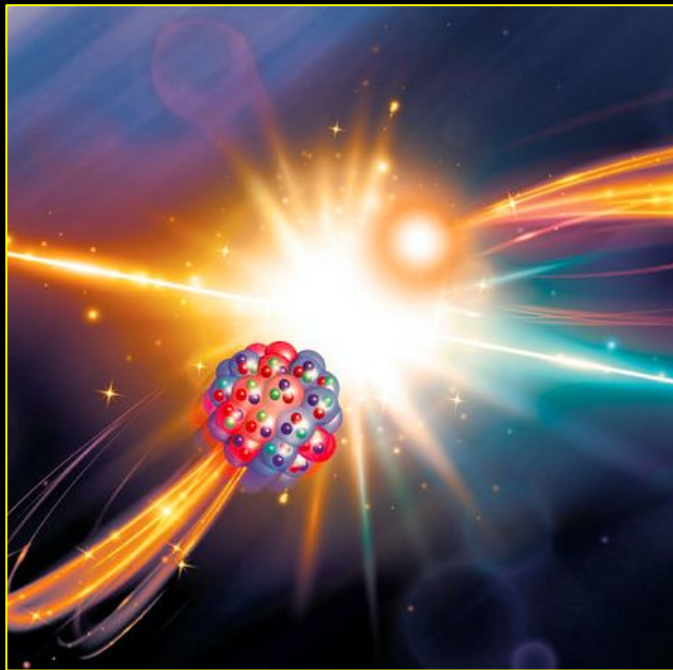


AI-optimized Detector Design



C. Fanelli



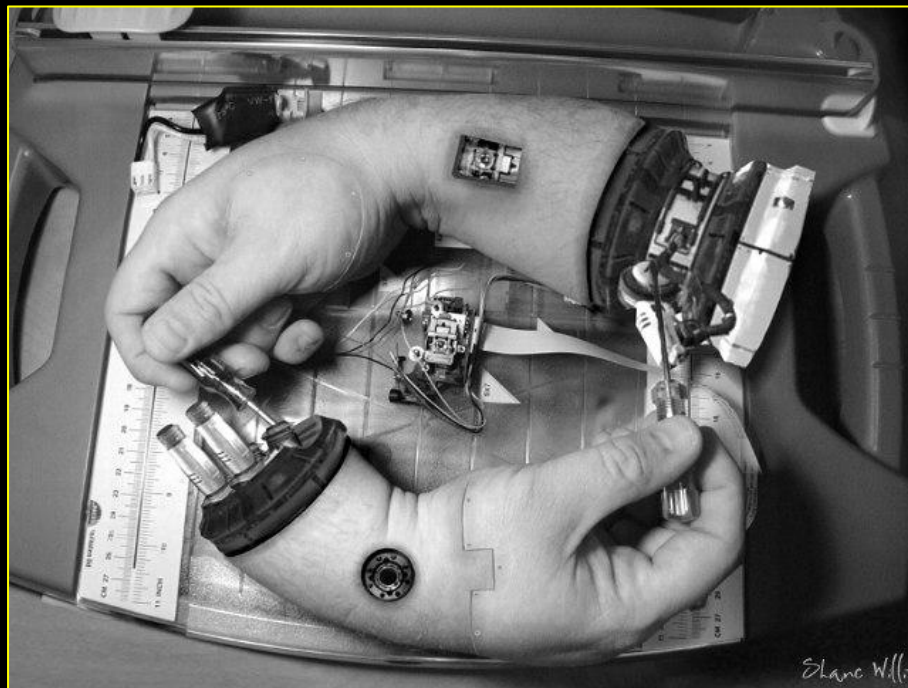
AI-optimized detector design for the future

Electron-Ion Collider: the dual-radiator RICH case

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arXiv:1911.05797v1 [physics.ins-det] 13 Nov 2019

Automated Applications



AI techniques that can optimize the design of complex, large scale experiments can revolutionize the way experimental nuclear and particle physics is done

Electron Ion Collider



Url: energy.gov/EIC

Department of Energy

U.S. Department of Energy Selects Brookhaven National Laboratory to Host Major New Nuclear Physics Facility

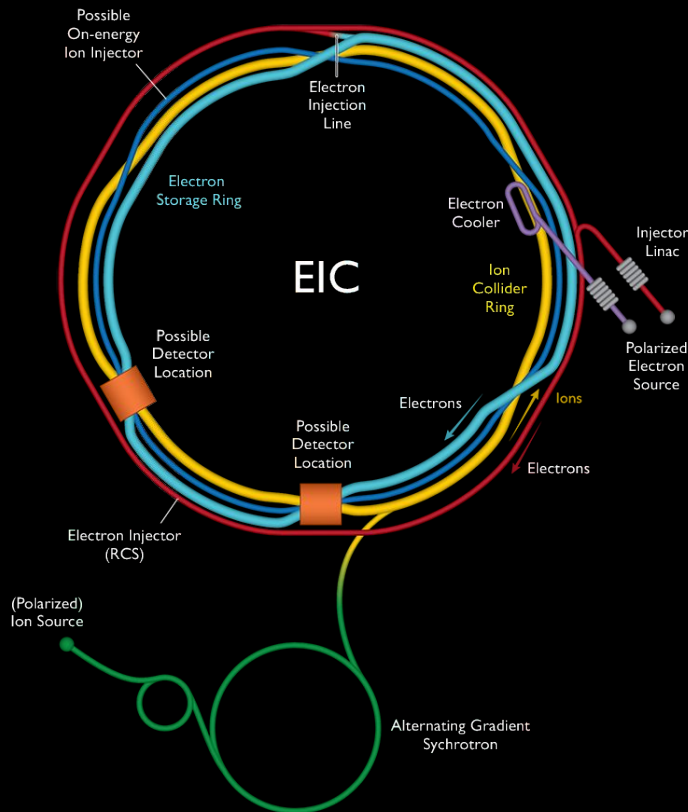
JANUARY 9, 2020

[Home](#) » U.S. Department of Energy Selects Brookhaven National Laboratory to Host Major New Nuclear Physics Facility

WASHINGTON, D.C. – Today, the **U.S. Department of Energy (DOE)** announced the selection of Brookhaven National Laboratory in Upton, NY, as the site for a planned major new nuclear physics research facility.

The Electron Ion Collider (EIC), to be designed and constructed over ten years at an estimated cost between **\$1.6 and \$2.6 billion**, will smash electrons into protons and heavier atomic nuclei in an effort to penetrate the mysteries of the “strong force” that binds the atomic nucleus together.

