







Hall D Fast Feedback



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Hall D FFB Overview



- Data from 2 BPMs used to control 2 sets of correctors
 - Locking position at 1 point does not stabilize the trajectory or downstream position, 2 points are needed
 - Element locations are selected based on the optics
- Main goal is to compensate for 60Hz line motion





Based on Halls A & C FFB



FFB Control Algorithm: Lebedev & Dickson circa 1996

- Targets 60Hz line motion and harmonics
- Auto calibration: kick beam, record response and calculate matrix coefficients
- Feedback to 180Hz plus feedforward to 720Hz
- Position and energy correction





Hall D FFB



* There are only 8 fiber inputs so the Cavity BPMs will replace 2 Striplines



Hall D FFB Chassis







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Stripline BPMs

- Used instead of M15 antenna BPMs
 - Easier & more precise manufacturing
 - No hand bending of antennas
 - Better sensitivity
 - 50 ohm devices
- Position calculated as difference-oversum
- Each characterized with Goubau Line BPM Test Stand



26 Striplines IPMBS00 IPMBS01 IPMBS02 IPMBS03 IPMBS04 IPMBE01 IPMBE02 IPMBE03 IPMBE04 IPMBT01 IPMBT02 IPMBT03 **IPM5C00** IPM5C01 **IPM5C02** IPM5C03 IPM5C04 IPM5C05 **IPM5C06 IPM5C07 IPM5C08 IPM5C09** IPM5C10 IPM5C11 IPM5C11B **IPMAD00C**



Stripline Bandwidth vs Resolution







Cavity BPMs

- IPM5C11A at shield wall, IPMAD00 at Goniometer
- Positions go as X/I & Y/I
- Electromagnetic field excited by beam
 - BCM: TM₀₁₀ Mode
 - BPM: TM₁₁₀ Mode
 - Signal disappears at boresight
- Tuning port for centering at 1497MHz
 - Temperature stabilized
- Better sensitivity than Striplines







Active Collimator

- IPC5H01 in Hall D
 Alcove
- Intercepts photon beam
 - Tungsten pincushion wedges
 - Current output
- Difference-oversum used on inner wedges for FFB (region 1)
- Works at low beam currents





Hall D FFB Algorithm

- Correctors up to 1kHz
- Hall A&C FFB @ 10uA
 - Hall D: 5nA to 500nA
 - SEE: 20um @10uA
 - Striplines: 100um @ 330nA/120Hz BW



- Use Cavity BPMs & Active Collimator for lower currents

- Plan A: Hall A&C style feedback and feedforward
 1 Skapa data & DACa (due to bardware limitations in (
 - 1.8ksps data & DACs (due to hardware limitations in A&C)
- Plan B: High bandwidth feedback (no feedforward)
 - Take advantage of 30ksps fiber data and 1MHz DACs
 - Must have low latency and good signal-to-noise
- Plan C: 60Hz line-locked feedforward only (last run)





Hardware Testing

- Hardware was verified using beam
 - Fiber data to FFB
 - Magnet controls
- Magnet locations mapped correctly
- Good response at 5.5GeV with headroom for 12GeV



IPM5C07 Stripline Frequency Response



Active Collimator plot of time domain response to 1kHz FFB magnet kick at BS04V







60Hz Suppression (Plan C)

- Line-synchronized 60Hz Feedforward suppression algorithm used last 2 days of the run
- Also engaged slow EPICS position locks to steady the beam







Hall D FFB To Do

- Implement Hall A&C FFB algorithm (Plan A)
 - Translate into the new electronics
 - Incorporate Active Collimator
 - Incorporate Cavity BPMs
- Commission Cavity BPMs (beam time)
 - Finish firmware and software
 - Measure bandwidth & current limitations
- Commission Active Collimator (beam time)
 - Measure bandwidth & current limitations
- Iterative FFB testing and tweaking (beam time)



Hall D Fast Feedback







Questions?



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Hall D Fast Feedback







Backup Slides...









Bandwidth vs Resolution



- Improving the signal-to-noise improves performance
- Filtering down to 1 Hz instead of 10 Hz gives an improvement factor of about 3.2
- This square root of bandwidth improvement holds true as long as the noise is Gaussian







FFB Component Locations



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