of the given input histogram with a reference run used as ML performance benchmark Gabriele Benelli, Brown University

Pixel 1D Histograms AutoEncoder



- Input histograms: cluster charge in barrel and forward pixel layers [2]
- AutoEncoders trained separately on each histogram type:
 - One hidden layer with half as many nodes as input bins $(100 \rightarrow 50)$
 - Training on all lumi-sections from 2017, with filters (HV on, minimal statistics)



- Changing detector/beam conditions produce a **spectrum of shape variations**
- Anomalous lumi-sections **input** histograms get badly **reconstructed** resulting in large MSE
- Anomalies may affect individual histograms, in this case an on-going HV scan for pixel forward disk +1, and at different lumi-sections during a given run
- Multiple histograms MSEs may be combined to flag anomalies

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Pixel 1D Histograms NMF

- Input histogram: cluster charge in barrel pixel layer 2 [2]
- NMF [4] algorithm trained using all LSs from reference run used for human certification:
 - 6-component model
 - Two individual LSs are reconstructed as a linear combination of the 6 components



- Anomalous lumi-sections **input histograms** cannot be **reconstructed** satisfactorily resulting in large MSE (note the factor 100 scale difference in the lower MSE panels)
- The anomalous LS in the right plot is due to a pixel timing scan affecting barrel layer 2
- NMF component contribution provides extra insight that could be used by experts and in further classification of anomalies



Pixel 2D Histograms ResNet AutoEncoder



- Input histogram: **2D pixel occupancy in barrel pixel layer 1** [2]
- ResNet [5] used as AutoEncoder, trained on 2017 data from same data-taking era with statistics preselection:



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- 200x140 input, 4 encoding blocks with increasing number of filters, hidden layer with 1000 nodes, 4 decoding blocks with decreasing number of filters, 200x140 output
- Pixel barrel layer 1 occupancy for 3 different lumi-sections (one per row) in the same run
- First column: input histograms
- Second column: ResNet reconstructed histograms
- Third column: MSE between input and reconstructed (darker red for larger MSE)
- ResNet not able to reconstruct anomalous LS input histogram, resulting in large MSE
- Anomaly due to transient lower trigger rate





ML for DC method illustration



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ML/statistical methods comparison





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- Nine cluster charge (BPIX L2, L3, L4, FPIX+D1,D2,D3, FPIX-D1,D2,D3) perLS 1-D histograms input [3]
- Moments: 1st and 2nd moments w.r.t. average and standard deviation of training dataset
- Landau fit: MSE between input and best fit
- Templates: minimum MSE between input and a set of reference histograms
- NMF: MSE between input and NMF reconstruction
- AutoEncoder: MSE between input and AutoEncoder reconstruction
- Diagonal plots: global score for good test set and anomalous runs for all models
- Off-diagonal plots: correlations between models (one LS per dot, scores normalized between 0-1)
 - Sensitivity vs. fake rate can be tuned and optimized





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CMS Preliminary

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- Operational performance example
- A variation to the ML for DC method illustrated above (same input histograms), • reflecting the situation during regular data-taking [3]:
 - Model is updated with dedicated training on LSes immediately preceding the run whose LSes are under consideration

2017 (13 TeV)

- Fraction of flagged lumisections 6.0 0 7.0 0 8.0 0 7.0 0 8.0 0 7.0 0 8.0 0 7.0 0 8.0 0 7.0 0 8.0 0 7.0 0 8.0 0 7.0 0 8.0 0 7.0 0 8.0 0 7.0 0 8.0 0 7.0 0 8.0 0 7.0 0 8.0 0 7.0 0 8.0 0 7.0 0 7.0 0 8.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0 7.0 0.0 Anomalous run Partly anomalous run Low number of entries 297498 300105 300370 301046 302019 302342 304120 306029. 297292 297672 299327 301475 302554 305180 305351 297114 300517 304626 306419 Application run
- Fraction of flagged LSs is low for good runs
 - **Anomalous runs** typically are runs with HV bias or timing scans (most of the time affecting globally the whole, at times only partially)
 - Low luminosity or low trigger rate runs typically results in flagged LSs

- First runs in a fill not included in the study above, •
- Studies conducted on exploiting reference runs (based on instantaneous luminosity, beams and detector conditions) to get homogeneous training datasets



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Prospects and Summary



- Very promising studies for ML tools to assist data quality monitoring and certification shifters and experts
- ML may help address some of the challenges that make DQM and DC such a labour intensive process
- Several ongoing efforts:
 - Streamline access to various sources of data
 - Data exploration and data cleaning
 - Facilitate ML training and testing
 - Streamline metrics for comparisons and optimization
 - Extend studies to other inputs
 - Extend from semi-supervised to fully supervised approaches (from anomaly detection to classification)
 - Integrate some of these tools as aids to the certification team and later as aids to online data quality monitoring
- Prospects to deploy some of these tools together with DQM perLS harvesting in the ongoing Run3 to improve DC and DQM







References



[1] CMS Collaboration, "The CMS Phase-1 Pixel Detector Upgrade",

CERN-CMS-NOTE-2020-005, https://cds.cern.ch/record/2745805

[2] CMS Collaboration, "**Tracker DQM Machine Learning studies for** data certification", CERN-CMS-DP-2021-034, <u>https://cds.cern.ch/</u> record/2799472

[3] CMS Collaboration, "**Prospects for computer-assisted data quality** monitoring at the CMS pixel detector", CERN-CMS-DP-2022-013, http://cds.cern.ch/record/2812026

[4] Lee, D.D. and Seung, H.S., "Algorithms for Non-negative Matrix Factorization", <u>Adv. Neural Inf. Process. Syst.13556-562 (2000)</u>

[5] K. He, X. Zhang, S. Ren, and J. Sun, "Deep Residual Learning for Image Recognition", <u>https://arxiv.org/abs/1512.03385</u>









CMS Run Registry



Run Registry	ONLINE	OFFLINE	ML	JSON PORT	AL LOG																							Ga	abriele Be	e nelli Log out
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Show workspace state columns









- Input 1-D histograms for ML/ Statistical methods comparison
- Example anomalous LS plots due to beam dump

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