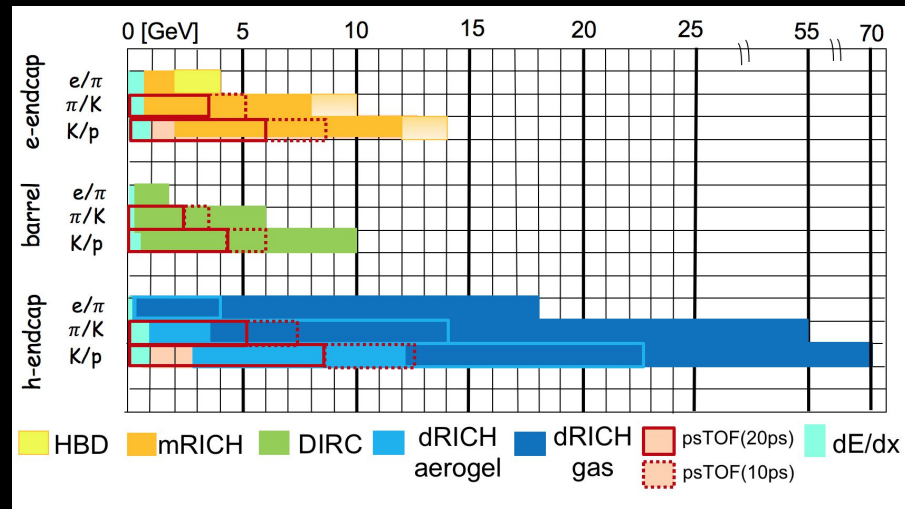
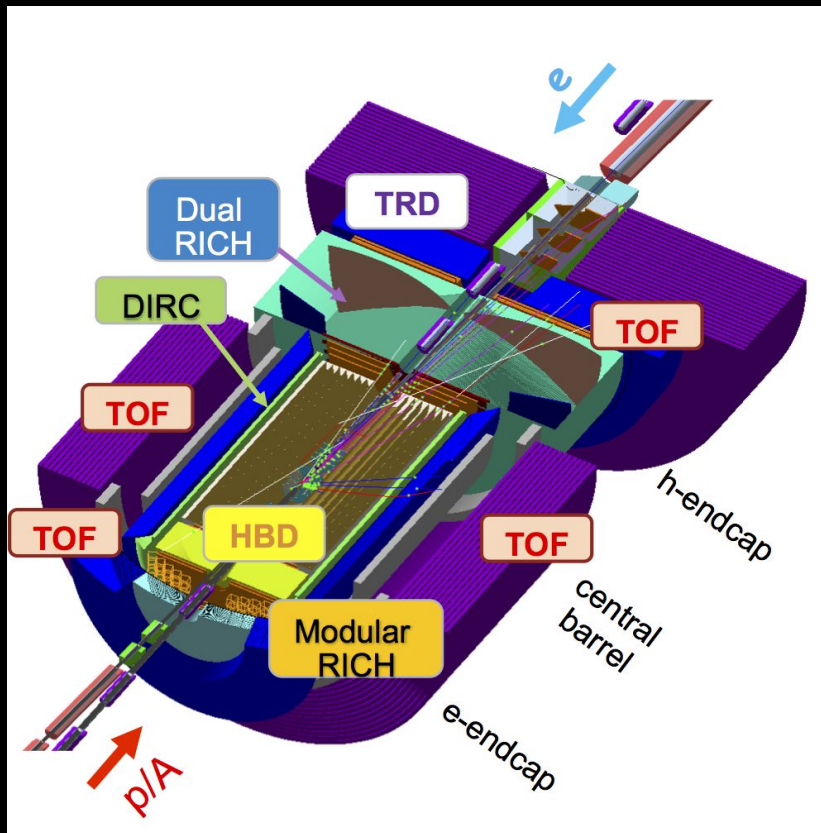
A machine for delving deeper than ever before
into the building blocks of matter



EIC will be the only electron-nucleus collider operating in the world and will be built in partnership with JLab.

It will consist of two intersecting accelerators, one producing an intense beam of electrons, the other a high-energy beam of protons or heavier atomic nuclei

Detector Concepts



Different detector concepts...

h-endcap: a dual-radiator RICH needed to cover continuously momenta up to 50 GeV/c

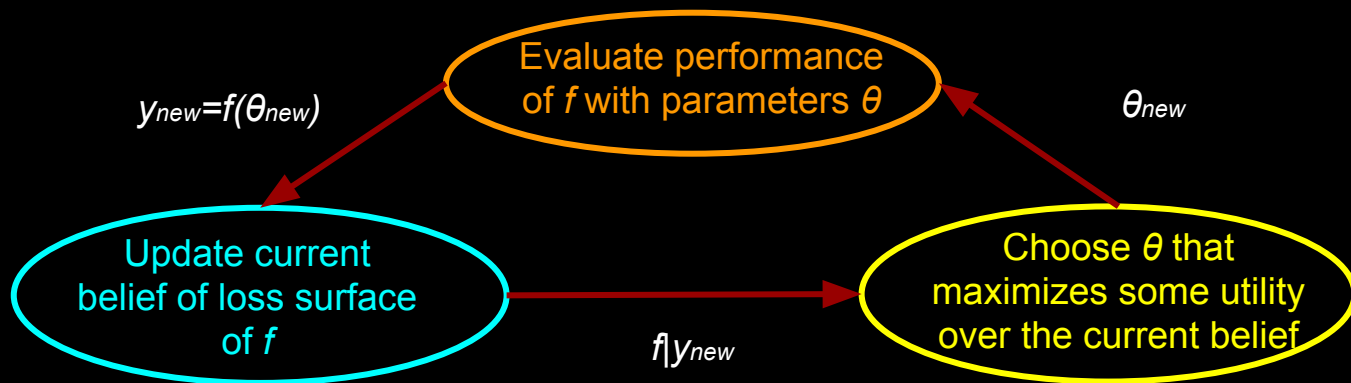
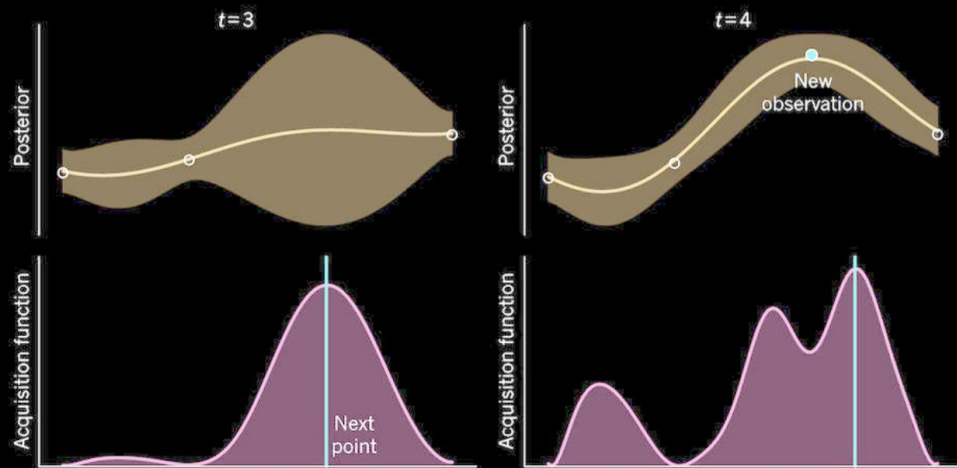
e-endcap: a small lens focused aerogel RICH for momenta up to 10 GeV/c

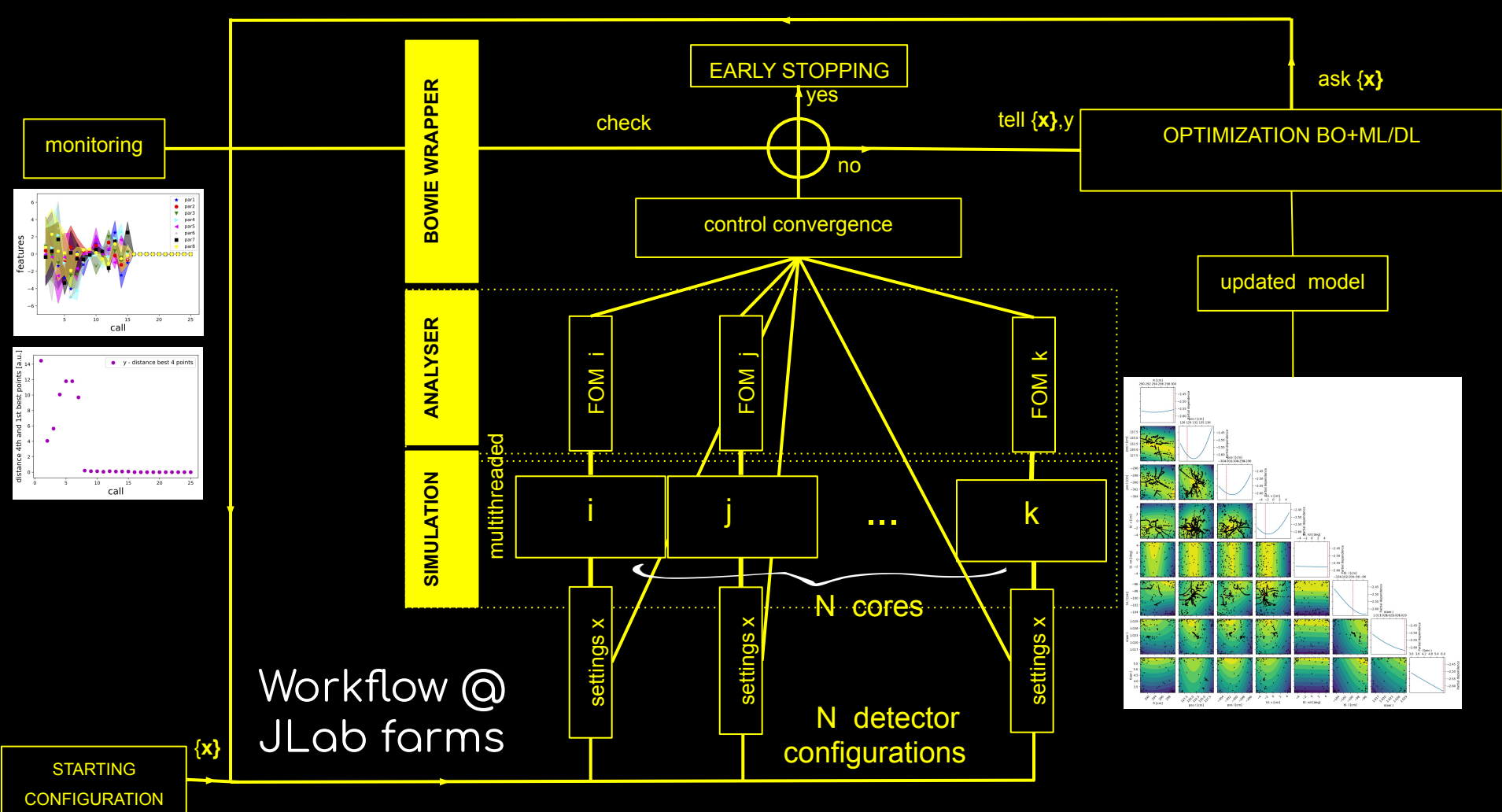
barrel: DIRC provide a compact and cost effective way to cover momenta up to 6 GeV/c

TOF (and or dE/dx in the TPC) can cover the low momenta region

Bayesian Optimization

- BO is a strategy developed for global optimization.
- After gathering evaluations BO builds a posterior distribution used to construct an **acquisition function**.
- This cheap function determines what is **next query point**.





Case Study: dRICH

- 6 Identical open sectors (petals)
- Optical sensor elements:
8500 cm²/sector, 3 mm pixel
- Large focusing mirror

aerogel (4 cm, $n(400\text{ nm})$ 1.02)
+ 3 mm acrylic filter
+ gas (1.6 m, $n_{\text{C}_2\text{F}_6}$ 1.0008)

- Continuous momentum coverage.
Simple geometry/optics,
cost effective.
- Legacy design from [EICUG2017](#)

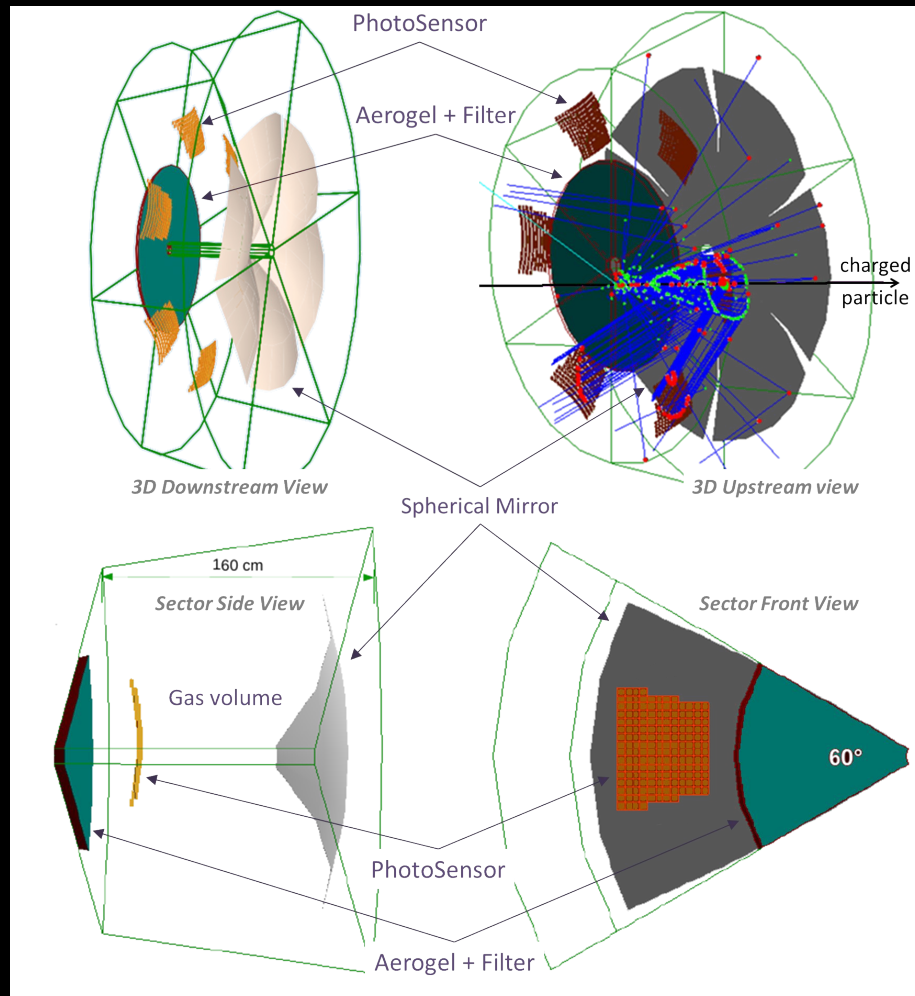


Figure of Merit

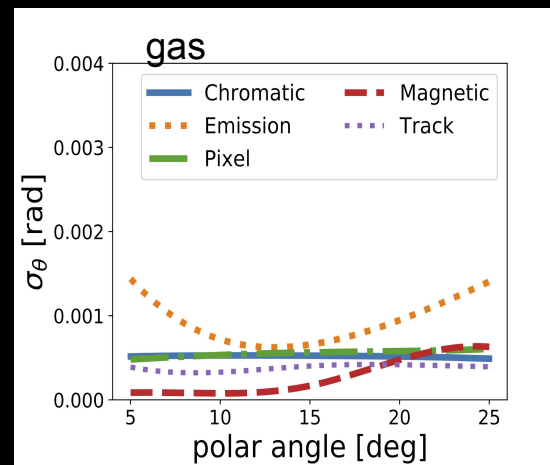
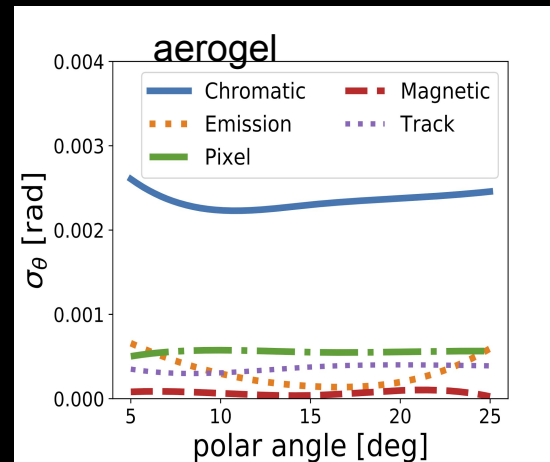
$$N\sigma = \frac{||\langle\theta_K\rangle - \langle\theta_\pi\rangle||\sqrt{N_\gamma}}{\sigma_\theta^{1p.e.}}$$

$$N_\gamma = (N_\gamma^\pi + N_\gamma^K)/2$$

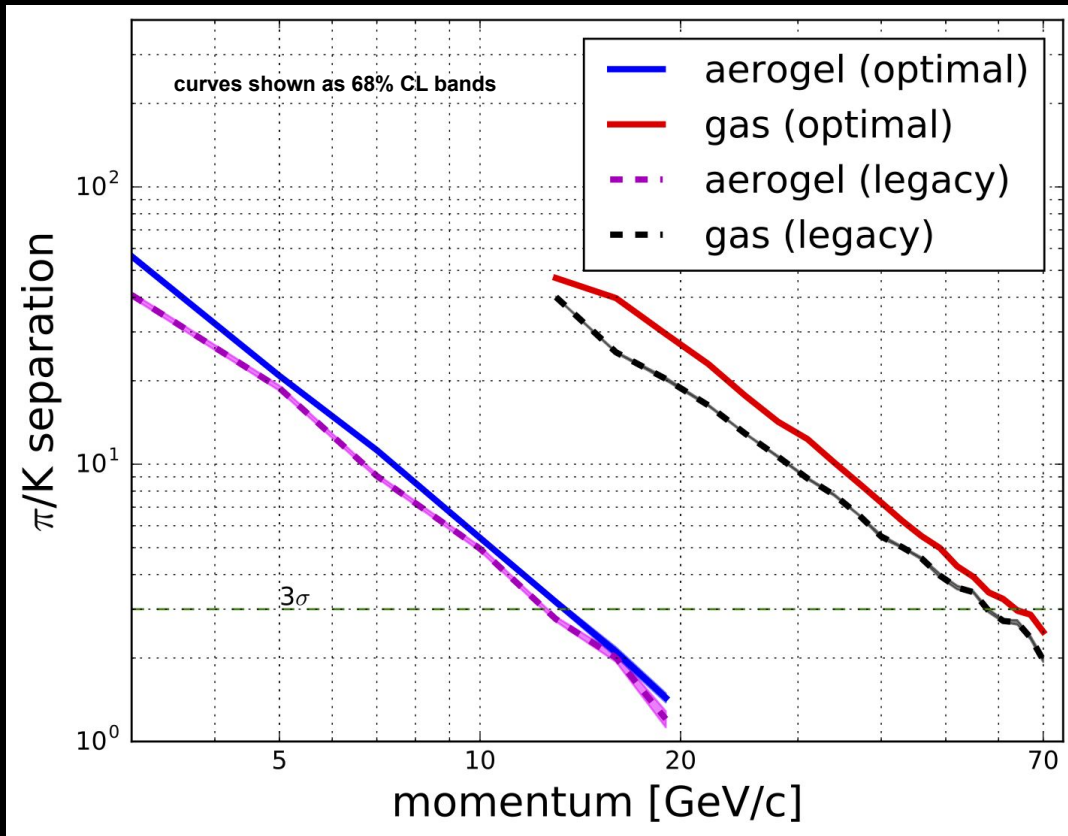
$$h = 2 \cdot \left[\frac{1}{(N\sigma)|_1} + \frac{1}{(N\sigma)|_2} \right]^{-1}$$

@ $p_1 = 14$ GeV/c (aerogel) and $p_2 = 60$ GeV/c (gas)

considering the two parts disentangled



dRICH Performance @ the optimal design point

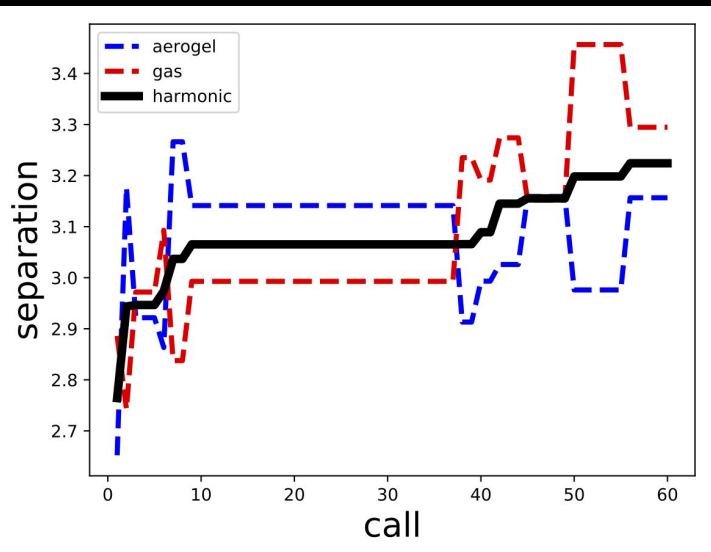


- Statistically significant Improvement in both parts.
- In particular in the gas region where the 5σ threshold shifted from 43 to 50 GeV/c and the 3σ one extended up to
- Notice that before this study we did not know “how well” the legacy design was performing.

CF et al. AI-optimized detector design for the future EIC *arXiv:1911.05797* (2019)

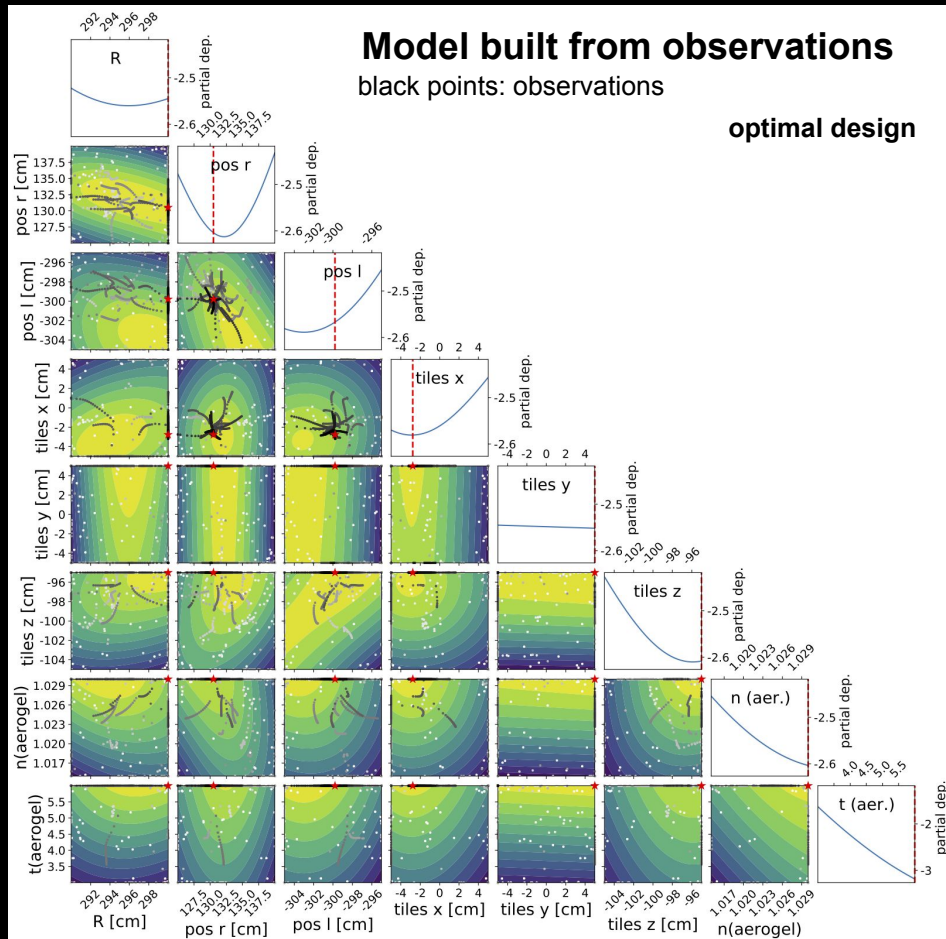
The Model and the Optimized FoM

$$N\sigma = \frac{\|\langle\theta_K\rangle - \langle\theta_\pi\rangle\| \sqrt{N_\gamma}}{\sigma_\theta^{1p.e.}}$$

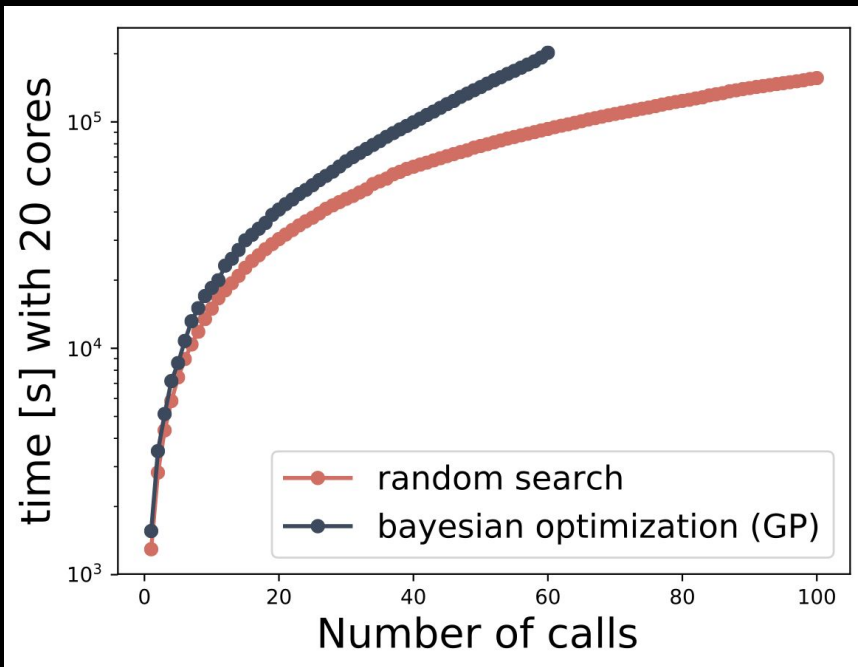
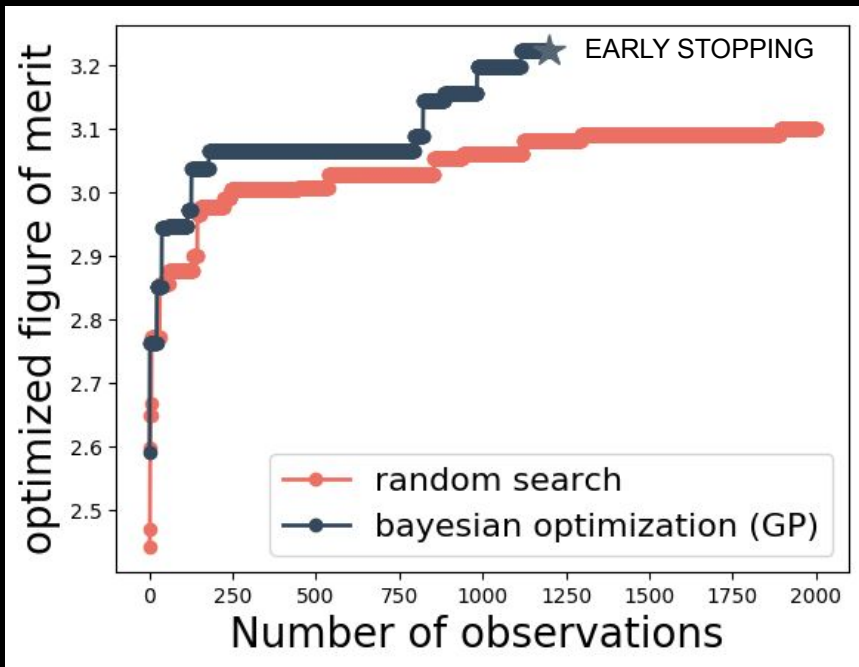


Model built from observations
black points: observations

optimal design

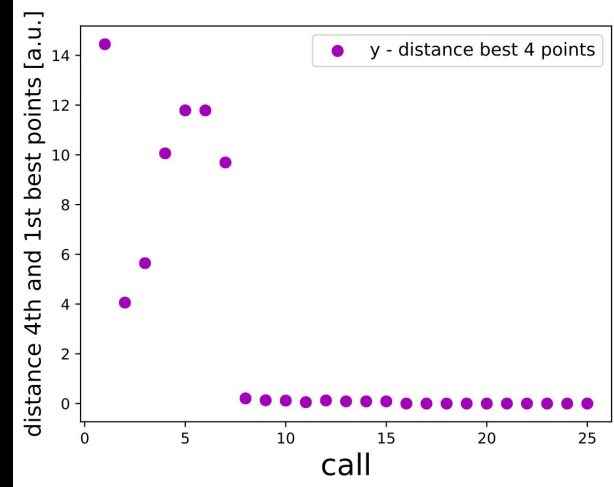
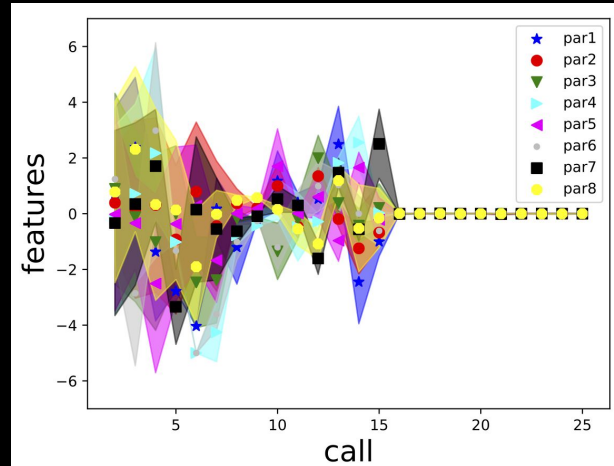


Comparison with Random Search



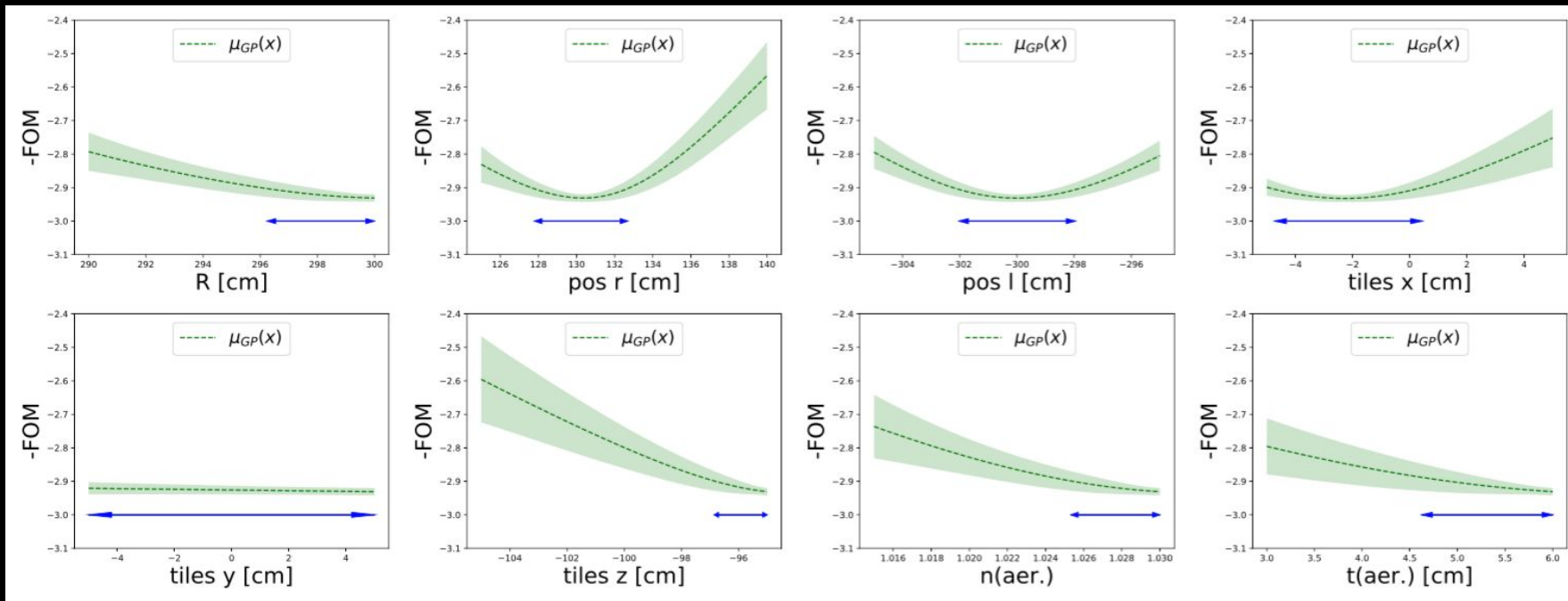
Convergence Criteria

- We defined a set of conditions to ensure convergence.
- These correspond to the logic AND of booleans on each feature and on the variation of the figure of merit.
- They are built on standardized Z and Fisher statistics.
- Pre-processing of data required to remove outliers.



Tolerance Regions

- BO provides a model of how the FoM depends on the parameters, hence it is possible to use the posterior to define a tolerance on the parameters (regions ensuring improved PID, see previous slide).



- Larger than the construction tolerances on each parameter.
Notice a small lateral shift of the tiles has negligible impact on the PID capability.

Vision Slide

- “AI techniques that can optimize the design of complex, large scale experiments can revolutionize the way experimental nuclear and particle physics is done”

- AI for detector design
- Intelligent detection systems able to self-calibrate/align
- etc

Bayesian
Optimization

DL-boosted



Evolutionary
autoML

Meta-learning

Reinforcement
Learning

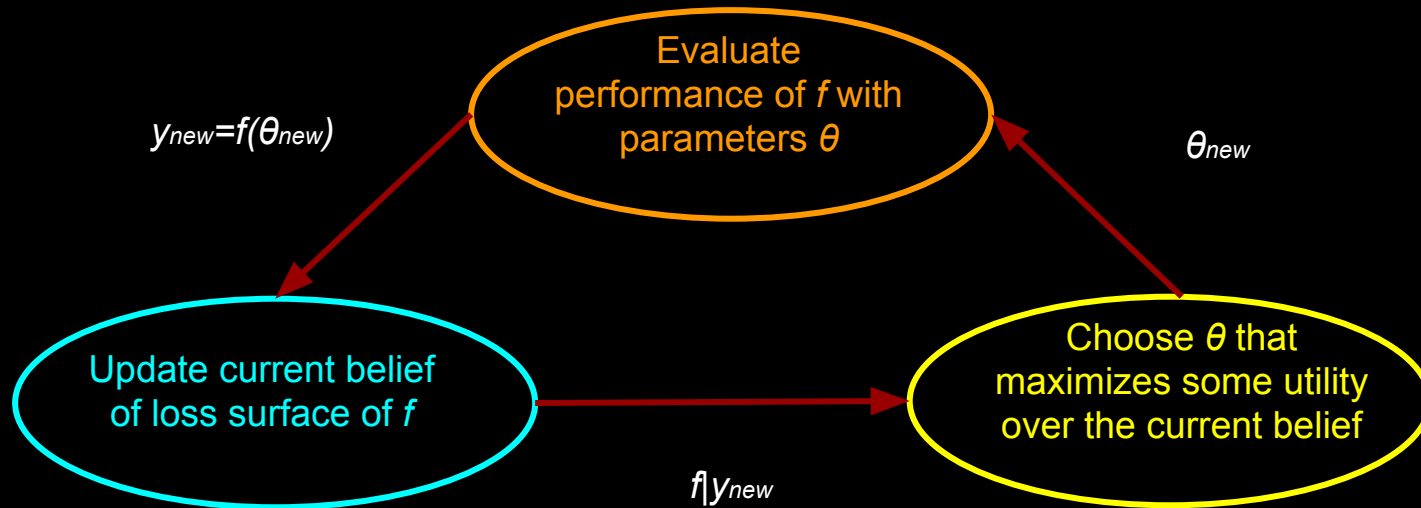
Summary

- Presented AI-driven detector design for the case of the dual-RICH in EIC.
- Key-features: automated, highly-parallelized, self-consistent.
- These same tools can be extended and applied to other detectors and possibly to the entire experiment, making the EIC R&D one of the first programs to systematically exploit AI in the detector-design phase.
- AI can help coordinate the efforts of different groups developing different sub-detectors towards the final global detector design.

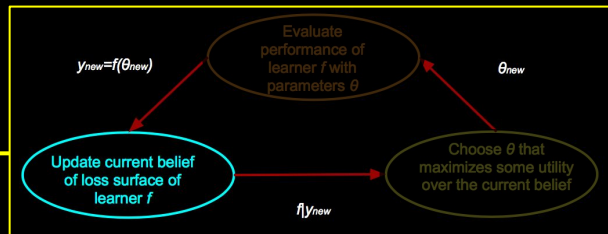
BACKUP

Bayesian Optimization

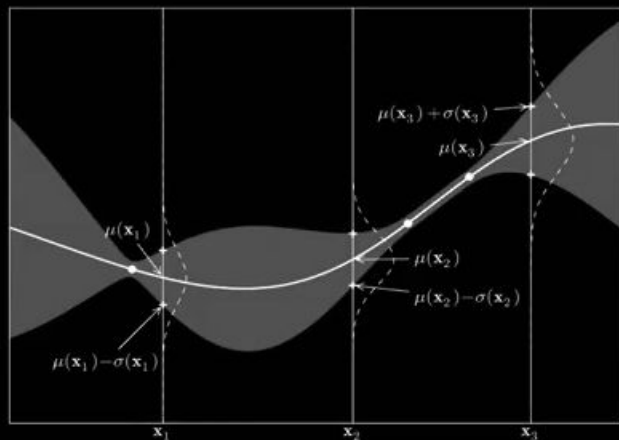
It basically consists of three steps



Update

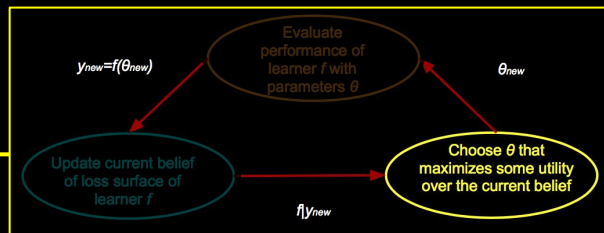


- GPs are the generalization of a Gaussian distribution to a distribution over functions, instead of random variables.
- GP is completely specified by its mean function and covariance function.

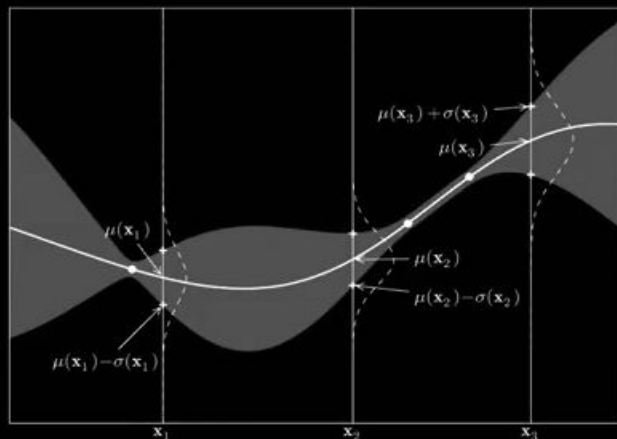


- How should I read this?
 - **Solid line:** function we are trying to min/max
 - **Shaded region:** probability model (we know the actual points already evaluated but we are more uncertain in regions where we haven't).
 - In every point a normal distribution of the potential performance function

Next points



- Where am I going to sample next?
- We use utility functions called acquisition functions (formalize what is the best guess)
- Expected improvements is one example: find next point that improves the performance the most.



EXPLOITATION
Sample a θ with higher value than current one

EXPLORATION
Sample a point where uncertainty is high

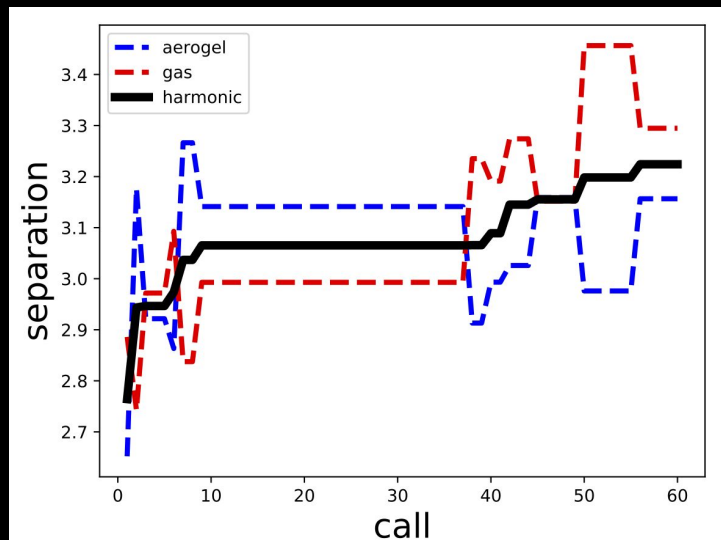
want to maximize

$$EI(\theta) = \begin{cases} (\mu(\theta) - f(\hat{\theta})) \Phi(Z) + \sigma(\theta) \phi(Z), & \sigma(\theta) > 0 \\ 0, & \sigma(\theta) = 0 \end{cases}$$

best value we found so far

$$Z = \frac{\mu(\theta) - f(\hat{\theta})}{\sigma(\theta)}$$

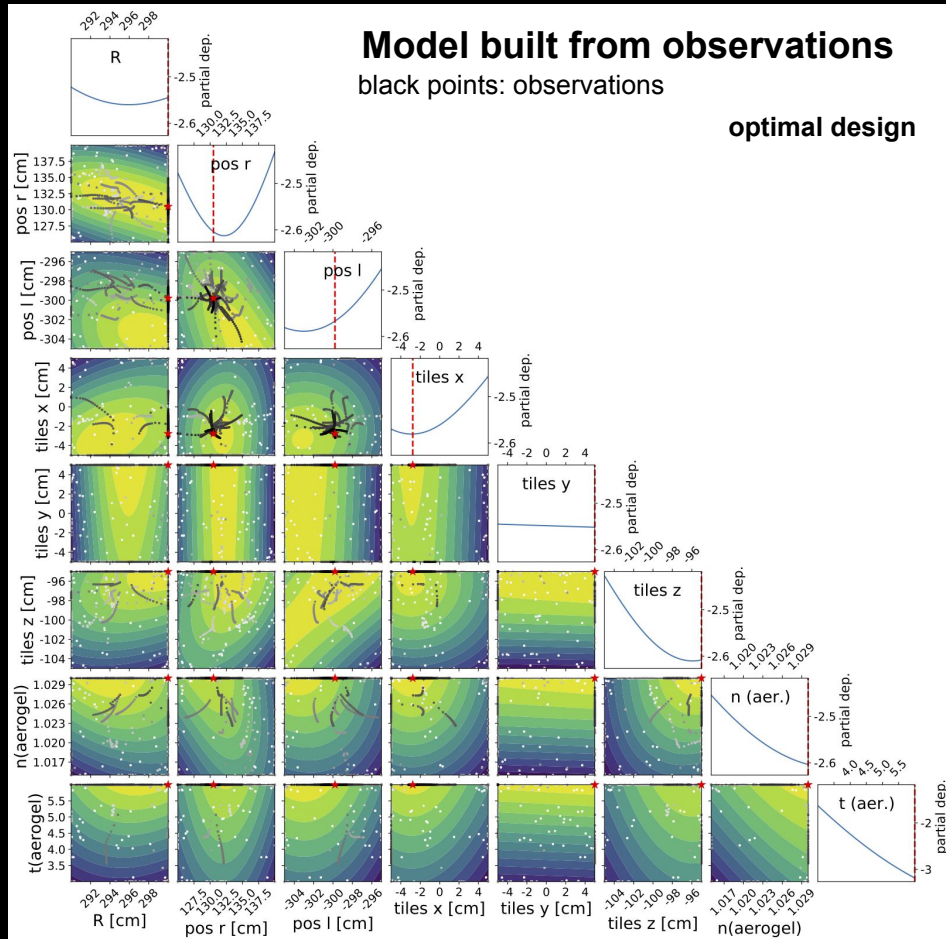
The Model and the Optimized FoM



	FoM (h)	$(N\sigma)$ @ 14 GeV/c	$(N\sigma)$ @ 60 GeV/c
BO	3.23	3.16	3.30
legacy	2.9	3.0	2.8

Model built from observations
black points: observations

optimal design

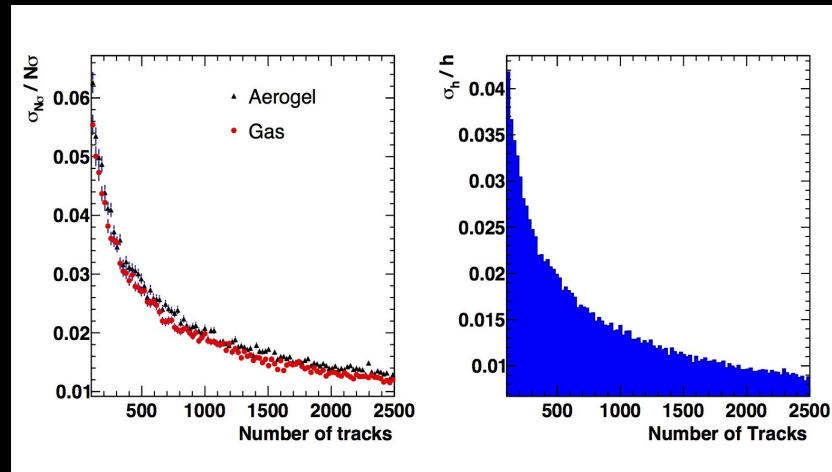
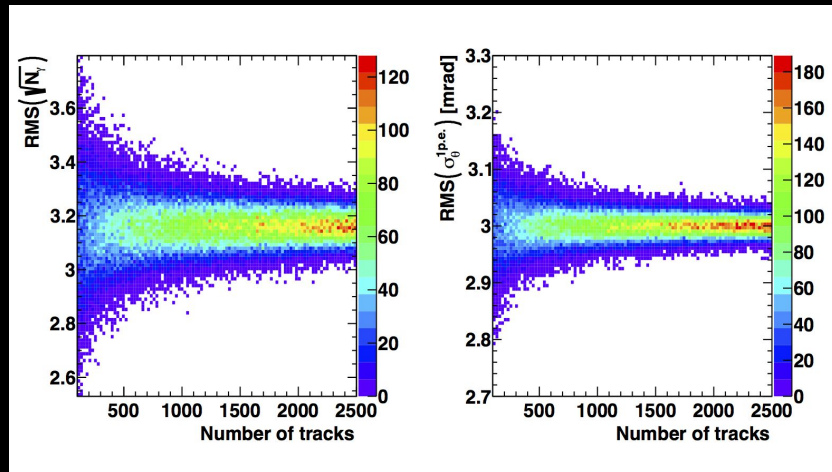


Noise Studies

- Dedicated studies to characterize the noise as this is an optimization of a noisy function
- We choose N tracks = 400 based on the studies on noise to minimize as much as possible computing time during simulation.

symbol	description	value
T	maximum number of calls	100
M	points generated in parallel (GP)	20
N	pions (and kaons) per sample	200
kappa	controls variance in predicted values	1.96
xi	controls improvement over previous best values	0.01
noise	expected noise (relative)	2.5%

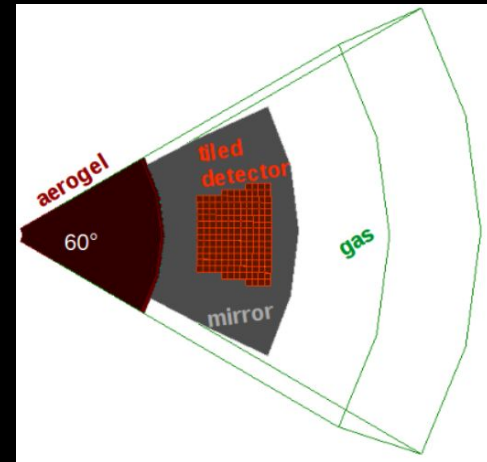
(list of hyperparameters)



Construction Constraints

The idea is that we have a bunch of parameters to optimize that characterize the detector design. We know from previous studies their ranges and the construction tolerances.

parameter	description	range [units]	tolerance [units]
R	mirror radius	[290,300] [cm]	100 [μm]
pos r	radial position of mirror center	[125,140] [cm]	100 [μm]
pos l	longitudinal position of mirror center	[-305,-295] [cm]	100 [μm]
tiles x	shift along x of tiles center	[-5,5] [cm]	100 [μm]
tiles y	shift along y of tiles center	[-5,5] [cm]	100 [μm]
tiles z	shift along z of tiles center	[-105,-95] [cm]	100 [μm]
n _{aerogel}	aerogel refractive index	[1.015,1.030]	0.2%
t _{aerogel}	aerogel thickness	[3.0,6.0] [cm]	1 [mm]



Ranges depend mainly on mechanical constraints and optics requirements.

These requirements can change in the next future based on inputs from prototyping.